

# Brushless 20 Click



PID: MIKROE-5294

**Brushless 20 Click** is a compact add-on board that controls brushless DC (BLDC) motors with any MCU. This board features the [DRV8313](#), a fully integrated three-phase BLDC motor driver from [Texas Instruments](#). It provides three individually controllable half-H-bridge drivers intended to drive a three-phase BLDC motor, solenoids, or other loads. Each output driver channel consists of N-channel power MOSFETs configured in a 1/2-H-bridge configuration. Besides, it has a wide operating voltage range from 8V to 60V, alongside several built-in protection circuits such as undervoltage, charge pump faults, overcurrent, and overtemperature. This Click board™ makes the perfect solution for driving three-phase brushless DC motors up to 2A output current rating.

Brushless 20 Click is supported by a [mikroSDK](#) compliant library, which includes functions that simplify software development. This [Click board™](#) comes as a fully tested product, ready to be used on a system equipped with the [mikroBUS™](#) socket.

## How does it work?

Brushless 20 Click as its foundation uses the DRV8313, a fully integrated three-phase BLDC motor driver from Texas Instruments. The highly integrated DRV8313 comes with PWM/enable control interface, wide voltage operating range, an integrated 10mA LDO, and robust on-chip protection features. Low RDS(on) and efficient switching algorithms ensure excellent thermal performance and high drive capability. This Click board™ offers an energy-saving solution and quiet motor operation for brushless DC (BLDC) motors used in various applications.

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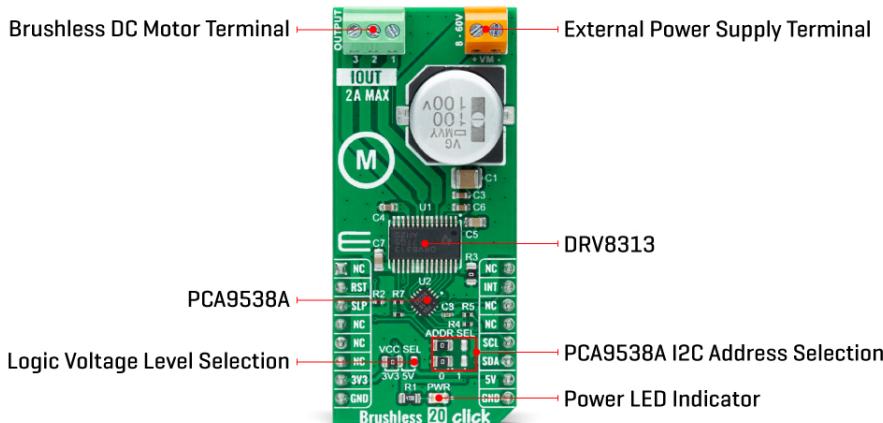
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Each output driver channel consists of N-channel power MOSFETs configured in a 1/2-H-bridge configuration. Control pins can be accessed through the I2C interface and the [PCA9538A](#) port expander, with which the states of those pins, alongside the state of the output terminals, can be directly controlled. The PCA9538A also allows choosing the least significant bit (LSB) of its I2C slave address by positioning SMD jumpers labeled as ADDR SEL to an appropriate position marked as 0 and 1, alongside its interrupt and Reset features routed to the INT and RST pins of the mikroBUS™ socket.

The DRV8313 is active unless the SLP pin, routed to the CS pin of the mikroBUS™ socket, is brought to a low logic state. The charge pump and output FETs are disabled in sleep mode, alongside the internal LDO regulator. The DRV8313 is automatically brought out of sleep mode if SLP is brought to a logic high state. This board also supports an external power supply for the motor, which can be connected to the input terminal labeled as VM and should be within the range of 8V to 60V, while the BLDC motor coils can be connected to the terminals labeled as 1, 2, and 3.

This Click board™ can operate with both 3.3V and 5V logic voltage levels selected via the VCC SEL jumper. This way, it is allowed for both 3.3V and 5V capable MCUs to use the communication lines properly. However, the Click board™ comes equipped with a library containing easy-to-use functions and an example code that can be used, as a reference, for further development.

## Specifications

Type	Brushless
Applications	Can be used for driving three-phase brushless DC motors up to 2A output current rating
On-board modules	DRV8313 - three-phase BLDC motor driver from Texas Instruments
Key Features	Triple 1/2 H-bridge driver, high current drive capability, low MOSFET ON resistance, integrated protection features, sleep mode for standby operation, and more
Interface	I2C
Feature	No ClickID

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Compatibility	mikroBUS™					
Click board size	L (57.15 x 25.4 mm)					
Input Voltage	3.3V or 5V					

## Pinout diagram

This table shows how the pinout on Brushless 20 Click corresponds to the pinout on the mikroBUS™ socket (the latter shown in the two middle columns).

Notes	Pin	mikro™ BUS					Pin	Notes
	NC	1	AN	PWM	16	NC		
Reset	<b>RST</b>	2	RST	INT	15	<b>INT</b>	Interrupt	
Sleep Mode	<b>SLP</b>	3	CS	RX	14	NC		
	NC	4	SCK	TX	13	NC		
	NC	5	MISO	SCL	12	<b>SCL</b>	I2C Clock	
	NC	6	MOSI	SDA	11	<b>SDA</b>	I2C Data	
Power Supply	<b>3.3V</b>	7	3.3V	5V	10	<b>5V</b>	Power Supply	
Ground	<b>GND</b>	8	GND	GND	9	<b>GND</b>	Ground	

## Onboard settings and indicators

Label	Name	Default	Description
LD1	PWR	-	Power LED Indicator
JP1	VCC SEL	Left	Logic Level Voltage Selection 3V3/5V: Left position 3V3, Right position 5V
JP2-JP3	ADDR SEL	Left	I2C Address Selection 0/1: Left position 0, Right position 1

## Brushless 20 Click electrical specifications

Description	Min	Typ	Max	Unit
Supply Voltage	3.3	-	5	V
External Supply Voltage Range	8	-	60	V
Maximum Output Current	-	-	2	A
Operating Temperature Range	-40	+25	+120	°C

## Software Support

We provide a library for the Brushless 20 Click as well as a demo application (example), developed using MikroElektronika [compilers](#). The demo can run on all the main MikroElektronika [development boards](#).

Package can be downloaded/installed directly from NECTO Studio Package Manager(recommended way), downloaded from our [LibStock™](#) or found on [Mikroe github account](#).

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## Library Description

This library contains API for Brushless 20 Click driver.

### Key functions

- brushless20\_perform\_com\_sequence This function performs a single commutation sequence for the selected rotation direction at a desired speed.
- brushless20\_drive\_motor This function drives the motor for a desired time by performing multiple commutation sequences for the selected rotation direction at a desired speed.
- brushless20\_get\_fault\_pin This function returns the fault pin logic state.

## Example Description

This example demonstrates the use of the Brushless 20 Click board™ by driving the motor in both directions at different speeds.

The full application code, and ready to use projects can be installed directly from NECTO Studio Package Manager(recommended way), downloaded from our [LibStock™](#) or found on [Mikroe github account](#).

Other Mikroe Libraries used in the example:

- MikroSDK.Board
- MikroSDK.Log
- Click.Brushless20

## Additional notes and informations

Depending on the development board you are using, you may need [USB UART click](#), [USB UART 2 Click](#) or [RS232 Click](#) to connect to your PC, for development systems with no UART to USB interface available on the board. UART terminal is available in all MikroElektronika [compilers](#).

## mikroSDK

This Click board™ is supported with [mikroSDK](#) - MikroElektronika Software Development Kit. To ensure proper operation of mikroSDK compliant Click board™ demo applications, mikroSDK should be downloaded from the [LibStock](#) and installed for the compiler you are using.

For more information about mikroSDK, visit the [official page](#).

## Resources

[mikroBUS™](#)

[mikroSDK](#)

[Click board™ Catalog](#)

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[Click boards™](#)

## Downloads

[Brushless 20 click example on Libstock](#)[DRV8313 datasheet](#)[PCA9538A datasheet](#)[Brushless 20 click 2D and 3D files](#)[Brushless 20 click schematic](#)

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