Current Transducer LF 2010-S

I_{PN} = 2000 A

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.

Features

- Bipolar and insulated current measurement
- Current output
- Closed loop (compensated) current transducer
- Panel mounting.

Advantages

- High accuracy
- Very low offset drift over temperature.

Applications

- Windmill inverters
- Test and measurement
- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications.

Standards

- IEC 61010-1: 2010
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- UL 508 : 2013.

Application Domain

- Industrial.

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Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (–40 °C … 85 °C)	$\pm U_{C\ max}$	V	±25.2
Maximum primary conductor temperature	$T_{B\ max}$	°C	100
Maximum steady state primary current (–40 °C … 85 °C))	$I_{P\ N\ max}$	A	2000

Stresses above these ratings may cause permanent damage.
Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13.

Ratings

Parameter	Unit	Value
Primary involved potential	V AC/DC	1500
Maximum surrounding air temperature	°C	85
Primary current	A	0 ... 2000
Secondary supply voltage	V DC	0 ... 24
Secondary current	mA	0 ... 400

Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 1500 V AC/DC, consideration shall be given to the following:

1 - These products must be mounted in a suitable end-use enclosure.

2 - The secondary pin terminals have not been evaluated for field wiring.

3 - Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).

4 - Based on the temperature test performed on LF 2010-S series, the primary bar or conductor shall not exceed 120 °C in the end use application when the primary current does not exceed 2500 A and 100 °C when the primary current is up to 3500 A.

5 - LF 2010-S series shall be used in a pollution degree 2.

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

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Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_d	kV	6	
Impulse withstand voltage 1.2/50 µs	U_{Ni}	kV	23	
Clearance (pri. - sec.)	d_{Cl}	mm	28.0	Shortest distance through air
Creepage distance (pri. - sec.)	d_{Cp}	mm	29.8	Shortest path along device body
Application example Rated insulation RMS voltage	U_{Nm}	V	3600	Basic insulation according to IEC 61800-5-1, CAT III, PD2
Application example Rated insulation RMS voltage	U_{Nm}	V	1000	Reinforced insulation according to IEC 61800-5-1, CAT III, PD2
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	T_A	°C	–40		85	
Ambient storage temperature	$T_{A\,st}$	°C	–50		90	
Mass	m	g		1500		

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Electrical data

At T_A = 25 °C, $\pm U_C$ = ±24 V, R_M = 1 Ω, unless otherwise noted.
Lines with a * in the conditions column apply over the –40 … 85 °C ambient temperature range.

Parameter	Symbol	Unit	Min	Typ	Max		Conditions
Primary nominal DC current	I_{PN}	A			2000	*	
Primary current, measuring range	I_{PM}	A	–4250		4250	*	With $\pm U_C$ = ±22.8 V; T_A = 85 °C; R_M = 1 Ω For other conditions, see figure 1
Measuring resistance	R_M	Ω	0			*	Max value of R_M is given in figure 1
Secondary nominal RMS current	I_{SN}	A			0.4	*	
Resistance of secondary winding	R_S	Ω			18.6		$R_S(T_A) = R_S \times (1 + 0.004 \times (T_A + \Delta\text{temp} - 25))$ Estimated temperature increase @I_{PN} is Δtemp = 15 °C
Secondary current	I_S	A	–0.85		0.85	*	
Number of secondary turns	N_S			5000			
Theoretical sensitivity	S_{th}	mA/A		0.2			
Supply voltage	$\pm U_C$	V	±14.25		±25.2	*	
Current consumption @ I_{PN} = 0	I_C	mA		42 48			$\pm U_C$ = ±15 V $\pm U_C$ = ±24 V
Offset current, referred to primary	I_O	A	–1		1		
Temperature variation of I_O, referred to primary	I_{OT}	A	–1		1	*	
Magnetic offset current after 3 × I_{PN} referred to primary	I_{OM}	A		±1			
Sensitivity error	ε_S	%	–0.15		0.15	*	
Linearity error	ε_L	% of I_{PN}	–0.1		0.1	*	
Total error at I_{PN}	ε_{tot}	% of I_{PN}	–0.2 –0.3		0.2 0.3	 *	25 … 70 … 85 °C –40 … 85 °C
Output RMS noise current, referred to primary	I_{no}	mA		90			1 Hz to 20 kHz (see figure 4)
Delay time to 10 % of the final output value I_{PN} step	t_{D10}	µs		< 0.5			0 to 1 kA, 200 A/µs
Delay time @ 90 % of the final output value I_{PN} step	t_{D90}	µs		< 0.5			0 to 1 kA, 200 A/µs
Frequency bandwidth	BW	kHz		150			–3 dB, small signal bandwidth (see figure 5)

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in “typical” graphs.
On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.
Unless otherwise stated (e.g. “100 % tested”), the LEM definition for such intervals designated with “min” and “max” is that the probability for values of samples to lie in this interval is 99.73 %.
For a normal (Gaussian) distribution, this corresponds to an interval between –3 sigma and +3 sigma. If “typical” values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between –sigma and +sigma for a normal distribution.
Typical, maximal and minimal values are determined during the initial characterization of the product.

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Typical performance characteristics

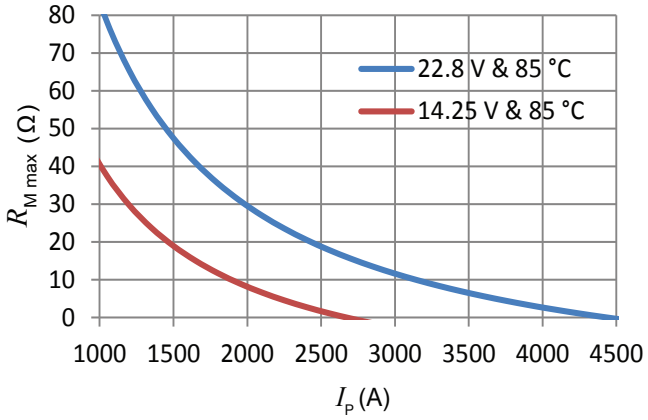

Figure 1: Maximum measuring resistance

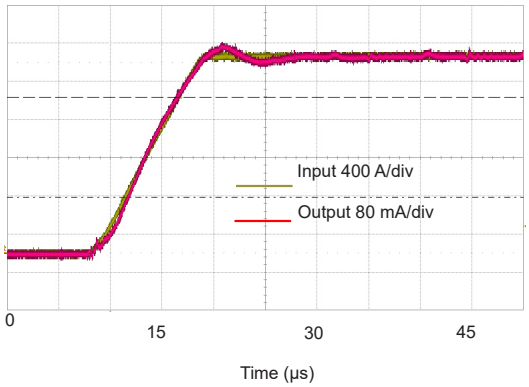

Figure 2: Typical delay time (0 to 2 kA, 400 A/µs)

$$R_{M\,max} = N_S \times \frac{U_{C\,min} - 0.6\ V}{I_P} - R_{S\,max}$$

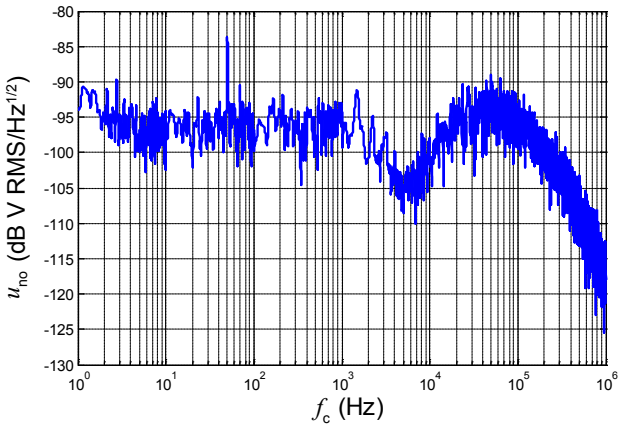

Figure 3: Typical output noise voltage spectral density e_{no} with R_M = 100 Ω

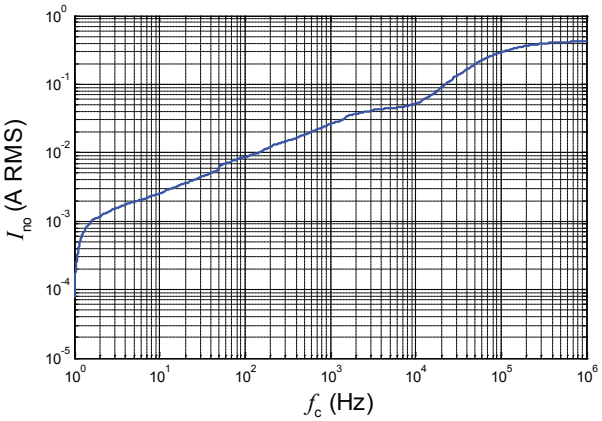

Figure 4: Typical total output RMS noise current with R_M = 100 Ω (primary referred)

Figure 3 (output noise voltage spectral density) shows that there are no significant discrete frequencies in the output.
Figure 4 confirms the absence of steps in the total output RMS noise current that would indicate discrete frequencies.
To calculate the noise in a frequency band $f1$ to $f2$, the formula is:
with $I_{no}(f)$ read from figure 4 (typical, RMS value).

$$I_{no}(f_1 \text{ to } f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

Example:
What is the noise from 1 to 10^6 Hz?
Figure 4 gives I_{no} (1 Hz) = 0.2 mA and I_{no} (10^6 Hz) = 400 mA.
The output RMS noise current is therefore:

$\sqrt{(400 \times 10^{-3})^2 - (0.2 \times 10^{-3})^2}$ = 400 mA referred to primary

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Typical performance characteristics continued

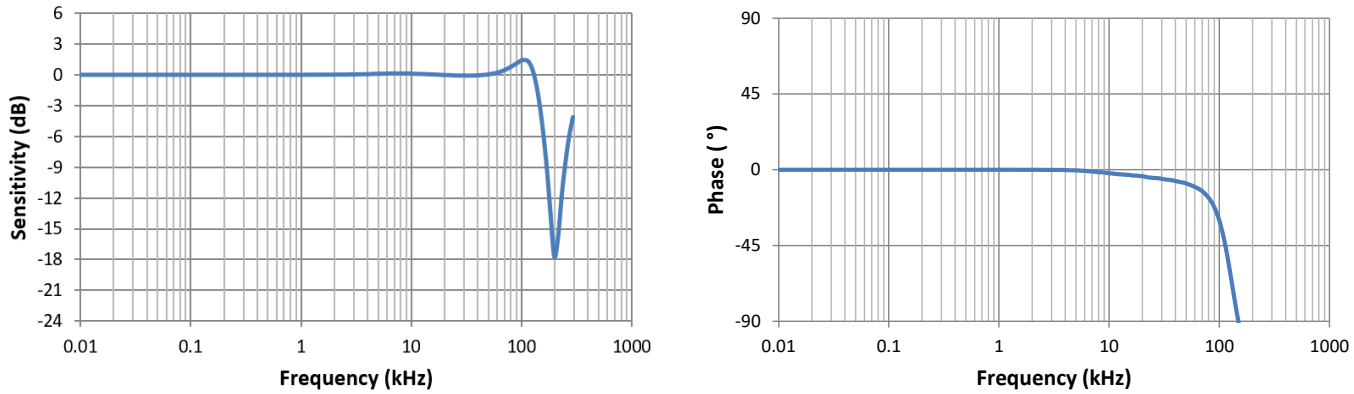

Figure 5: Typical frequency response, small signal bandwidth

Performance parameters definition

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to I_{PM}, then to $-I_{PM}$ and back to 0 (equally spaced I_{PM}/10 steps).
The sensitivity S is defined as the slope of the linear regression line for a cycle between $\pm I_{PM}$.
The linearity error ε_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Magnetic offset

The magnetic offset I_{OM} is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

Electrical offset

The electrical offset current I_{OE} is the residual output current when the input current is zero.

Total error

The total error ε_{tot} is the error at $\pm I_{PN}$, relative to the rated value I_{PM}.
It includes all errors mentioned above.

Delay times

The delay time t_{D10} and the delay time t_{D90} are shown in the next figure.

Both slightly depend on the primary current di/dt. They are measured at nominal current.

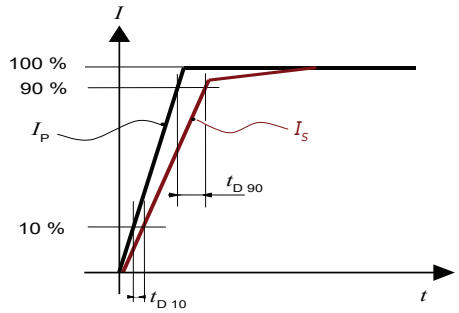

Figure 6: t_{D10} (delay time @ 10 %) and t_{D90} (delay time @ 90 %)

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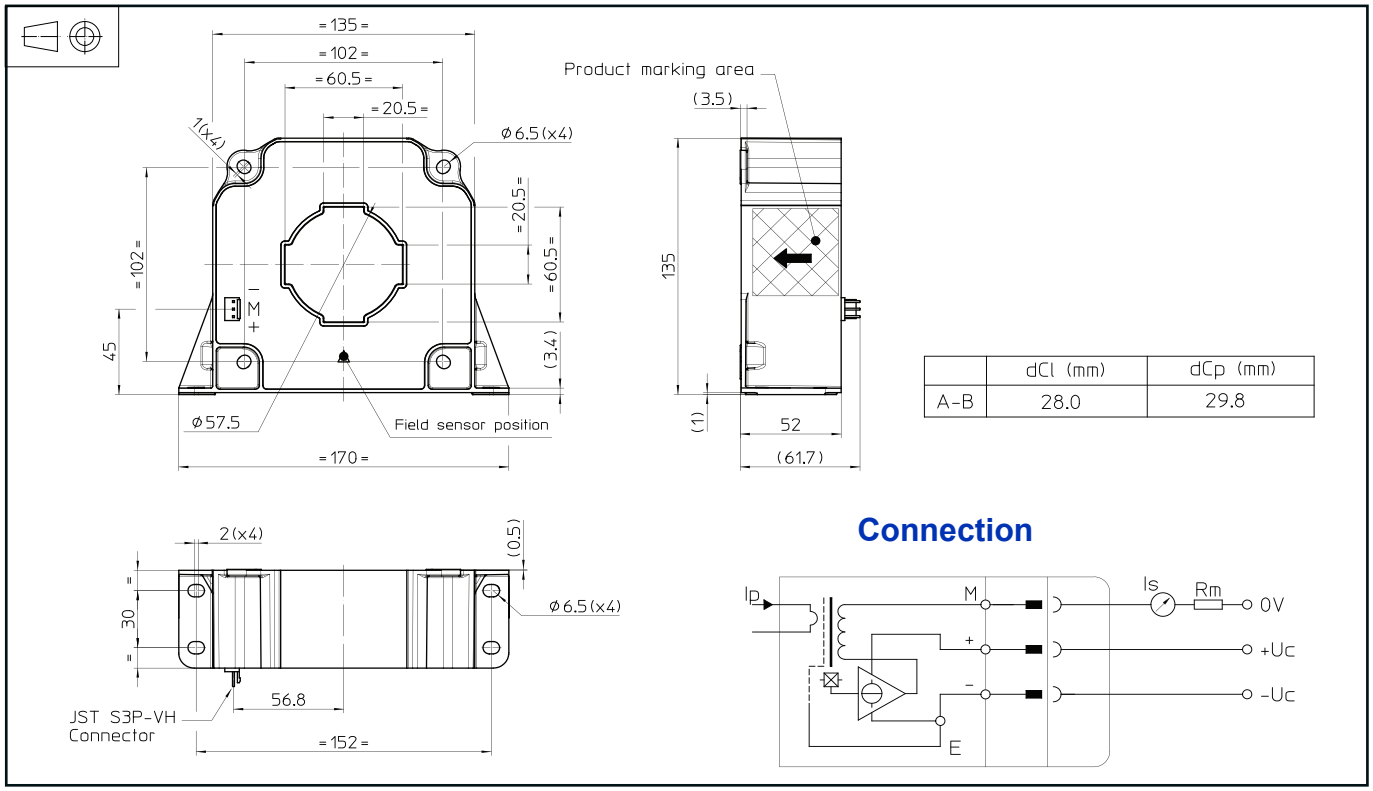
Dimensions (in mm)



	dCl (mm)	dCp (mm)
A-B	28.0	29.8

Connection

Mechanical characteristics

- General tolerance ±0.5 mm
- Transducer fastening
  Vertical position 4 slotted holes ⌀ 6.5 mm
  4 M6 steel screws
  Recommended fastening torque 5.5 N·m (±10 %)
- Primary through-hole ⌀ 57 mm
  Or 60 mm × 20 mm
- Transducer fastening
  Horizontal position 4 slotted holes ⌀ 6.5 mm
  4 M6 steel screws
  Recommended fastening torque 5.5 N·m (±10 %)
- Connection of secondary JST S3P-VH.

Remarks

- I_S is positive when I_P flows in the direction of arrow.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary current or secondary voltage present.
- Maximum temperature of primary conductor: see page 2.
- This is a standard model. For different versions (supply voltages, turns ratios, unidirectional measurements...), please contact us
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: **Products/Product Documentation.**

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.

This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.

Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary connection, power supply).
Ignoring this warning can lead to injury and/or cause serious damage.
This transducer is a build-in device, whose conducting parts must be inaccessible after installation.
A protective housing or additional shield could be used.
Main supply must be able to be disconnected.

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