

## PROFET™ + 24V smart high-side power switch single channel, 80 mΩ

### Basic Features

- Adjustable current limitation with OCT-pin
- One channel device
- Very low stand-by current
- 3.3 V and 5 V compatible logic inputs
- Electrostatic discharge protection (ESD)
- Optimized electromagnetic compatibility
- Logic ground independent from load ground
- Very low power DMOS leakage current in OFF state
- Green product (RoHS compliant)



### Potential applications

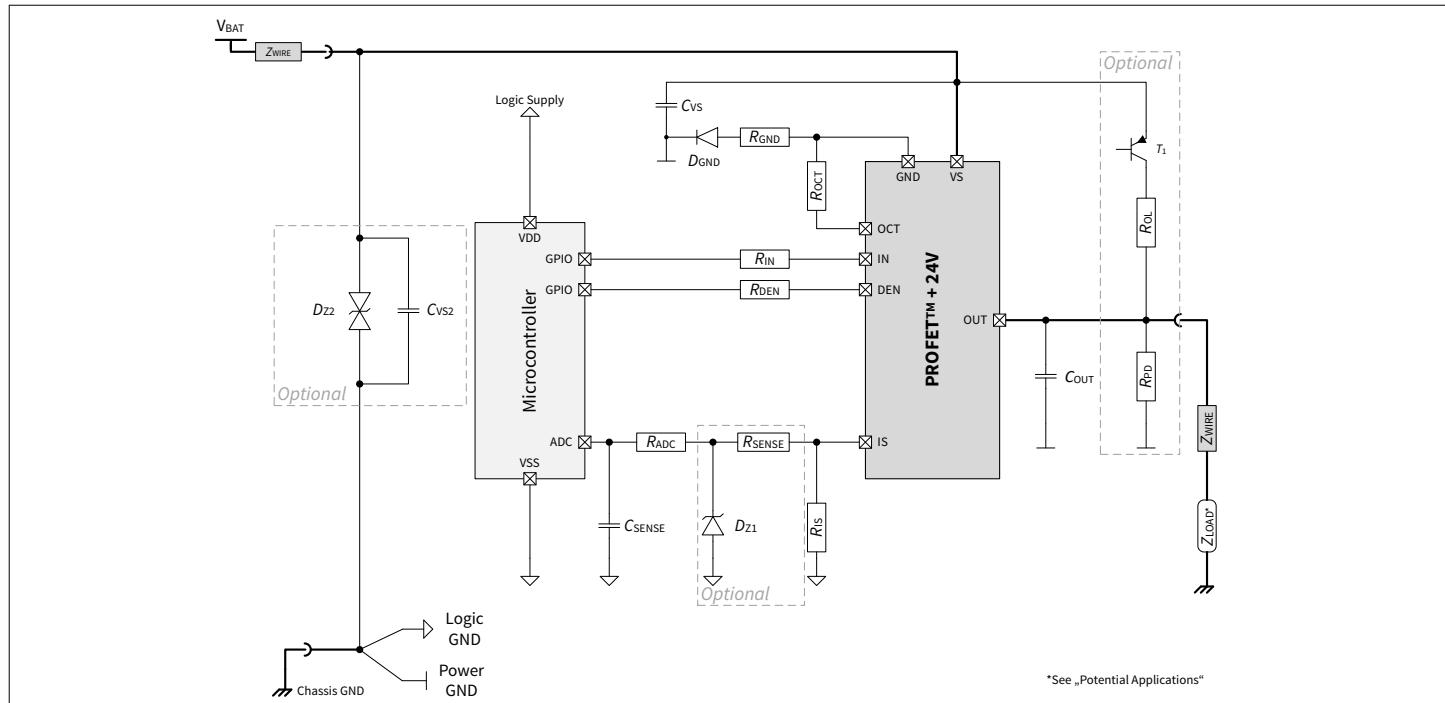
- Suitable for resistive, inductive and capacitive loads
- Replaces electromechanical relays, fuses and discrete circuits
- Suitable for driving electronic loads (for example, radar, camera modules)
- Suitable for 12 V and 24 V truck and transportation system
- Protection of system supply
- Main switch for ECU power supply

### Product validation

Qualified for automotive applications. Product validation according to AEC-Q100.

### Description

The BTT6080-1ERL is a 80 mΩ single channel Smart High-Side Power Switch, embedded in a PG-TDSO-14, Exposed Pad package, providing protective functions and diagnosis. The power transistor is built by an N-channel vertical power MOSFET with charge pump. The device offers an adjustable current limitation to offer higher reliability for protecting the system.



Product type	Package	Marking
BTT6080-1ERL	PG-TDSO-14	6080-1ERL

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## 1 Product Description

**Table 1 Product Summary**

Parameter	Symbol	Value
Nominal operating voltage range	$V_{NOM}$	8 V ... 36 V
Maximum supply voltage	$V_{S(LD)}$	65 V
Maximum ON state resistance at $T_J = 150^\circ\text{C}$	$R_{DS(ON)}$	150 mΩ
Nominal load current	$I_{L(NOM)}$	2.5 A
Typical current sense ratio	$k_{ILIS}$	1250
Adjustable current limitation	$I_{LIM}$	0.81 A to 5.56 A
Maximum standby current with load at $T_J = 25^\circ\text{C}$	$I_{S(OFF)}$	0.5 μA

### Diagnostic Functions

- Proportional load current sense
- Open load in ON and OFF
- Short circuit to battery and ground
- Overtemperature, Stable diagnostic signal during short circuit
- Enhanced  $k_{ILIS}$  dependency with temperature and load current

### Protection Functions

- Stable behavior during undervoltage
- Reverse polarity protection with external components
- Secure load turn-off during loss of logic ground with external components
- Overtemperature protection with latch
- Overvoltage protection with external components
- Enhanced short circuit operation

## 2

## Block Diagram

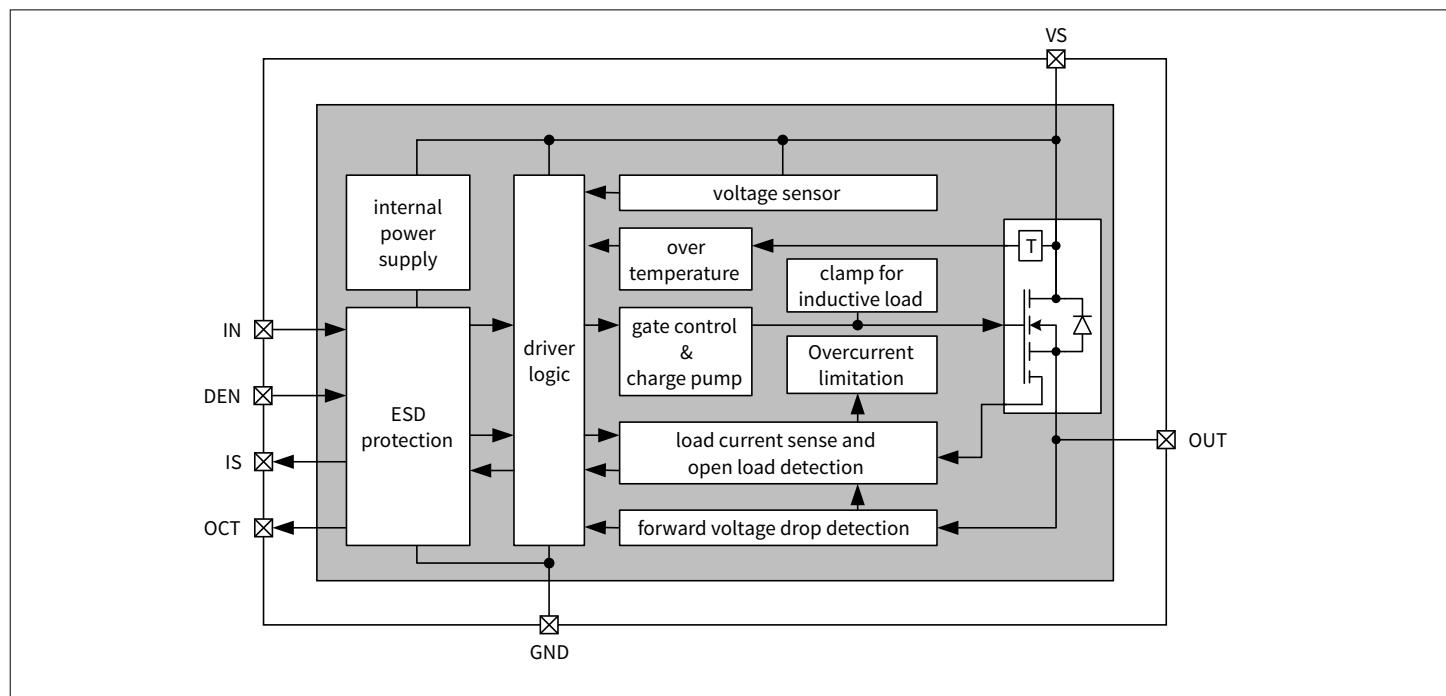


Figure 2

Block Diagram for the BTT6080-1ERL

## 3 Pin Configuration

### 3.1 Pin Assignment

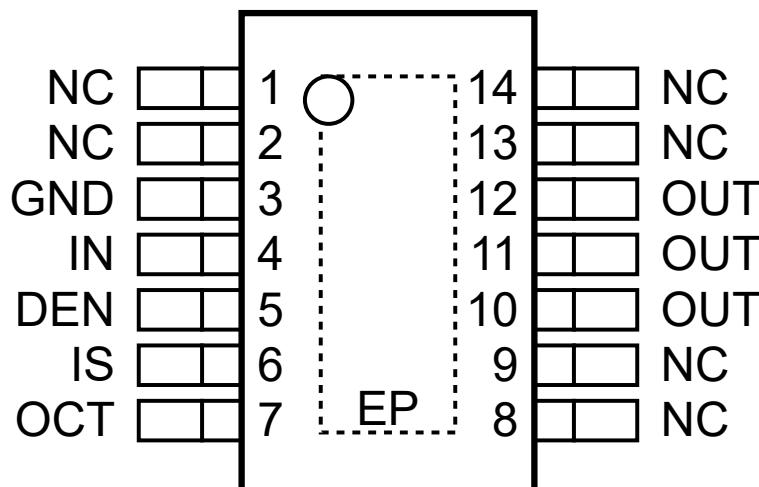


Figure 3 Pin configuration PG-TDSO-14

### 3.2 Pin Definitions and Functions

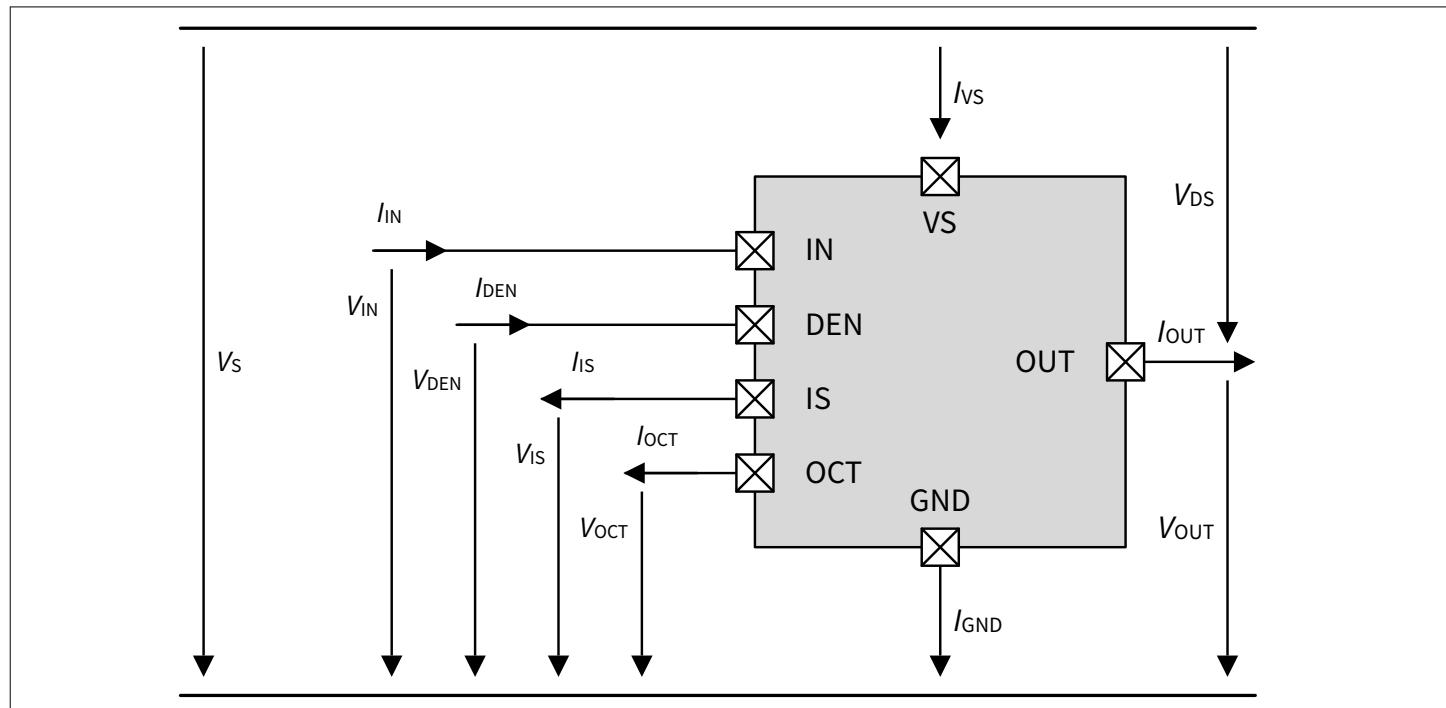
Table 2 Pin Definitions and Functions

Pin	Symbol	Function
Cooling Tab	VS	<b>Voltage supply</b> ; Battery voltage
1, 2, 8, 9, 13, 14	NC	<b>Not connected</b> ; No internal connection to the chip
3	GND	<b>Ground</b> ; Ground connection
4	IN	<b>Input channel</b> ; Input signal for channel activation
5	DEN	<b>Diagnostic enable</b> ; Digital signal to enable/disable the diagnosis of the device
6	IS	<b>Sense</b> ; Sense current of the selected channel
7	OCT	Adjustable overcurrent <b>threshold</b> ; A resistor $R_{OCT}$ needs to be connected between OCT pin and GND pin to adjust the overcurrent threshold. $R_{OCT}$ resistor must be placed close to the OCT pin
10, 11, 12	OUT	<b>Output</b> ; Protected high side power output channel <sup>1)</sup>

1) All output pins must be connected together on the PCB. All pins of the output are internally connected together. PCB traces have to be designed to withstand the maximum current which can flow

### 3.3 Voltage and Current Definition

Figure 4 shows all terms used in this data sheet, with associated convention for positive values.



**Figure 4** **Voltage and Current Definition**

## 4 General Product Characteristics

### 4.1 Absolute Maximum Ratings

**Table 3 Absolute Maximum Ratings<sup>1)</sup>**

$T_J = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ ; (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Supply Voltages</b>							
Supply voltage	$V_S$	-0.3	-	48	V	-	P_4.1.1
Reverse polarity voltage	$-V_{S(\text{REV})}$	0	-	28	V	$t < 2 \text{ min}$ $T_A = 25^\circ\text{C}$ $R_L \geq 25 \Omega$ $R_{\text{GND}} = 150 \Omega$	P_4.1.2
Supply voltage for short circuit protection	$V_{\text{BAT}(\text{SC})}$	0	-	36	V	$R_{\text{ECU}} = 20 \text{ m}\Omega$ $R_{\text{Cable}} = 16 \text{ m}\Omega/\text{m}$ $L_{\text{Cable}} = 1 \mu\text{H}/\text{m}$ , $I = 0$ or $40 \text{ m}$ See <a href="#">Chapter 6</a> and <a href="#">Figure 31</a>	P_4.1.3
Supply voltage for Load dump protection	$V_{S(\text{LD})}$	-	-	65	V	<sup>2)</sup> $R_I = 2 \Omega$ $R_L = 25 \Omega$	P_4.1.12
<b>Input Pins</b>							
Voltage at INPUT pin	$V_{\text{IN}}$	-0.3	-	6 7	V	- $t < 2 \text{ min}$	P_4.1.13
Current through INPUT pin	$I_{\text{IN}}$	-2	-	2	mA	-	P_4.1.14
Voltage at DEN pin	$V_{\text{DEN}}$	-0.3	-	6 7	V	- $t < 2 \text{ min}$	P_4.1.15
Current through DEN pin	$I_{\text{DEN}}$	-2	-	2	mA	-	P_4.1.16
<b>OCT Pin</b>							
Voltage at OCT pin	$V_{\text{OCT}}$	-0.3	-	$V_S$	V	-	P_4.1.5
Current through OCT pin	$I_{\text{OCT}}$	-2	-	2	mA	-	P_4.1.6
<b>Sense Pin</b>							
Voltage at IS pin	$V_{\text{IS}}$	-0.3	-	$V_S$	V	-	P_4.1.19
Current through IS pin	$I_{\text{IS}}$	-25	-	50	mA	-	P_4.1.20
<b>Power Stage</b>							
Load current	$ I_L $	-	-	$I_{\text{L}(\text{LIM})}$	A	-	P_4.1.21
<b>(table continues...)</b>							

**Table 3 (continued) Absolute Maximum Ratings<sup>1)</sup>** $T_J = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ ; (unless otherwise specified)

<b>Parameter</b>	<b>Symbol</b>	<b>Values</b>			<b>Unit</b>	<b>Note or Test Condition</b>	<b>Number</b>
		<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>			
Power dissipation (DC)	$P_{\text{TOT}}$	-	-	1.6	W	$T = 85^\circ\text{C}$ $T_J < 150^\circ\text{C}$	P_4.1.22
Maximum energy dissipation Single pulse	$E_{\text{AS}}$	-	-	45	mJ	$I_L = 2.5 \text{ A}$ $T_{J(0)} = 150^\circ\text{C}$ $V_S = 28 \text{ V}$	P_4.1.23
Voltage at power transistor	$V_{\text{DS}}$	-	-	65	V	-	P_4.1.26

**Current**

Current through ground pin	$I_{\text{GND}}$	-20 -200	-	20 20	mA	- $t < 2 \text{ min}$	P_4.1.27
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**Temperature**

Junction temperature	$T_J$	-40	-	150	°C	-	P_4.1.28
Storage temperature	$T_{\text{STG}}$	-55	-	150	°C	-	P_4.1.30

**ESD Susceptibility**

ESD susceptibility (all pins)	$V_{\text{ESD}}$	-2	-	2	kV	<sup>3)</sup> HBM	P_4.1.31
ESD susceptibility OUT Pin vs. GND and VS connected	$V_{\text{ESD}}$	-4	-	4	kV	<sup>3)</sup> HBM	P_4.1.32
ESD susceptibility	$V_{\text{ESD}}$	-500	-	500	V	<sup>4)</sup> CDM	P_4.1.33
ESD susceptibility pin (corner pins)	$V_{\text{ESD}}$	-750	-	750	V	<sup>4)</sup> CDM	P_4.1.34

1) Not subject to production test. Specified by design

2)  $V_{\text{S(LD)}}$  is setup without the DUT connected to the generator per ISO 7637-1

3) ESD susceptibility, Human Body Model “HBM” according to AEC Q100-002

4) ESD susceptibility, Charged Device Model “CDM” according to AEC Q100-011

**Notes:**

1. Stresses above the ones listed here may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.
2. Integrated protection functions are designed to prevent IC destruction under fault conditions described in the data sheet. Fault conditions are considered as “outside” normal operating range. Protection functions are not designed for continuous repetitive operation.

## 4.2 Functional Range

**Table 4 Functional Range**

$T_J = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ ; (unless otherwise specified)

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Nominal operating voltage	$V_{\text{NOM}}$	8	28	36	V	–	P_4.2.1
Extended operating voltage	$V_{\text{S(OP)}}$	5	–	48	V	<sup>2)</sup> $V_{\text{IN}} = 4.5 \text{ V}$ $R_L = 25 \Omega$ $V_{\text{DS}} < 0.5 \text{ V}$ See <a href="#">Figure 16</a>	P_4.2.2
Minimum functional supply voltage	$V_{\text{S(OP)_MIN}}$	3.8	4.3	5	V	<sup>1)</sup> $V_{\text{IN}} = 4.5 \text{ V}$ $R_L = 25 \Omega$ From $I_{\text{OUT}} = 0 \text{ A}$ to $V_{\text{DS}} < 0.5 \text{ V}$ ; See <a href="#">Figure 16</a>	P_4.2.3
Undervoltage shutdown	$V_{\text{S(UV)}}$	2.5	3.5	4.1	V	<sup>1)</sup> $V_{\text{IN}} = 4.5 \text{ V}$ $V_{\text{DEN}} = 0 \text{ V}$ $R_L = 25 \Omega$ From $V_{\text{DS}} < 1 \text{ V}$ to $I_{\text{OUT}} = 0 \text{ A}$ See <a href="#">Figure 16</a>	P_4.2.4
Undervoltage shutdown hysteresis	$V_{\text{S(UV)_HYS}}$	–	850	–	mV	<sup>2)</sup>	P_4.2.13
Operating current channel active	$I_{\text{GND}}$	–	2.5	3.5	mA	$V_{\text{IN}} = 5.5 \text{ V}$ $V_{\text{DEN}} = 5.5 \text{ V}$ Device in $R_{\text{DS(ON)}}$ $V_S = 36 \text{ V}$	P_4.2.5
Standby current for whole device with load (ambient)	$I_{\text{S(OFF)}}$	–	0.1	0.5	$\mu\text{A}$	<sup>1)</sup> $V_S = 36 \text{ V}$ $V_{\text{OUT}} = 0 \text{ V}$ $V_{\text{IN}}$ floating $V_{\text{DEN}}$ floating $T_J \leq 85^\circ\text{C}$	P_4.2.7
Maximum standby current for whole device with load	$I_{\text{S(OFF)_150}}$	–	3	15	$\mu\text{A}$	$V_S = 36 \text{ V}$ $V_{\text{OUT}} = 0 \text{ V}$ $V_{\text{IN}}$ floating $V_{\text{DEN}}$ floating $T_J = 150^\circ\text{C}$	P_4.2.10

(table continues...)

**Table 4 (continued) Functional Range** $T_J = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ ; (unless otherwise specified)

<b>Parameter</b>	<b>Symbol</b>	<b>Values</b>			<b>Unit</b>	<b>Note or Test Condition</b>	<b>Number</b>
		<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>			
Standby current for whole device with load, diagnostic active	$I_{S(\text{OFF\_DEN})}$	–	1.3	–	mA	<sup>2)</sup> $V_S = 36\text{ V}$ $V_{\text{OUT}} = 0\text{ V}$ $V_{\text{IN}}$ floating $V_{\text{DEN}} = 5.5\text{ V}$	P_4.2.8

1) Test at  $T_J = -40^\circ\text{C}$  only

2) Not subject to production test. Specified by design

**Note:** Within the functional range the IC operates as described in the circuit description. The electrical characteristics are specified within the conditions given in the related electrical characteristics table.

## 4.3 Thermal Resistance

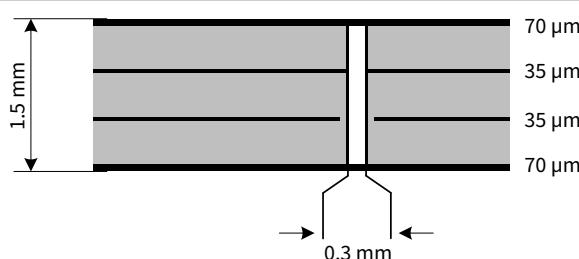
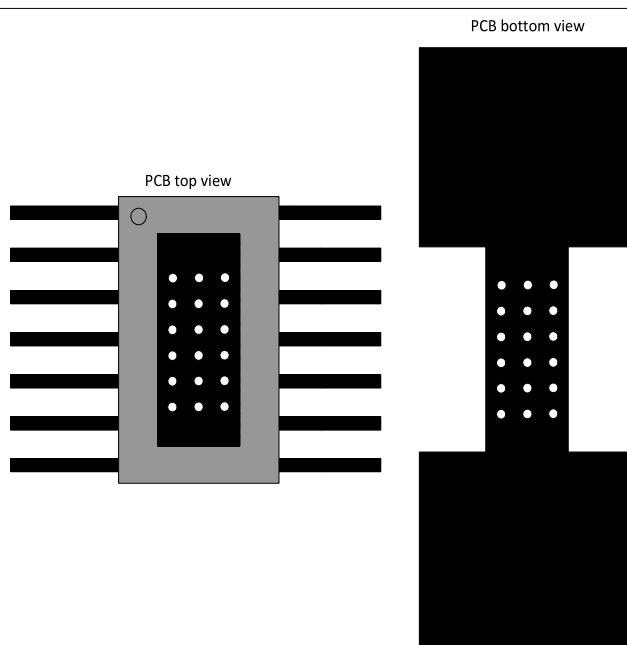
**Table 5 Thermal Resistance**

<b>Parameter</b>	<b>Symbol</b>	<b>Values</b>			<b>Unit</b>	<b>Note or Test Condition</b>	<b>Number</b>
		<b>Min.</b>	<b>Typ.</b>	<b>Max.</b>			
Junction to case	$R_{\text{thJC}}$	–	2.7	–	K/W	<sup>1)</sup>	P_4.3.1
Junction to ambient	$R_{\text{thJA}}$	–	29.5	–	K/W	<sup>1) 2)</sup>	P_4.3.2

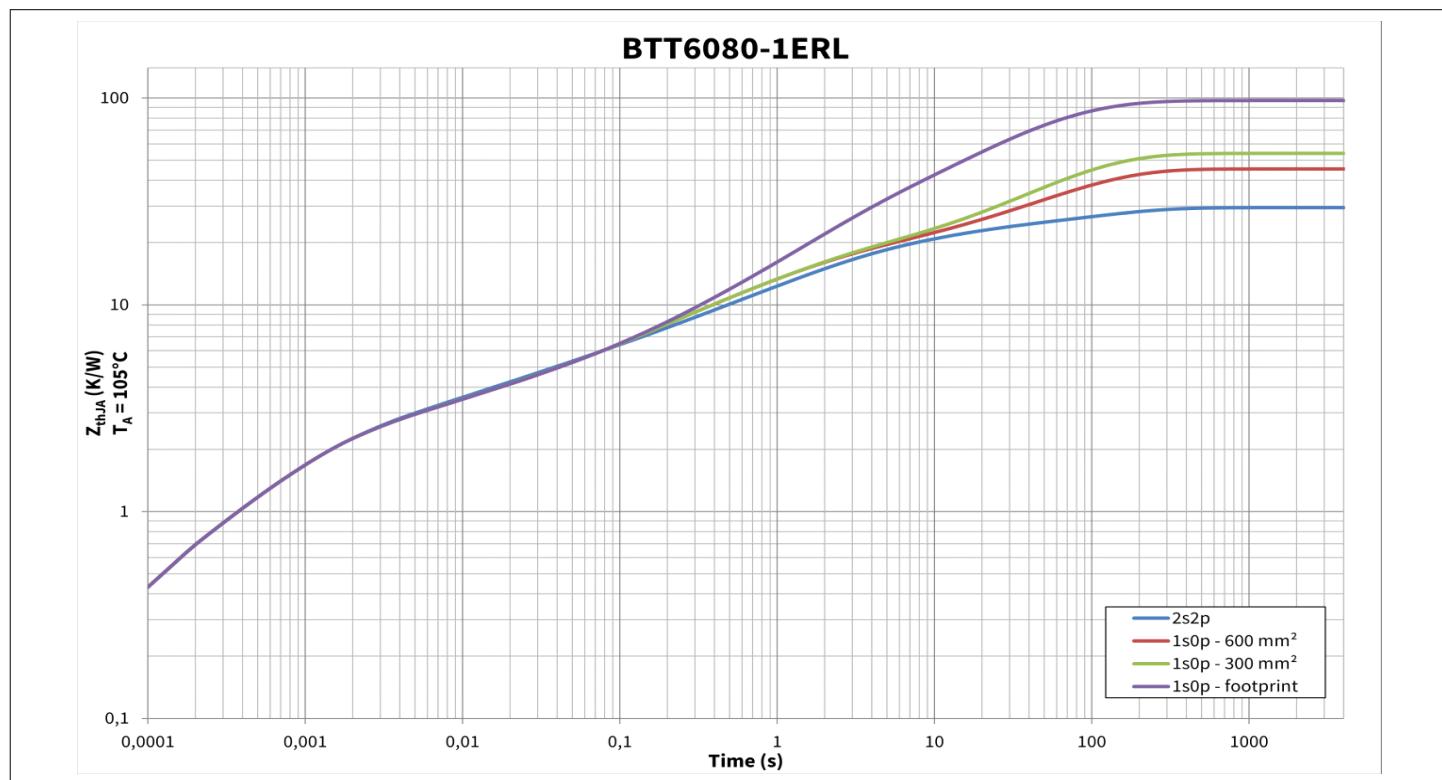
1) Not subject to production test. Specified by design

2) Specified  $R_{\text{thJA}}$  value is according to JEDEC JESD51-2,-5,-7 at natural convection on FR4 2s2p board with 1 W power dissipation at  $T_A = 105^\circ\text{C}$ ; The product (chip + package) was simulated on a 76.4 x 114.3 x 1.5 mm board with 2 inner copper layers (2 x 7  $\mu\text{m}$  Cu, 2 x 35  $\mu\text{m}$  Cu). Where applicable, a thermal via array under the exposed pad contacts the first inner copper layer. Please refer to [Figure 5](#)

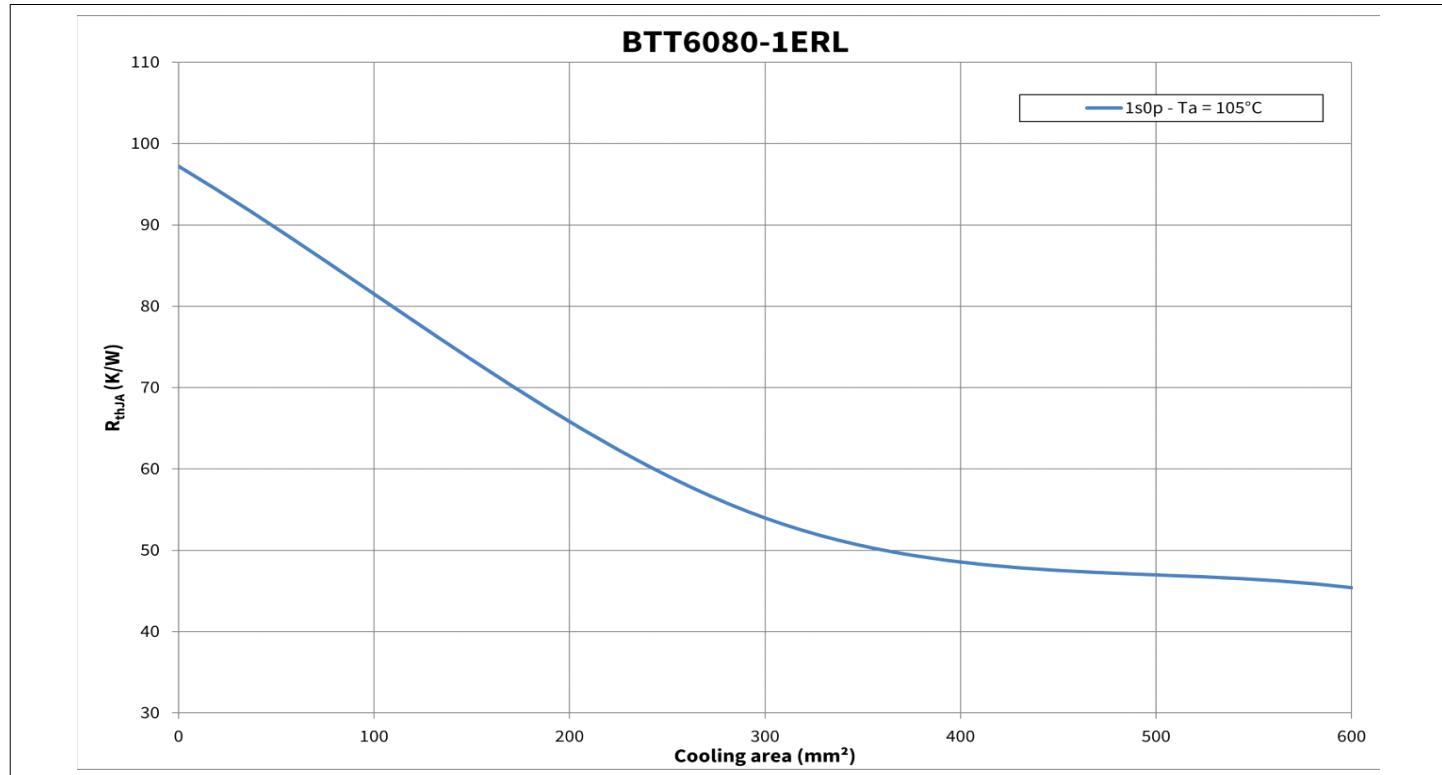
### 4.3.1 PCB Set-up

**Figure 5** 2s2p PCB Cross Section**Figure 6** PC Board Top and Bottom View for Thermal Simulation with  $600 \text{ mm}^2$  Cooling Area

### 4.3.2 Thermal Impedance



**Figure 7** Typical Thermal Impedance. 2s2p set-up according [Figure 5](#)



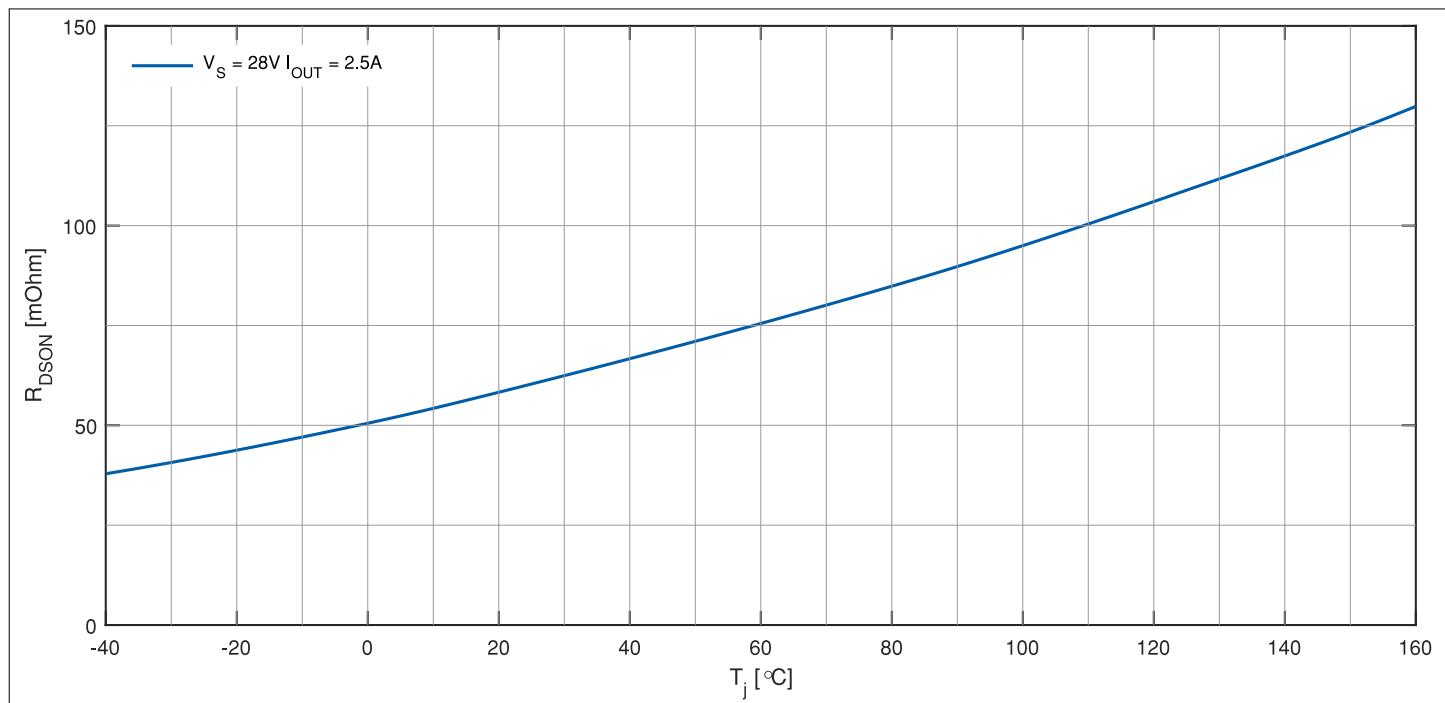
**Figure 8** Typical Thermal Resistance. PCB set-up 1s0p

## 5 Power Stage

The power stage is built using an N-channel vertical power MOSFET (DMOS) with charge pump.

### 5.1 Output ON-State Resistance

The ON-state resistance  $R_{DS(ON)}$  depends on the supply voltage as well as the junction temperature  $T_j$ . [Figure 9](#) shows the dependencies in terms of temperature for the typical ON-state resistance. The behavior in reverse polarity is described in [Chapter 6.4](#).

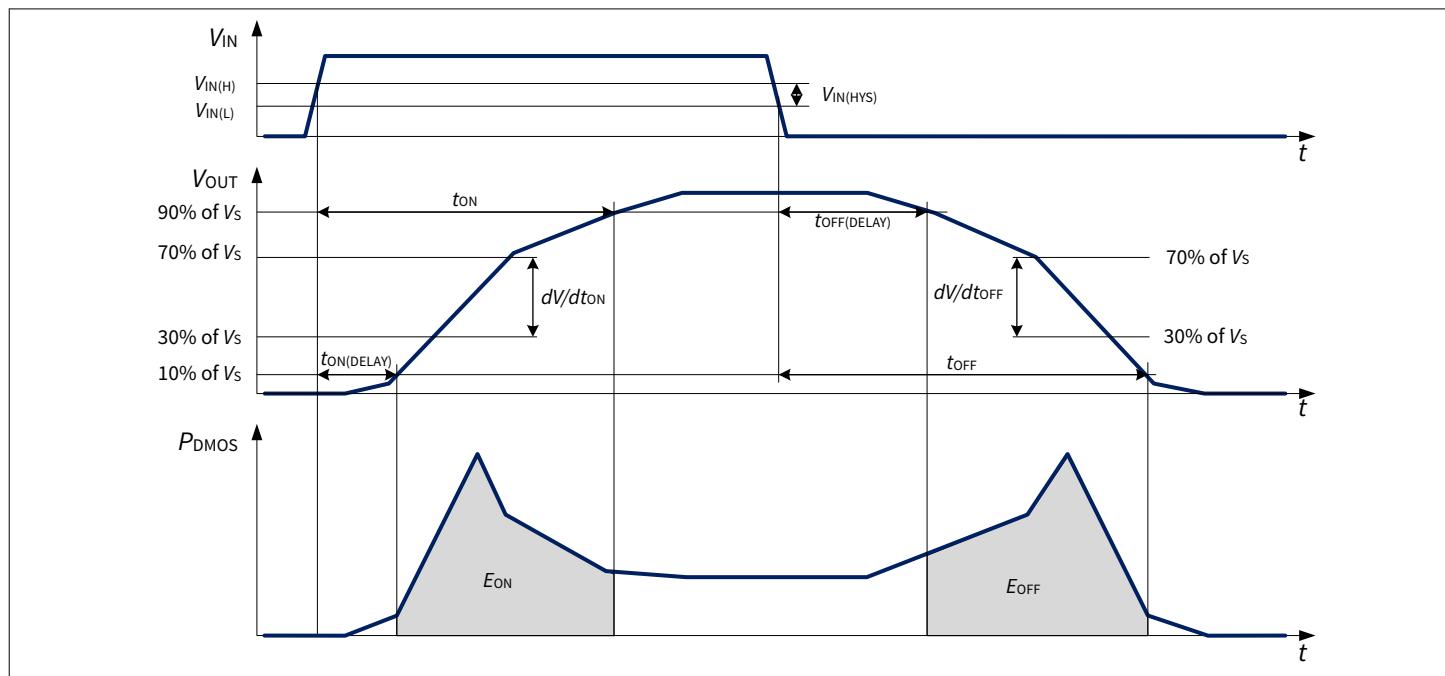


**Figure 9 Typical ON-State Resistance**

A “high” signal (see [Chapter 8](#)) at the input pin causes the power DMOS to switch ON with a dedicated slope, which is optimized in terms of EMC emission.

## 5.2 Turn ON/OFF Characteristics with Resistive Load

Figure 10 shows the typical timing when switching a resistive load.

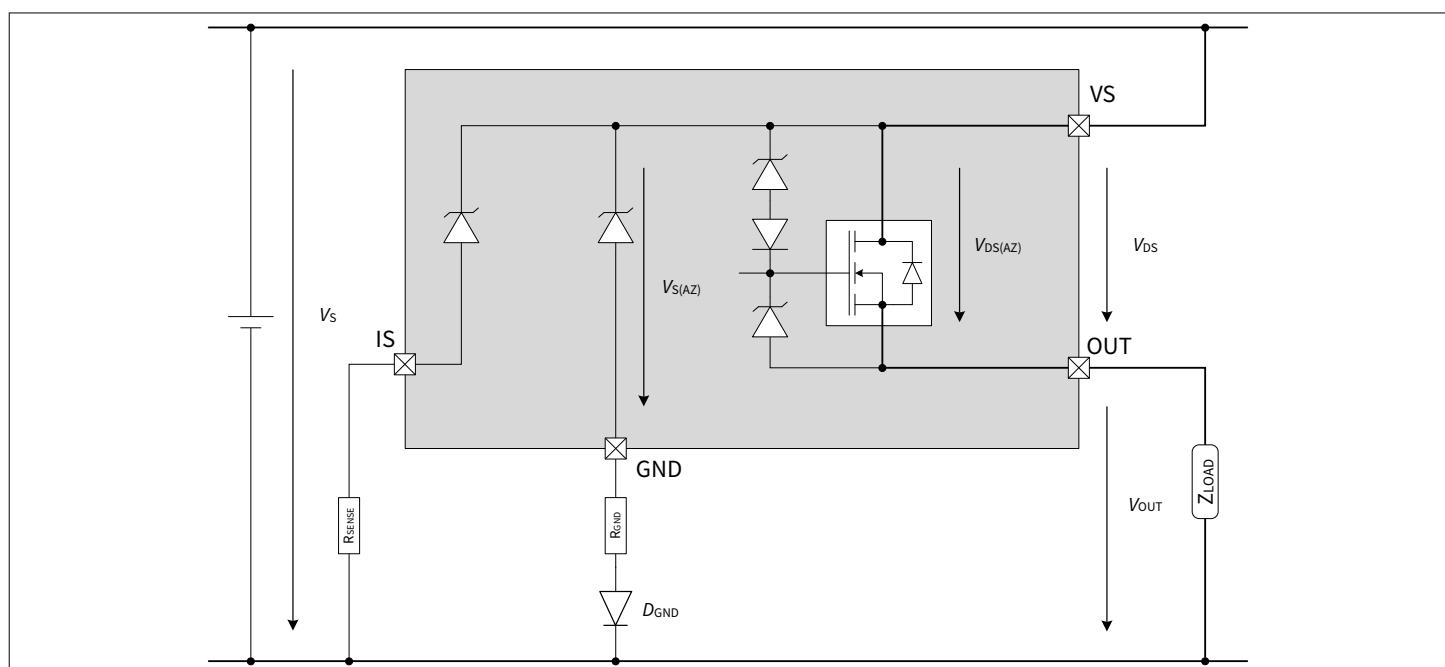


**Figure 10**      **Switching a Resistive Load Timing**

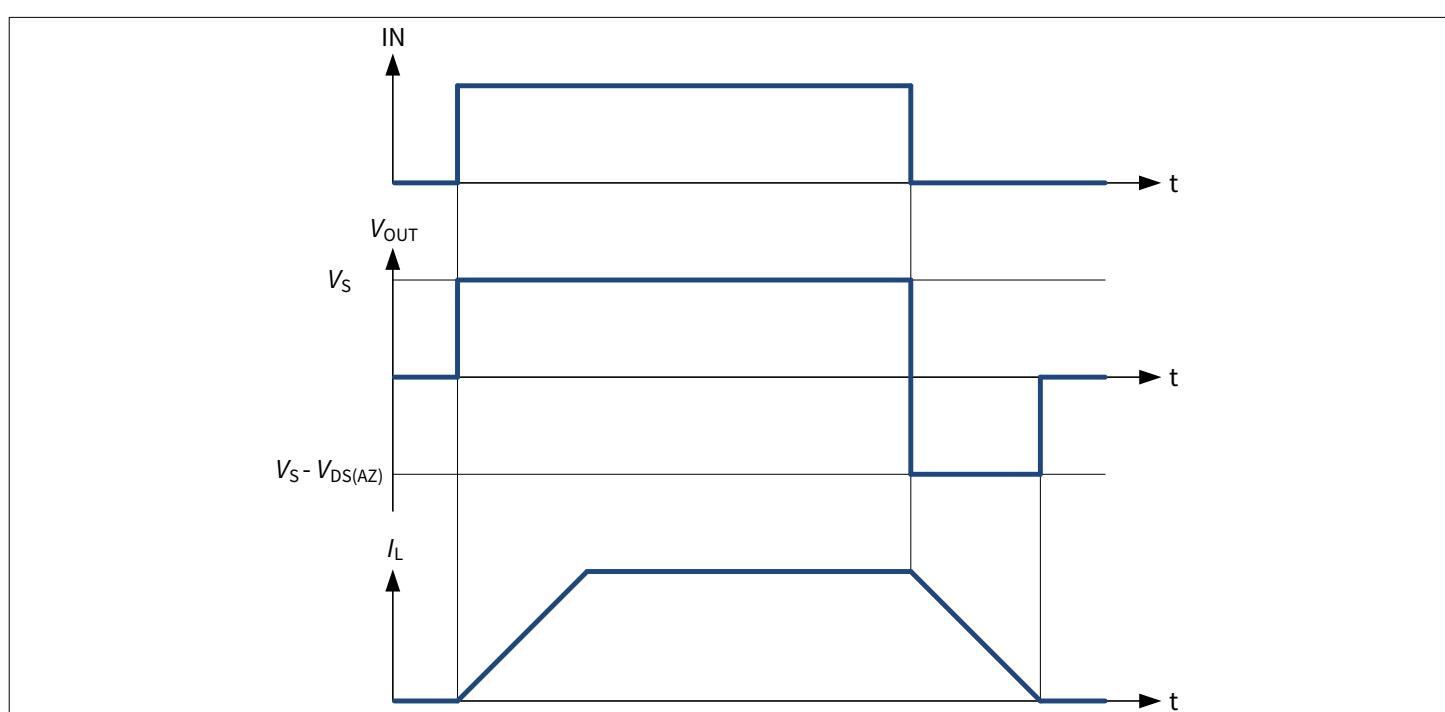
## 5.3 Inductive Load

### 5.3.1 Output Clamping

When switching OFF inductive loads with high side switches, the voltage  $V_{OUT}$  drops below ground potential, because the inductance intends to continue driving the current. To prevent the destruction of the device by avalanche due to high voltages, there is a voltage clamp mechanism  $Z_{DS(AZ)}$  implemented that limits negative output voltage to a certain level ( $V_S - V_{DS(AZ)}$ ). Please refer to [Figure 11](#) and [Figure 12](#) for details. Nevertheless, the maximum allowed load inductance is limited.



**Figure 11** Output Clamp



**Figure 12** Switching an Inductive Load Timing

### 5.3.2 Maximum Load Inductance

During demagnetization of inductive loads, energy has to be dissipated in the BTT6080-1ERL. This energy can be calculated with following equation:

$$E = V_{DS(AZ)} \times \frac{L}{R_L} \times \left[ \frac{V_S - V_{DS(AZ)}}{R_L} \times \ln\left(1 - \frac{R_L \times I_L}{V_S - V_{DS(AZ)}}\right) + I_L \right] \quad (1)$$

Following equation simplifies under the assumption of  $R_L = 0 \Omega$ .

$$E = \frac{1}{2} \times L \times I^2 \times \left(1 - \frac{V_S}{V_S - V_{DS(AZ)}}\right) \quad (2)$$

The energy, which is converted into heat, is limited by the thermal design of the component. See [Figure 13](#) for the maximum allowed energy dissipation as a function of the load current.

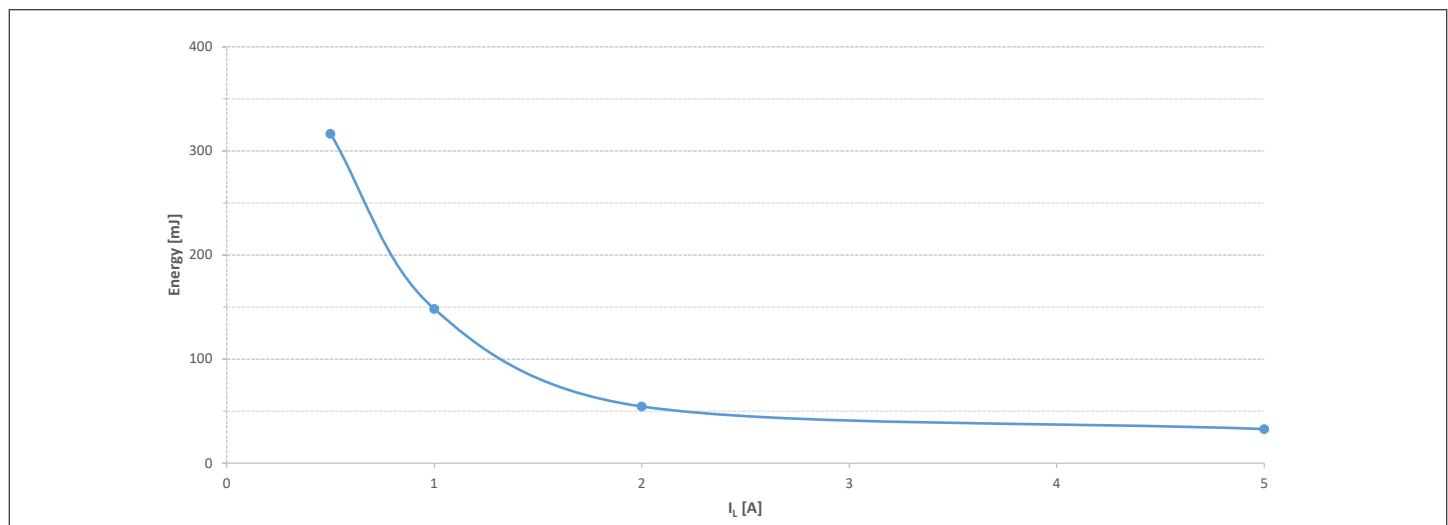


Figure 13

Maximum Energy Dissipation Single Pulse,  $T_{J\_START} = 150^\circ\text{C}$ ;  $V_S = 28 \text{ V}$

## 5.4 Inverse Current Capability

In case of inverse current, meaning a voltage  $V_{INV}$  at the OUTput higher than the supply voltage  $V_S$ , a current  $I_{L(INV)}$  will flow from output to  $V_S$  pin via the body diode of the power transistor (please refer to Figure 14). The output stage follows the state of the IN pin, except if the IN pin goes from OFF to ON during inverse. In that particular case, the output stage is kept OFF until the inverse current disappears. Nevertheless, the inverse current should not be higher than  $I_{L(INV)}$ . At the appearance of  $V_{INV}$ , a parasitic diagnostic can be observed. After, the diagnosis is valid and reflects the output state. At  $V_{INV}$  vanishing, the diagnosis is valid and reflects the output state. During inverse current, no protection functions are available.

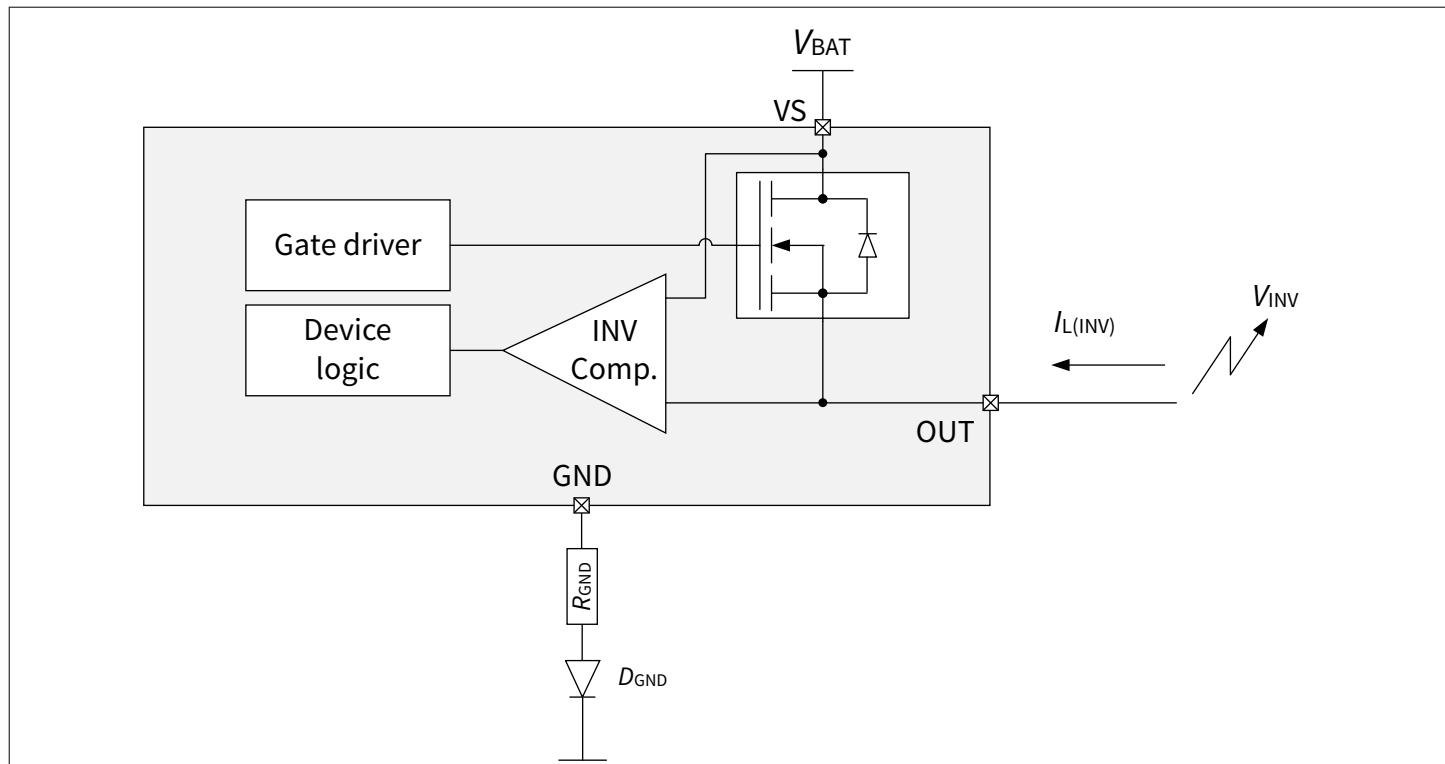


Figure 14

Inverse Current Circuitry

## 5.5 Electrical Characteristics Power Stage

**Table 6 Electrical Characteristics: Power Stage**

$V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)

Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
ON-state resistance per channel	$R_{DS(ON)}_{150}$	–	125	150	$\text{m}\Omega$	$I_L = 2.5 \text{ A}$ $V_{IN} = 4.5 \text{ V}$ $T_J = 150^\circ\text{C}$ See <a href="#">Figure 9</a>	P_5.5.1
ON-state resistance per channel	$R_{DS(ON)}_{25}$	–	75	–	$\text{m}\Omega$	<a href="#">1</a> ) $T_J = 25^\circ\text{C}$	P_5.5.21
Nominal load current	$I_{L(NOM)}$	–	2.5	–	$\text{A}$	<a href="#">1</a> ) $T_A = 85^\circ\text{C}$ $T_J < 150^\circ\text{C}$	P_5.5.2
$I_{LIM}$ fraction to calculate the maximum application load current	$I_{LIM01\_fraction}$	–	–	0.70	–	<a href="#">1</a> ) <a href="#">2</a> ) $I_{L(APP),MAX} = I_{LIM01\_fraction} \times I_{LIM}$ $0.81 \text{ A} \leq I_{LIM} < 1.87 \text{ A}$	P_5.5.3
$I_{LIM}$ fraction to calculate the maximum application load current	$I_{LIM02\_fraction}$	–	–	0.75	–	<a href="#">1</a> ) <a href="#">2</a> ) $I_{L(APP),MAX} = I_{LIM02\_fraction} \times I_{LIM}$ $1.87 \text{ A} \leq I_{LIM} < 2.30 \text{ A}$	P_5.5.22
$I_{LIM}$ fraction to calculate the maximum application load current	$I_{LIM03\_fraction}$	–	–	0.80	–	<a href="#">1</a> ) <a href="#">2</a> ) $I_{L(APP),MAX} = I_{LIM03\_fraction} \times I_{LIM}$ $2.30 \text{ A} \leq I_{LIM} < 4.60 \text{ A}$	P_5.5.23
$I_{LIM}$ fraction to calculate the maximum application load current	$I_{LIM04\_fraction}$	–	–	0.85	–	<a href="#">1</a> ) <a href="#">2</a> ) $I_{L(APP),MAX} = I_{LIM04\_fraction} \times I_{LIM}$ $4.60 \text{ A} \leq I_{LIM} < 5.56 \text{ A}$	P_5.5.24
Output voltage drop limitation at small load currents	$V_{DS(NL)}$	–	12	25	$\text{mV}$	$I_L = I_{L0} = 50 \text{ mA}$	P_5.5.4

(table continues...)

**Table 6 (continued) Electrical Characteristics: Power Stage** $V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$ 

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Drain to source clamping voltage $V_{DS(AZ)} = [V_S - V_{OUT}]$	$V_{DS(AZ)}$	65	70	75	V	$I_{DS} = 20 \text{ mA}$ See Figure 12	P_5.5.5
Output leakage current $T_J \leq 85^\circ\text{C}$	$I_{L(OFF)}$	–	0.05	0.5	$\mu\text{A}$	<sup>3)</sup> $V_{IN}$ floating $V_{OUT} = 0 \text{ V}$ $T_J \leq 85^\circ\text{C}$	P_5.5.6
Output leakage current $T_J = 150^\circ\text{C}$	$I_{L(OFF)\_150}$	–	3	10	$\mu\text{A}$	$V_{IN}$ floating $V_{OUT} = 0 \text{ V}$ $T_J = 150^\circ\text{C}$	P_5.5.8
Inverse current capability	$I_{L(INV)}$	–	2.5	–	A	<sup>1)</sup> $V_S < V_{OUT}$ $T_J < 150^\circ\text{C}$ $\Delta T_J \leq 80\text{K}$ See Figure 14	P_5.5.9
Slew rate 30% to 70% $V_S$	$dV/dt_{ON}$	0.3	0.8	1.4	$\text{V}/\mu\text{s}$	$R_L = 25 \Omega$ $V_S = 28 \text{ V}$ $I_{OCT} = 97.84 \mu\text{A}$ See Figure 10	P_5.5.11
Slew rate 70% to 30% $V_S$	$-dV/dt_{OFF}$	0.3	0.8	1.4	$\text{V}/\mu\text{s}$		P_5.5.12
Slew rate matching $dV/dt_{ON} - dV/dt_{OFF}$	$\Delta dV/dt$	-0.3	0	0.3	$\text{V}/\mu\text{s}$		P_5.5.13
Turn-ON time to $V_{OUT} = 90\% V_S$	$t_{ON}$	20	60	150	$\mu\text{s}$		P_5.5.14
Turn-OFF time to $V_{OUT} = 10\% V_S$	$t_{OFF}$	20	50	150	$\mu\text{s}$		P_5.5.15
Turn-ON/OFF matching $t_{OFF} - t_{ON}$	$\Delta t_{SW}$	-50	-10	50	$\mu\text{s}$		P_5.5.16
Turn-ON time to $V_{OUT} = 10\% V_S$	$t_{ON\_delay}$	–	30	70	$\mu\text{s}$		P_5.5.17
Turn-OFF time to $V_{OUT} = 90\% V_S$	$t_{OFF\_delay}$	–	30	70	$\mu\text{s}$		P_5.5.18
Switch ON energy	$E_{ON}$	–	0.32	–	$\text{mJ}$	<sup>1)</sup> $R_L = 25 \Omega$ $V_{OUT} = 90\% V_S$ $V_S = 36 \text{ V}$ $I_{OCT} = 97.84 \mu\text{A}$	P_5.5.19

(table continues...)

**Table 6 (continued) Electrical Characteristics: Power Stage**

$V_S$  = 8 V to 36 V,  $T_J$  = -40°C to +150°C (unless otherwise specified)

Typical values are given at  $V_S$  = 28 V,  $T_J$  = 25°C

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Switch OFF energy	$E_{OFF}$	-	0.30	-	mJ	<sup>1)</sup> $R_L$ = 25 Ω $V_{OUT}$ = 10% $V_S$ $V_S$ = 36 V $I_{OCT}$ = 97.84 μA	P_5.5.20

- 1) Not subject to production test, specified by design
- 2) This parameter describes the safety margin between the adjustable current limitation and the expected load current of the application. This is essential to prevent the unintentional activation of the current limitation circuit during normal operation. Keep in mind that when designing a real-world application, thermal constraints can impact the maximum allowed current ( $I_{L(APP)}$ ) to prevent overheating. This is particularly crucial when the current limit is set to high values and the ambient temperature ( $T_{AMB}$ ) is elevated. To ensure reliable operation, it's essential to consider the thermal design of the application and the resulting thermal budget in order to not exceed the maximum allowed junction temperature ( $T_J$ ) of 150°C.
- 3) Test at  $T_J$  = -40°C only

## 6 Protection Functions

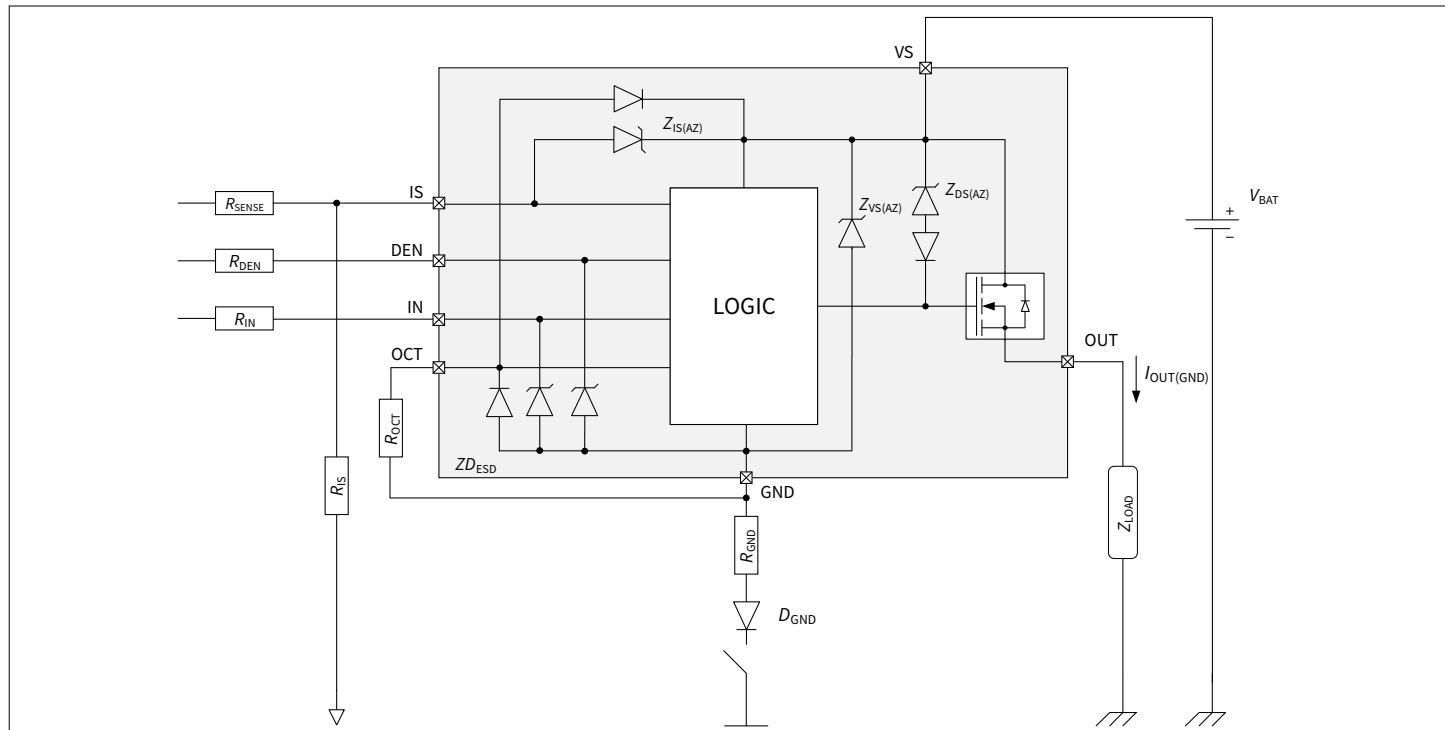
The device provides integrated protection functions. These functions are designed to prevent the destruction of the IC from fault conditions described in the data sheet. Fault conditions are considered as “outside” normal operating range. Protection functions are designed for neither continuous nor repetitive operation.

### 6.1 Loss of Ground Protection

In case of loss of the module ground and the load remains connected to ground, the device protects itself by automatically turning OFF (when it was previously ON) or remains OFF, regardless of the voltage applied on IN pin.

In case of loss of device ground, it is recommended to use input resistors between the microcontroller and the BTT6080-1ERL to ensure switching OFF of the channel.

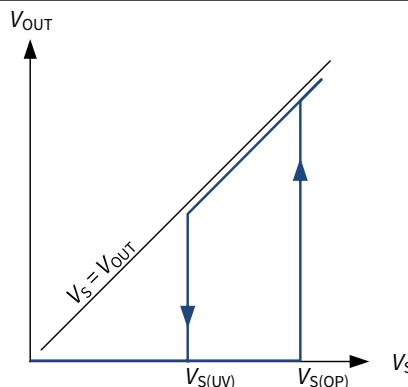
In case of loss of module or device ground, a current ( $I_{OUT(GND)}$ ) can flow out of the DMOS. [Figure 15](#) sketches the situation.



**Figure 15** Loss of Ground Protection with External Components

### 6.2 Undervoltage Protection

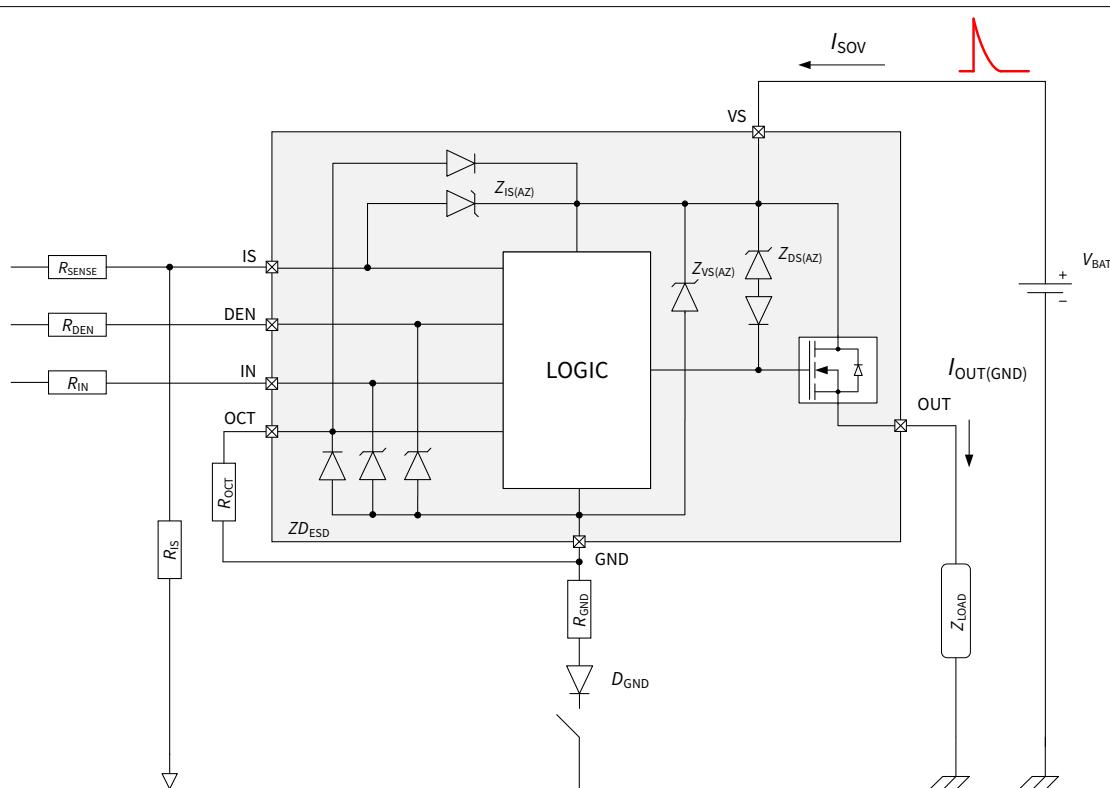
Between  $V_{S(UV)}$  and  $V_{S(OP)}$ , the under voltage mechanism is triggered.  $V_{S(OP)}$  represents the minimum voltage where the switching ON and OFF can take place.  $V_{S(UV)}$  represents the minimum voltage the switch can hold ON. If the supply voltage is below the undervoltage mechanism  $V_{S(UV)}$ , the device is OFF (turns OFF). As soon as the supply voltage is above the undervoltage mechanism  $V_{S(OP)}$ , then the device can be switched ON. When the switch is ON, protection functions are operational. Nevertheless, the diagnosis is not guaranteed until  $V_S$  is in the  $V_{NOM}$  range. [Figure 16](#) sketches the undervoltage mechanism.



**Figure 16** Undervoltage Behavior

### 6.3 Overvoltage Protection

There is an integrated clamp mechanism for overvoltage protection ( $Z_{VS(AZ)}$ ). To guarantee this mechanism operates properly in the application, the current in the Zener diode has to be limited by a ground resistor. [Figure 17](#) shows a typical application to withstand overvoltage issues. In case of supply voltage higher than  $V_{S(AZ)}$ , the power transistor switches ON and the voltage across the logic section is clamped. As a result, the internal ground potential rises to  $V_S - V_{S(AZ)}$ . Due to the ESD Zener diodes, the potential at pin IN and DEN rises almost to that potential, depending on the impedance of the connected circuitry. In the case the device was ON, prior to overvoltage, the BTT6080-1ERL remains ON. In the case the BTT6080-1ERL was OFF, prior to overvoltage, the power transistor can be activated. In the case the supply voltage is in above  $V_{BAT(SC)}$  and below  $V_{DS(AZ)}$ , the output transistor is still operational and follows the input. If the channel is in the ON state, parameters are no longer guaranteed and lifetime is reduced compared to the nominal supply voltage range. This especially impacts the short circuit robustness, as well as the maximum energy  $E_{AS}$  capability.

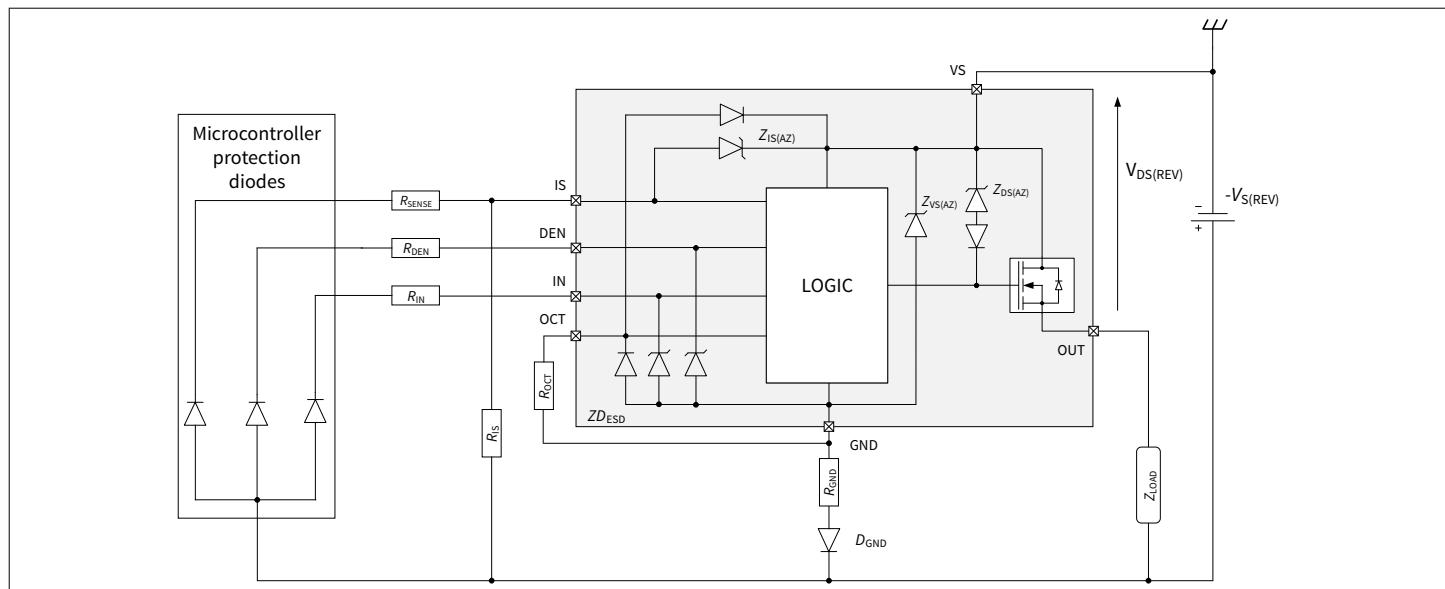


**Figure 17** Overvoltage Protection with External Components

## 6.4 Reverse Polarity Protection

In case of reverse polarity, the intrinsic body diode of the power DMOS causes power dissipation. The current in this intrinsic body diode is limited by the load itself. Additionally, the current into the ground path and the logic pins has to be limited to the maximum current described in [Chapter 4.1](#) with an external resistor. [Figure 18](#) shows a typical application.  $R_{GND}$  resistor is used to limit the current in the Zener protection of the device. Resistors  $R_{DEN}$  and  $R_{IN}$  are used to limit the current in the logic of the device and in the ESD protection stage.  $R_{SENSE}$  is used to limit the current in the sense transistor which behaves as a diode. The recommended value for  $R_{DEN} = R_{IN} = R_{SENSE} = 10 \text{ k}\Omega$ .

During reverse polarity, no protection functions are available.



**Figure 18** Reverse Polarity Protection with External Components

## 6.5 Overload Protection

In case of overload or short circuit to ground, the BTT6080-1ERL offers several protection mechanisms.

### 6.5.1 Adjustable Overcurrent Threshold

The BTT6080-1ERL is protected in case of overload and short circuit to ground.

The device offers an adjustable current limitation range from  $I_{LIM,MIN}$  to  $I_{LIM,MAX}$ . This feature offers protection against overstress for the load as well as for the power output stage. The configured current threshold is independent of  $V_{DS}$  and  $T_J$ . In case of DMOS temperature increase exceeding the device safe operation environment, overtemperature and dynamic temperature protection mechanism will be triggered as shown in [Figure 20](#).

For the adjustment of the current threshold for the output channel, the following equation can be considered:

$$I_{LIM} = (k_{ILIOCT} \times I_{OCT}) + \Delta I_{LIM} \quad (3)$$

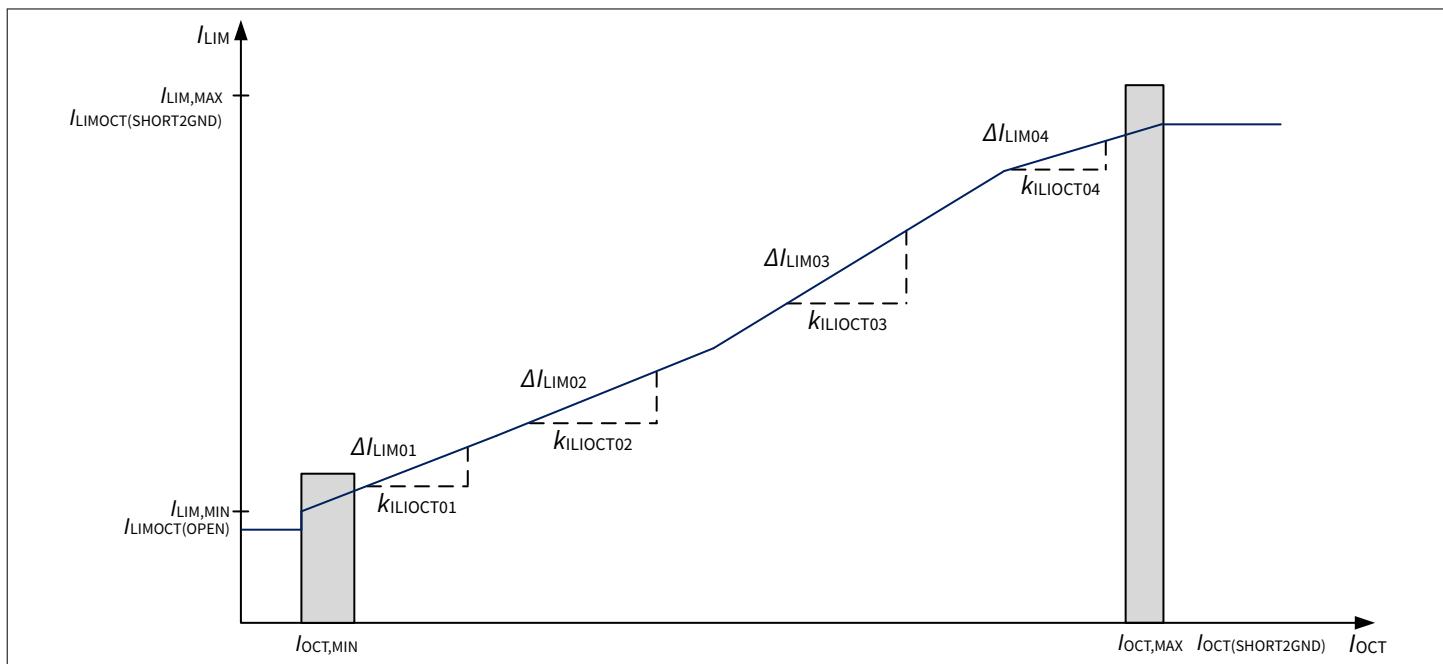
where

$$I_{OCT} = (I_{LIM} - \Delta I_{LIM}) / k_{ILIOCT} \quad (4)$$

To select the proper resistor value  $R_{OCT}$  connected between the OCT pin and device ground, the following equation can be considered:

$$R_{OCT} = (V_{OCT} \times k_{ILIOCT}) / (I_{LIM} - \Delta I_{LIM}) \quad (5)$$

In case of an OCT pin short to ground with the current exceeding  $I_{OCT(SHORT2GND)}$  the device will set the current limit value to  $I_{LIMOCT(SHORT2GND)}$ . The behavior of how  $I_{OCT}$  is related to  $I_{LIM}$  is described in [Figure 19](#). However, due to the maximum rating of the allowed current through OCT pin  $I_{OCT}$ , it is not recommended to shorten the OCT pin to device GND. In the case of reverse battery condition, this could lead to violations of the maximum ratings, therefore  $I_{OCT}$  absolute maximum rating needs to be considered.



**Figure 19**

Adjustable overcurrent threshold behavior

When setting the required current limitation, make sure that there is a safety margin between the adjusted current limitation and the expected load current of the application. This is important to prevent unintentional activation of the current limitation circuit during normal operation. When the load current is close(r) to the adjusted current limitation threshold, the turn-on slew rate becomes slower, causing a longer  $t_{ON}$  timing, while the turn-off slew rate may become faster, resulting in a shorter  $t_{OFF}$  timing. Keeping this safety margin ensures that the influence of the current limitation threshold on switching timings is moderate.

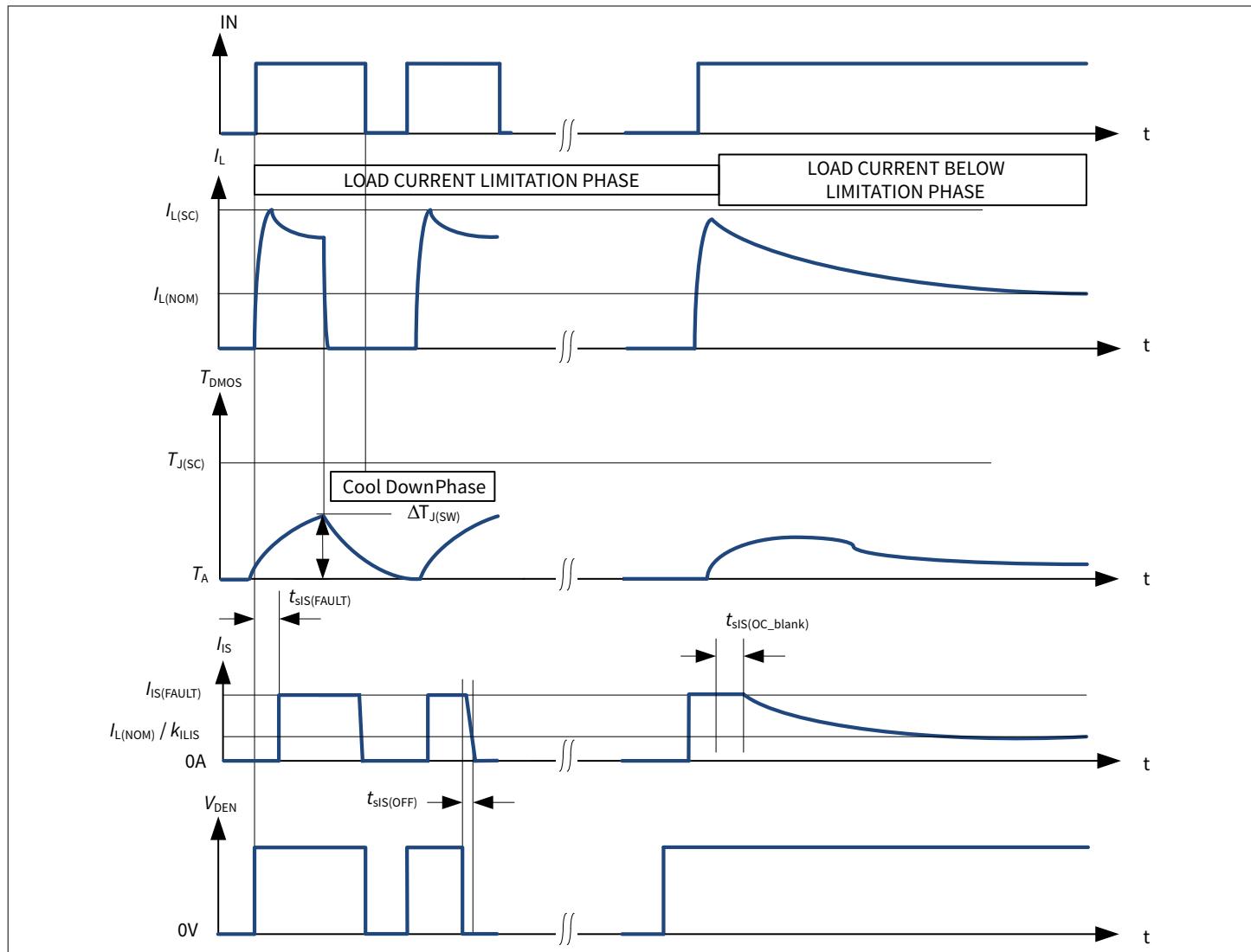
The maximum application load capability of the device at a certain current limitation threshold is given by the equation

$$I_{L(APP), MAX} = I_{LIM0x\_fraction} \times I_{LIM} \quad (6)$$

where  $x = 1 - 4$  (see [Table 6](#))

### 6.5.2 Overtemperature protection

The channel incorporates both an absolute ( $T_{J(SC)}$ ) and a dynamic ( $T_{J(SW)}$ ) temperature sensor. Activation of either sensor will cause the overheated channel to switch OFF to prevent destruction. The channel remains switched OFF even when the temperature has cooled down to an acceptable value (latch behavior). No retry strategy is implemented to switch ON the channel when the DMOS temperature has cooled down and only the IN pin signal toggling can re-activate the power stage. Figure 20 depicts the behavior of the device during an overtemperature condition.



**Figure 20** Overload Protection

**Note:** For better understanding, the time scale is not linear. The real timing of this drawing is application dependant and cannot be described.

## 6.6 Electrical Characteristics for the Protection Functions

**Table 7 Electrical Characteristics: Protection**

$V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)

Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Loss of Ground</b>							
Output leakage current while GND disconnected	$I_{\text{OUT}(\text{GND})}$	–	0.1	–	mA	<a href="#">1) 2)</a> $V_S = 48 \text{ V}$ See <a href="#">Figure 15</a>	P_6.6.1
<b>Reverse Polarity</b>							
Drain source diode voltage during reverse polarity	$V_{\text{DS}(\text{REV})}$	200	650	700	mV	$I_L = -2.5 \text{ A}$ $T_J = 150^\circ\text{C}$ See <a href="#">Figure 18</a>	P_6.6.2
<b>Overshoot</b>							
Overshoot protection	$V_{\text{S}(\text{AZ})}$	65	70	75	V	$I_{\text{sov}} = 20 \text{ mA}$ See <a href="#">Figure 17</a>	P_6.6.3
<b>Overload Condition</b>							
Dynamic temperature increase while switching	$\Delta T_{\text{J}(\text{SW})}$	–	80	–	K	<a href="#">3)</a> See <a href="#">Figure 20</a>	P_6.6.8
Thermal shutdown temperature	$T_{\text{J}(\text{SC})}$	150	170	200	°C	<a href="#">3) 4)</a> See <a href="#">Figure 20</a>	P_6.6.10
Thermal shutdown hysteresis	$\Delta T_{\text{J}(\text{SC})}$	–	30	–	K	<a href="#">3) 4)</a> See <a href="#">Figure 20</a>	P_6.6.11
Adjustable overcurrent limitation accuracy (low)	$I_{\text{LIM}01(\text{ACC})}$	-70.3%	–	70.3%	–	<a href="#">2)</a> $0.81 \text{ A} \leq I_{\text{LIM}} < 1.87 \text{ A}$ $V_{\text{DS}} = 5 \text{ V}$	P_6.6.9
Adjustable overcurrent limitation d-value (low)	$\Delta I_{\text{LIM}01}$	–	0.58	–	A	<a href="#">2)</a> $0.81 \text{ A} \leq I_{\text{LIM}} < 1.87 \text{ A}$ $V_{\text{DS}} = 5 \text{ V}$	P_6.6.6
Adjustable overcurrent limitation k-factor (low)	$k_{\text{ILIOCT01}}$	–	33.4k	–	–	<a href="#">2)</a> $0.81 \text{ A} \leq I_{\text{LIM}} < 1.87 \text{ A}$ $V_{\text{DS}} = 5 \text{ V}$	P_6.6.7
Adjustable overcurrent limitation accuracy (medium1)	$I_{\text{LIM}02(\text{ACC})}$	-40.2%	–	40.2%	–	<a href="#">2)</a> $1.87 \text{ A} \leq I_{\text{LIM}} < 2.30 \text{ A}$ $V_{\text{DS}} = 5 \text{ V}$	P_6.6.14

(table continues...)

**Table 7 (continued) Electrical Characteristics: Protection** $V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$ 

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Adjustable overcurrent limitation d-value (medium1)	$\Delta I_{LIM02}$	–	0.24	–	A	2) $1.87 \text{ A} \leq I_{LIM} < 2.30 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.15
Adjustable overcurrent limitation k-factor (medium1)	$k_{ILIOCT02}$	–	42.4k	–	–	2) $1.87 \text{ A} \leq I_{LIM} < 2.30 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.16
Adjustable overcurrent limitation accuracy (medium2)	$I_{LIM03(ACC)}$	-37.5%	–	37.5%	–	2) $2.30 \text{ A} \leq I_{LIM} < 4.60 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.19
Adjustable overcurrent limitation d-value (medium2)	$\Delta I_{LIM03}$	–	-0.58	–	A	2) $2.30 \text{ A} \leq I_{LIM} < 4.60 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.20
Adjustable overcurrent limitation k-factor (medium2)	$k_{ILIOCT03}$	–	57.1k	–	–	2) $2.30 \text{ A} \leq I_{LIM} < 4.60 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.21
Current limitation value in case OCT pin open	$I_{LIMOCT(OPEN)}$	–	0.75	–	A	2) $I_{OCT} \leq I_{OCT(OPEN)}$	P_6.6.24
Current limitation value in case OCT pin short to device ground	$I_{LIMOCT(SHORT2GND)}$	5.1	7.9	10.7	A	2) $I_{OCT} \geq I_{OCT(SHORT2GND)}$	P_6.6.25
Adjustable overcurrent limitation accuracy (high)	$I_{LIM04(ACC)}$	-48.1%	–	48.1%	–	2) $4.60 \text{ A} \leq I_{LIM} \leq 5.56 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.27
Adjustable overcurrent limitation d-value (high)	$\Delta I_{LIM04}$	–	-6.46	–	A	2) $4.60 \text{ A} \leq I_{LIM} \leq 5.56 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.26
Adjustable overcurrent limitation k-factor (high)	$k_{ILIOCT04}$	–	122.9k	–	–	2) $4.60 \text{ A} \leq I_{LIM} \leq 5.56 \text{ A}$ $V_{DS} = 5 \text{ V}$	P_6.6.28

1) All pins are disconnected except VS and OUT

2) Not subject to production test, specified by design

3) Functional test only

4) Test at  $T_J = +150^\circ\text{C}$  only

## 7 Diagnostic Functions

For diagnosis purposes, the BTT6080-1ERL provides a combination of digital and analog information at pin IS. These signals are called SENSE. The current sense is enabled when DEN is activated (DEN pin is set to "high"). In case of disabled diagnostic (DEN is set to "low"), IS becomes high impedance.

### 7.1 IS Pin

The BTT6080-1ERL provides a SENSE current,  $I_{IS}$ , at IS pin as long as no "hard" failure mode occurs (short circuit to GND/OCT short circuit to GND/current limitation/overtemperature/excessive dynamic temperature increase or open load at OFF). IS current is a proportional signal to the load current (ratio  $k_{ILIS} = I_L / I_{IS}$ ).

The complete IS pin and diagnostic mechanism is described on [Figure 21](#). The accuracy of the sense current depends on temperature and load current. Due to the ESD protection, in connection to  $V_S$ , it is not recommended to share the IS pin with other devices if these devices are using a different battery feed. The consequence is that the unsupplied device would be supplied via the IS pin of the supplied device.

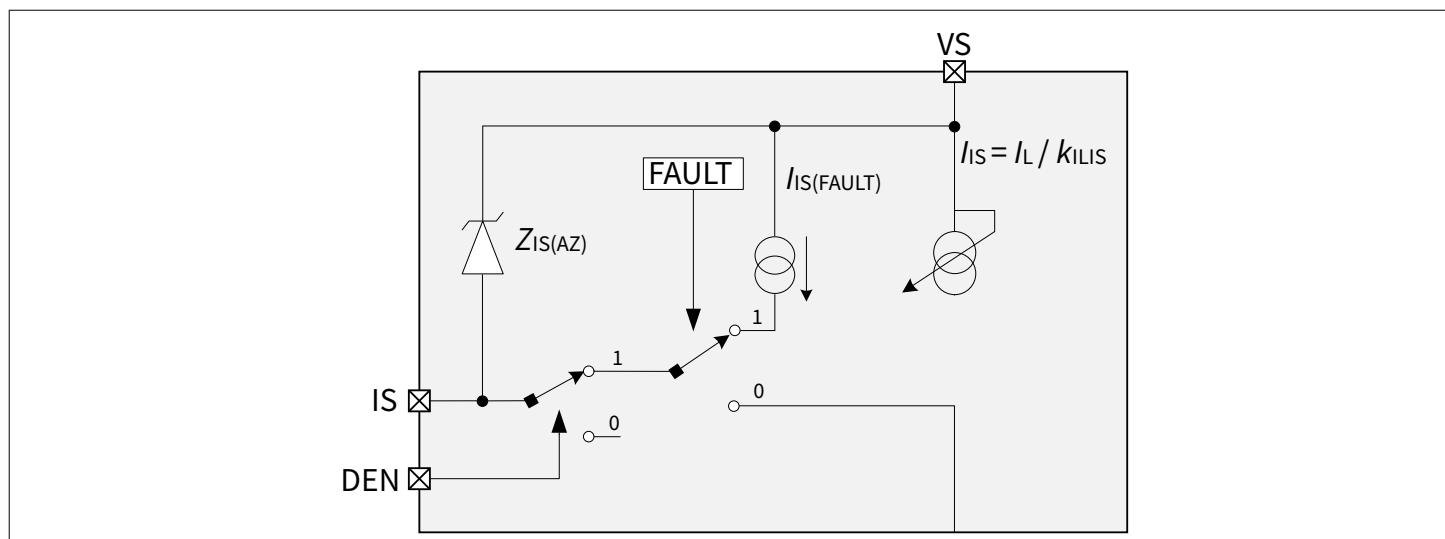


Figure 21

Diagnostic Block Diagram

## 7.2 SENSE Signal in Different Operating Modes

Table 8 gives a quick reference for the state of the IS pin during device operation.

**Table 8 Sense Signal, Function of Operation Mode**

Operation Mode	Input level	DEN	Output Level	Diagnostic Output
Normal operation	OFF	H	Z	Z
Short circuit to GND			~ GND	Z
Overtemperature			Z	Z
Short circuit to $V_S$			$V_S$	$I_{IS(FAULT)}$
Open Load			$< V_{OL(OFF)}$	Z
Inverse current			$> V_{OL(OFF)}^{1)}$	$I_{IS(FAULT)}$
OCT-pin short circuit to GND			~ $V_{INV}$	Z
Normal operation			Z	$I_{IS(FAULT)}$
Current limitation	ON	L	~ $V_S$	$I_{IS} = I_L / k_{ILIS}$
OCT-pin short circuit to GND			$< V_S$	$I_{IS(FAULT)}$
Short circuit to GND			~ $V_S$	$I_{IS} = I_L / k_{ILIS}$
Overtemperature			~ GND	$I_{IS(FAULT)}$
Short circuit to $V_S$			Z	$I_{IS(FAULT)}$
Open Load			$V_S$	$I_{IS} < I_L / k_{ILIS}$
Inverse current			~ $V_S^{2)}$	$I_{IS} < I_{IS(OL)}$
Underload			~ $V_S^{3)}$	$I_{IS(OL)} < I_{IS} < I_L / k_{ILIS}$
Diagnostic Disabled	Don't care	L	Don't care	Z

1) With additional pull-up resistor

2) The output current has to be smaller than  $I_{L(OL)}$

3) The output current has to be higher than  $I_{L(OL)}$

### 7.3 SENSE Signal in the Nominal Current Range

Figure 22 and Figure 24 show the current sense as a function of the load current in the power DMOS. Usually, a resistor  $R_{IS}$  is connected to the current sense IS pin. This resistor has to be higher than  $560\ \Omega$  to limit the power losses in the sense circuitry. A typical value is  $1.2\ k\Omega$ . The blue curve represents the ideal sense current, assuming an ideal  $k_{ILIS}$  factor value. The red curves show the accuracy the device provides across full temperature range, at a defined current.

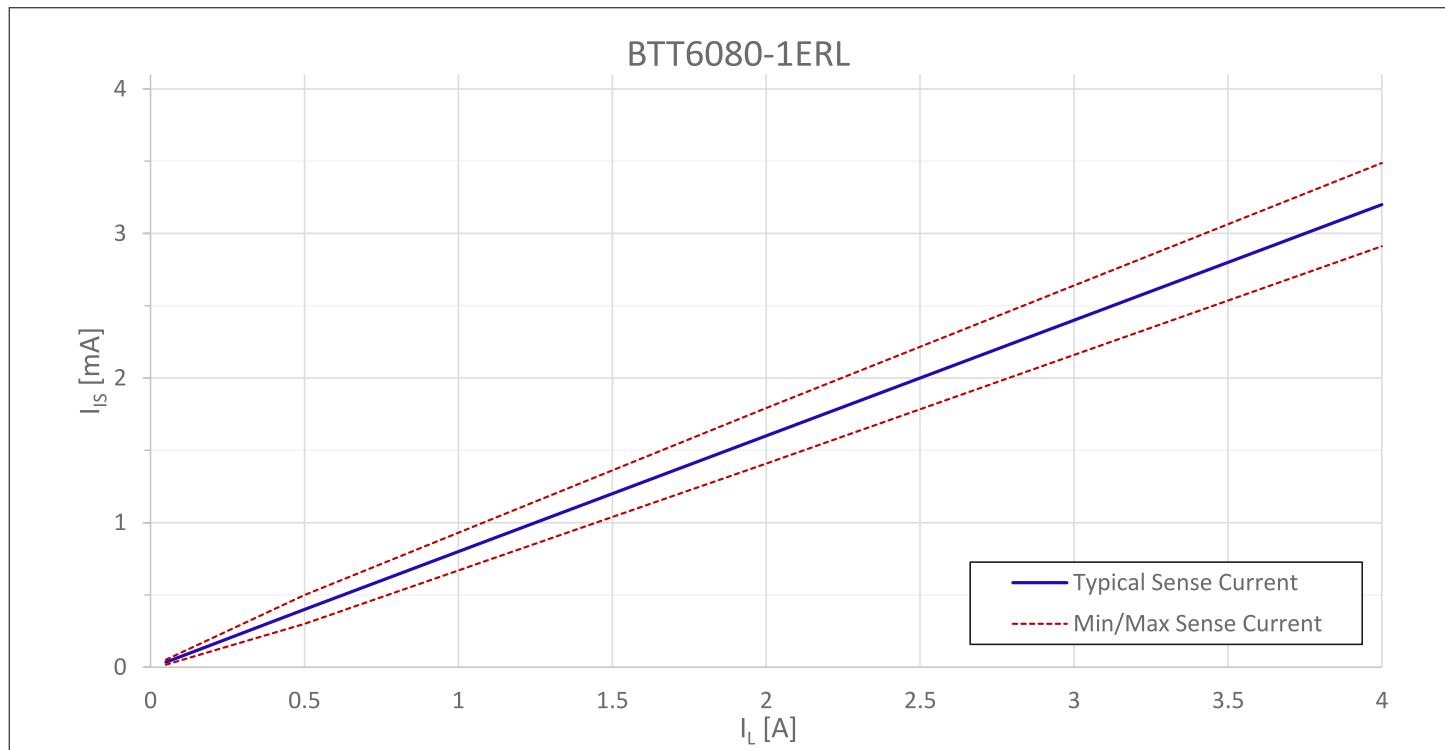


Figure 22

Current Sense for Nominal Load

### 7.3.1 SENSE Signal Variation as a Function of Temperature and Load Current

In some applications a better accuracy is required around half the nominal current  $I_{L(NOM)}$ . To achieve this accuracy requirement, a calibration on the application is possible. To avoid multiple calibration points at different load and temperature conditions, the BTT6080-1ERL allows limited derating of the  $k_{ILIS}$  value, at a given point ( $I_{L3}$ ;  $T_J = +25^\circ\text{C}$ ). This derating is described by the parameter  $\Delta k_{ILIS}$ .

Figure 23 shows the behavior of the sense current, assuming one calibration point at nominal load at  $+25^\circ\text{C}$ . The blue line indicates the typical  $k_{ILIS}$  ratio. The red lines indicate the  $k_{ILIS}$  accuracy without calibration. The green lines indicate the derating on the parameter across temperature and voltage, assuming one calibration point at nominal temperature and nominal battery voltage.

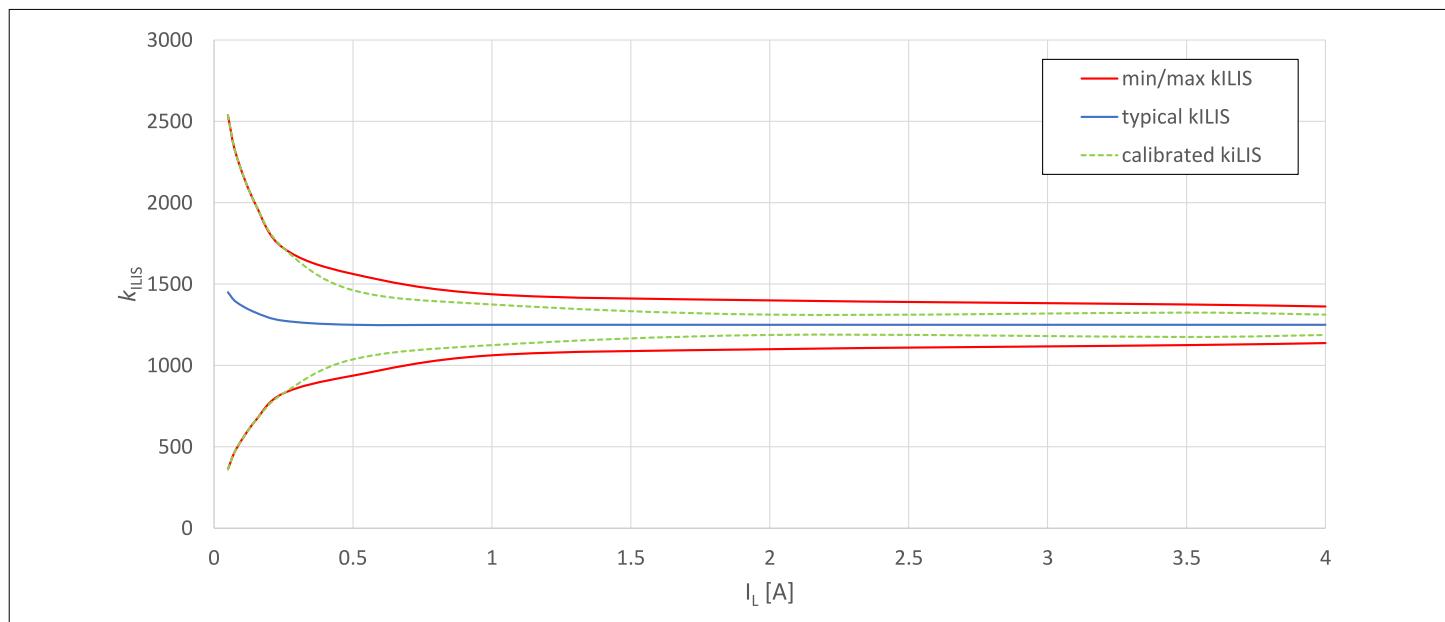


Figure 23

Improved Current Sense Accuracy with One Calibration Point

### 7.3.2 SENSE Signal Timing

Figure 24 shows the timing during settling and disabling of the sense.

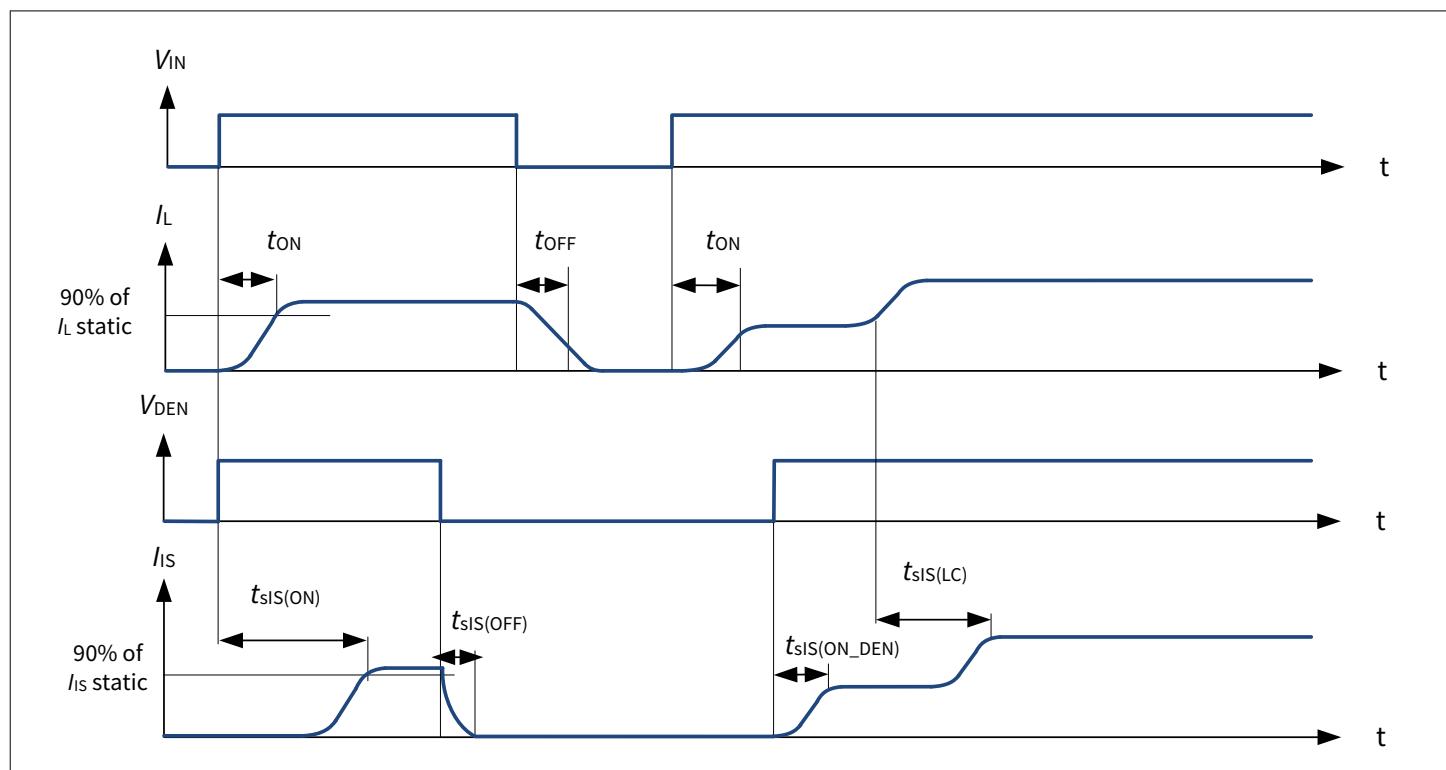


Figure 24 Current Sense Settling / Disabling Timing

### 7.3.3 SENSE Signal in Open Load

#### 7.3.3.1 Open Load in ON Diagnostic

If the channel is ON, a leakage current can still flow through an open load, for example due to humidity. The parameter  $I_{L(OL)}$  gives the threshold of recognition for this leakage current. If the current  $I_L$  flowing out the power DMOS is below this value, the device recognizes a failure, if the DEN is selected. In that case, the SENSE current is below  $I_{IS(OL)}$ . Otherwise, the minimum SENSE current is given above parameter  $I_{IS(OL)}$ . Figure 25 shows the SENSE current behavior in this area. The red curve shows a typical product curve. The blue curve shows the ideal current sense ratio.

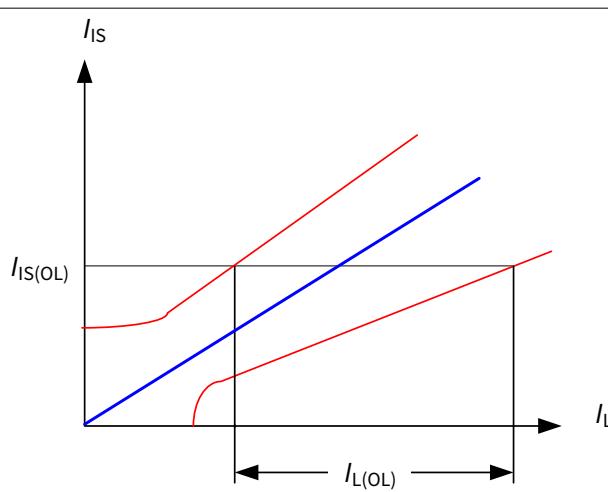


Figure 25 Current Sense Ratio for Low Currents

#### 7.3.3.2 Open Load in OFF Diagnostic

For open load diagnosis in OFF-state, an external output pull-up resistor ( $R_{OL}$ ) is recommended. For the calculation of pull-up resistor value, the leakage currents and the open load threshold voltage  $V_{OL(OFF)}$  have to be taken into account. Figure 26 gives a sketch of the situation.  $I_{leakage}$  defines the leakage current in the complete system, including  $I_{L(OFF)}$  (see Chapter 5.5) and external leakages in the application. (e.g, due to humidity, corrosion, etc....)

To reduce the stand-by current of the system, an open load resistor switch  $S_{OL}$  is recommended. If the channel is OFF, the output is no longer pulled down by the load and  $V_{OUT}$  voltage rises to nearly  $V_S$ . This is recognized by the device as an open load. The voltage threshold is given by  $V_{OL(OFF)}$ . In that case, the SENSE signal is switched to the  $I_{IS(FAULT)}$ .

An additional  $R_{PD}$  resistor can be used to pull  $V_{OUT}$  to 0 V. Otherwise, the OUT pin is floating. This resistor can be used as well for short circuit to battery detection, see Chapter 7.3.4.

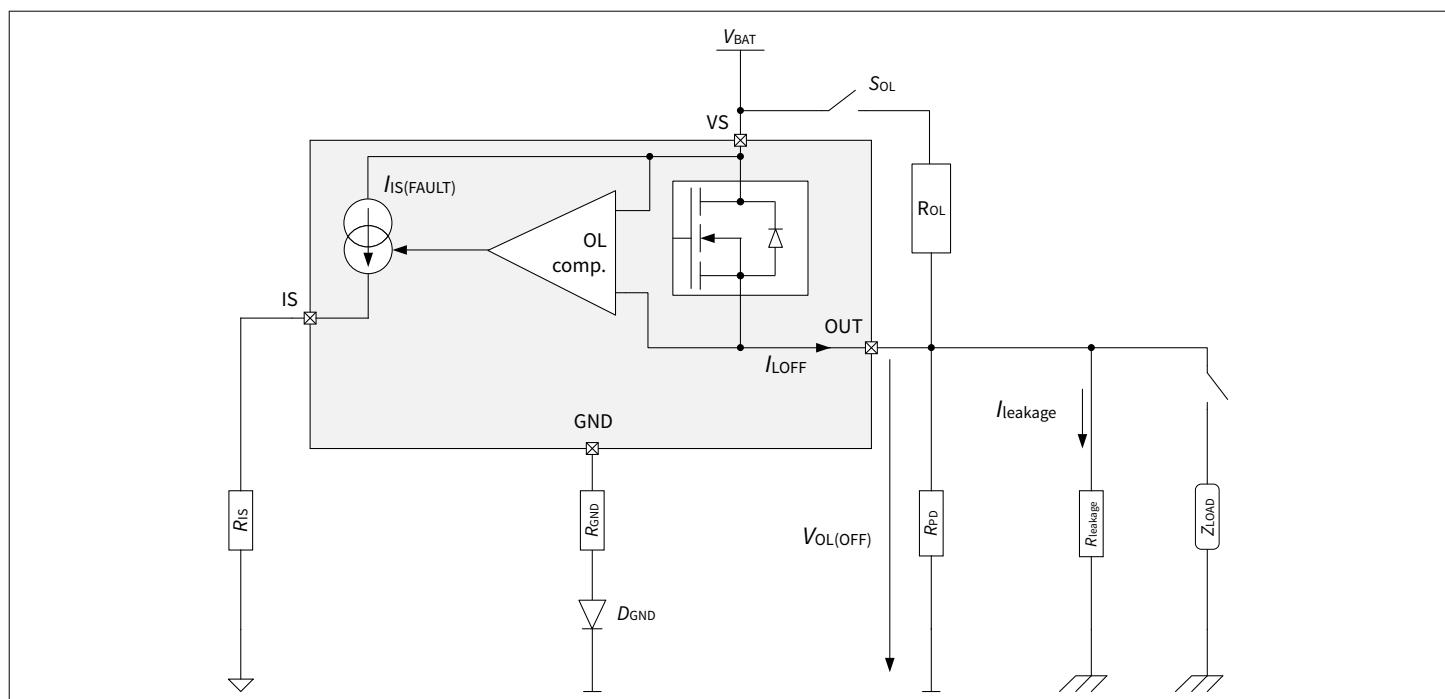


Figure 26 Open Load Detection in OFF Electrical Equivalent Circuit

### 7.3.3.3 Open Load Diagnostic Timing

Figure 27 shows the timing during either Open Load in ON or OFF condition when the DEN pin is HIGH. Please note that a delay  $t_{SIS(FAULT\_OL\_OFF)}$  has to be respected after the falling edge of the input, when applying an open load in OFF diagnosis request, otherwise the diagnosis can be wrong.

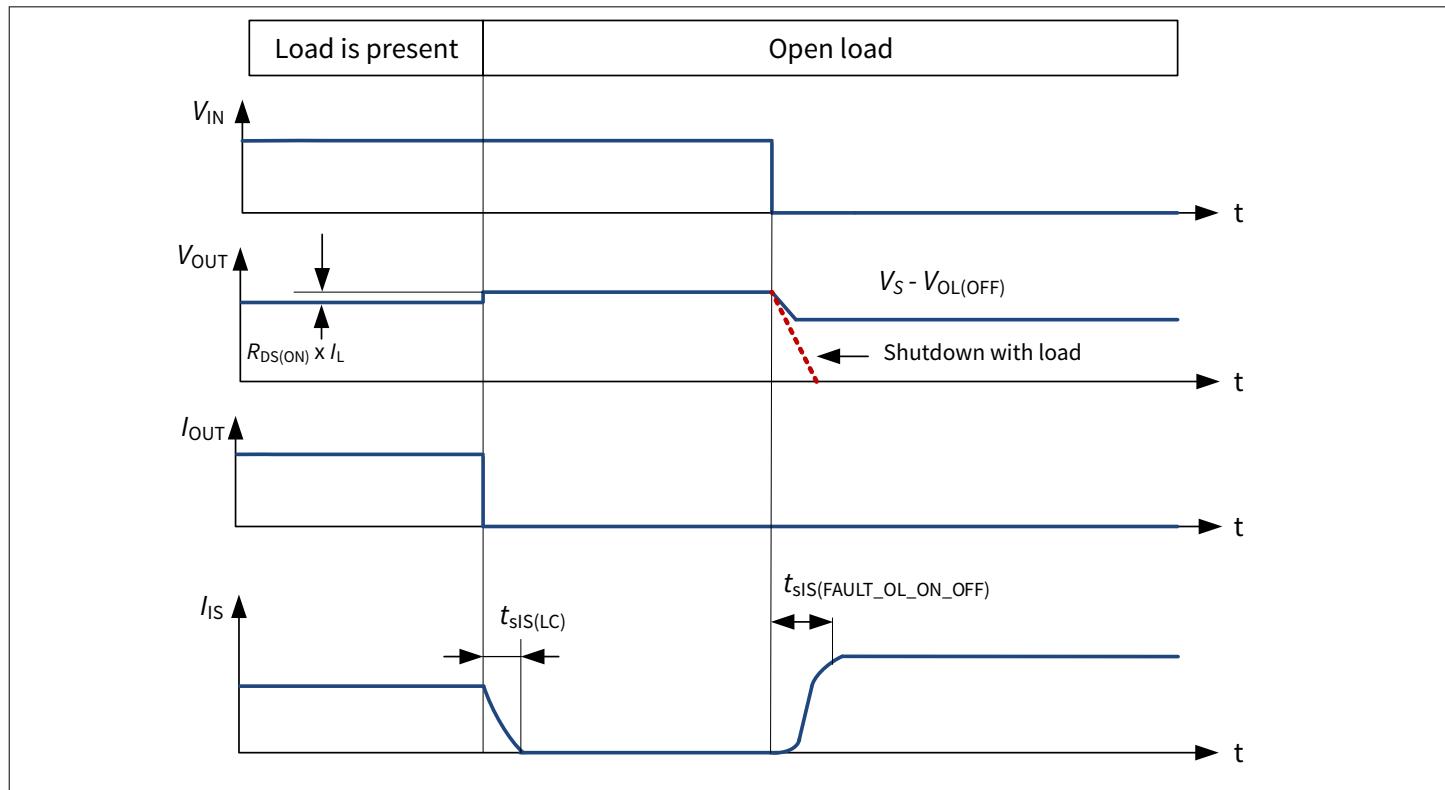


Figure 27 SENSE Signal in Open Load Timing

### 7.3.4 SENSE Signal with OUT in Short Circuit to $V_S$

In case of a short circuit between the OUTput-pin and the  $V_S$  pin, all or portion (depending on the short circuit impedance) of the load current will flow through the short circuit. As a result, a lower current compared to the normal operation will flow through the DMOS of the BTT6080-1ERL, which can be recognized at the SENSE signal. The open load at OFF detection circuitry can also be used to distinguish a short circuit to  $V_S$ . In that case, an external resistor to ground  $R_{SC\_VS}$  is required. Figure 28 gives a sketch of the situation.

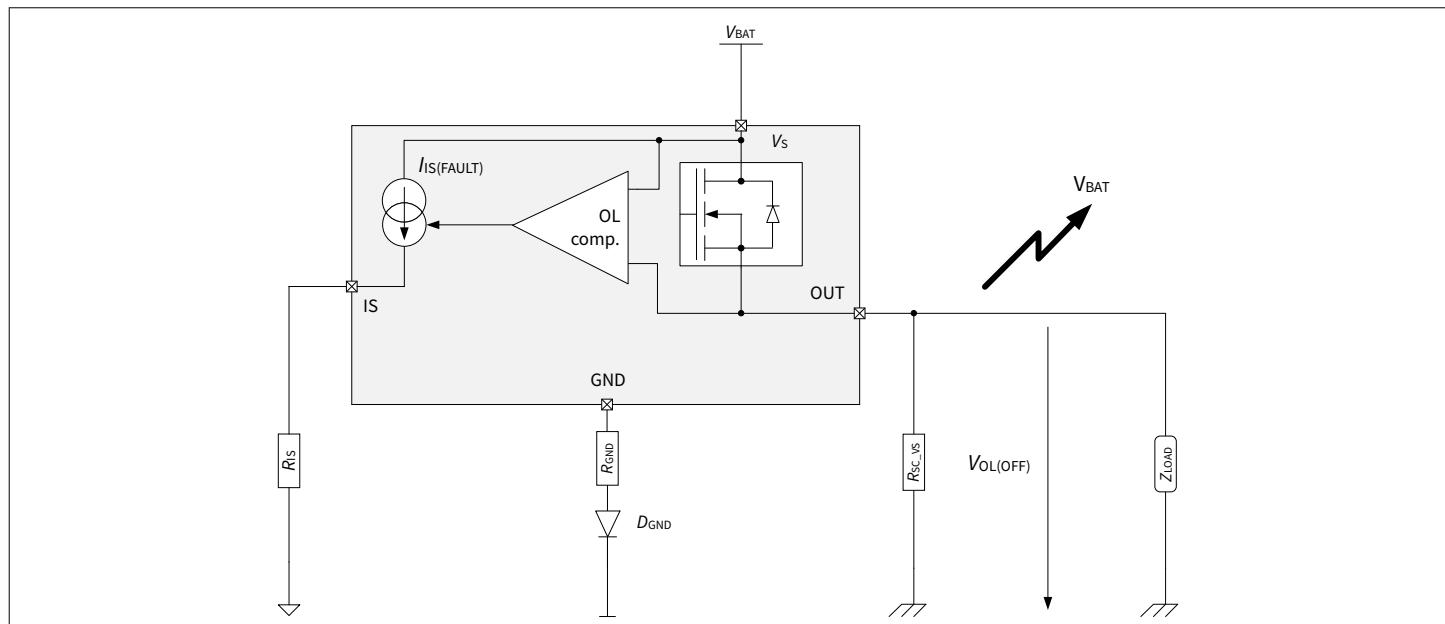


Figure 28 Short Circuit to Battery Detection in OFF Electrical Equivalent Circuit

### 7.3.5 SENSE Signal in Case of Overload

An overload condition is defined by a current flowing out of the DMOS reaching the current limitation and / or the absolute dynamic temperature swing  $T_{J(SW)}$  is reached, and / or the junction temperature reaches the thermal shutdown temperature  $T_{J(SC)}$ . Please refer to Chapter 6.5 for details.

If the diagnostic is selected, SENSE signal shows  $I_{S(FAULT)}$  value.

The device has a thermal latch behavior, such that when the overtemperature or the exceed dynamic temperature condition has disappeared, the DMOS is reactivated only when the IN is toggled LOW to HIGH. If the DEN pin is activated the SENSE follows the output stage. If no reset of the latch occurs, the device remains in the latching condition and  $I_{S(FAULT)}$  at the IS pin, even though the DMOS is OFF.

### 7.3.6 SENSE Signal in Case of Inverse Current

During inverse current, the sense signal will change to high impedance status when  $V_{OUT} \geq V_S + 10 \text{ mV}$ .

## 7.4 Electrical Characteristics Diagnostic Function

**Table 9 Electrical Characteristics: Diagnostics**

$V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)

Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
<b>Load Condition Threshold for Diagnostics</b>							
Open load detection threshold in OFF state	$V_S - V_{OL(OFF)}$	4	–	6	V	$V_{IN} = 0 \text{ V}$ $V_{DEN} = 4.5 \text{ V}$	P_7.5.1
Open load detection threshold in ON state	$I_{L(OL)}$	3	–	25	mA	$V_{IN} = V_{DEN} = 4.5 \text{ V}$ $I_{IS(OL)} = 5 \mu\text{A}$ See <a href="#">Figure 25</a>	P_7.5.2
<b>Sense Pin</b>							
IS pin leakage current when sense is disabled	$I_{IS(DIS)}$	–	–	1	$\mu\text{A}$	$V_{IN} = 4.5 \text{ V}$ $V_{DEN} = 0 \text{ V}$ $I_L = 3.5 \text{ A}$	P_7.5.4
Sense signal saturation voltage	$V_S - V_{IS}$ (RANGE)	1	–	3.5	V	$V_{IN} = 0 \text{ V}$ $V_{OUT} = V_S > 10 \text{ V}$ $V_{DEN} = 4.5 \text{ V}$ $I_{IS} = 6 \text{ mA}$	P_7.5.6
Sense fault current	$I_{IS(FAULT)-40}$	3	24	35	mA	$V_{IS} = V_{IN} = 0 \text{ V}$ $V_{OUT} = V_S > 10 \text{ V}$ $V_{DEN} = 4.5 \text{ V}$ $T_J = -40^\circ\text{C}$ See <a href="#">Figure 21</a>	P_7.5.7
Sense fault current	$I_{IS(FAULT)-25}$	4.5	24	35	mA	$V_{IS} = V_{IN} = 0 \text{ V}$ $V_{OUT} = V_S > 10 \text{ V}$ $V_{DEN} = 4.5 \text{ V}$ $T_J \geq 25^\circ\text{C}$ See <a href="#">Figure 21</a>	P_7.5.33
Sense pin maximum voltage	$V_{IS(AZ)}$	65	70	75	V	$I_{IS} = 5 \text{ mA}$ See <a href="#">Figure 21</a>	P_7.5.3
<b>Current Sense Ratio Signal in the Nominal Area, Stable Load Current Condition</b>							
Current sense ratio $I_{L0} = 50 \text{ mA}$	$k_{ILIS0}$	-75%	1450	+75%		$V_{IN} = 4.5 \text{ V}$ $V_{DEN} = 4.5 \text{ V}$	P_7.5.8
Current sense ratio $I_{L1} = 0.5 \text{ A}$	$k_{ILIS1}$	-25%	1250	+25%		See <a href="#">Figure 22</a> $T_J = -40^\circ\text{C; } 150^\circ\text{C}$	P_7.5.9

(table continues...)

**Table 9 (continued) Electrical Characteristics: Diagnostics** $V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$ 

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Current sense ratio $I_{L2} = 2.5 \text{ A}$	$k_{ILIS2}$	-12%	1250	+12%		<a href="#">1) <math>k_{ILIS3}</math> versus <math>k_{ILIS2}</math> See Figure 23</a>	P_7.5.10
Current sense ratio $I_{L3} = 3.5 \text{ A}$	$k_{ILIS3}$	-10%	1250	+10%			
$k_{ILIS}$ derating with current and temperature	$\Delta k_{ILIS}$	-6	0	+6	%	<a href="#">1) <math>k_{ILIS3}</math> versus <math>k_{ILIS2}</math> See Figure 23</a>	P_7.5.17

**Diagnostic Timing in Normal Condition**

Current sense settling time to $k_{ILIS}$ function stable after positive input slope on both INput and DEN	$t_{SIS(ON)}$	-	-	350	μs	<a href="#">1) <math>V_{DEN} = V_{IN} = 0 \text{ to } 4.5 \text{ V}</math> <math>V_S = 28 \text{ V}</math> <math>R_{IS} = 1.2 \text{ k}\Omega</math> <math>C_{SENSE} &lt; 100 \text{ pF}</math> <math>I_L = 2.5 \text{ A}</math> See Figure 24</a>	P_7.5.18
Current sense settling time with load current stable and transition of the DEN	$t_{SIS(ON\_DEN)}$	-	-	10	μs	$V_{IN} = 4.5 \text{ V}$ $V_{DEN} = 0 \text{ to } 4.5 \text{ V}$ $R_{IS} = 1.2 \text{ k}\Omega$ $C_{SENSE} < 100 \text{ pF}$ $I_L = 2.5 \text{ A}$ See Figure 24	P_7.5.19
Current sense settling time to $I_{IS}$ stable after positive input slope on current load	$t_{SIS(LC)}$	-	-	20	μs	<a href="#">1) <math>V_{IN} = 4.5 \text{ V}</math> <math>V_{DEN} = 4.5 \text{ V}</math> <math>R_{IS} = 1.2 \text{ k}\Omega</math> <math>C_{SENSE} &lt; 100 \text{ pF}</math> <math>I_L = I_{L2} = 2.5 \text{ A to } I_{L3} = 3.5 \text{ A}</math> See Figure 24</a>	P_7.5.20

**Diagnostic Timing in Open Load Condition**

Current sense settling time to $I_{IS}$ stable for open load detection in OFF state	$t_{SIS(FAULT\_OL\_OFF)}$	-	-	100	μs	$V_{IN} = 0 \text{ V}$ $V_{DEN} = 0 \text{ to } 4.5 \text{ V}$ $R_{IS} = 1.2 \text{ k}\Omega$ $C_{SENSE} < 100 \text{ pF}$ $V_{OUT} = V_S = 28 \text{ V}$ See Figure 27	P_7.5.22
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**(table continues...)**

**Table 9 (continued) Electrical Characteristics: Diagnostics** $V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$ 

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			
Current sense settling time for open load detection in ON-OFF transition	$t_{SIS(FAULT\_OL\_ON\_OFF)}$	–	200	–	μs	<sup>1)</sup> $V_{IN} = 4.5 \text{ to } 0 \text{ V}$ $V_{DEN} = 4.5 \text{ V}$ $R_{IS} = 1.2 \text{ k}\Omega$ $C_{SENSE} < 100 \text{ pF}$ $V_{OUT} = V_S = 28 \text{ V}$ See Figure 27	P_7.5.23

**Diagnostic Timing in Overload Condition**

Current sense settling time to $I_{IS}$ stable for overload detection	$t_{SIS(FAULT)}$	–	–	150	μs	<sup>1)</sup> $V_{IN} = V_{DEN} = 0 \text{ to } 4.5 \text{ V}$ $R_{IS} = 1.2 \text{ k}\Omega$ $C_{SENSE} < 100 \text{ pF}$ $V_{DS} = 24 \text{ V}$ See Figure 20	P_7.5.24
Current sense over current blanking time	$t_{SIS(OC\_blank)}$	–	350	–	μs	<sup>1)</sup> $V_{IN} = V_{DEN} = 4.5 \text{ V}$ $R_{IS} = 1.2 \text{ k}\Omega$ $C_{SENSE} < 100 \text{ pF}$ $V_{DS} = 5 \text{ V to } 0 \text{ V}$ See Figure 20	P_7.5.32
Diagnostic disable time DEN transition to $I_{IS} < 50\% I_L / k_{ILIS}$	$t_{SIS(OFF)}$	–	–	20	μs	$V_{IN} = 4.5 \text{ V}$ $V_{DEN} = 4.5 \text{ V to } 0 \text{ V}$ $R_{IS} = 1.2 \text{ k}\Omega$ $C_{SENSE} < 100 \text{ pF}$ $I_L = I_{L3} = 3.5 \text{ A}$ See Figure 24	P_7.5.25

1) Not subject to production test, specified by design

## 8

## Logic Pins

## 8.1 Input Circuitry

The input circuitry is compatible with 3.3 and 5 V microcontrollers. The concept of the input pin is to react to voltage thresholds. An implemented Schmitt trigger avoids any undefined state if the voltage on the input pin is slowly increasing or decreasing. The output is either OFF or ON but cannot be in a linear or undefined state. The input circuitry is compatible with PWM applications. Figure 29 shows the electrical equivalent input circuitry. In case the pin is not needed, it must be left opened, or must be connected to device ground (and not module ground) via an input resistor.

The IN and DEN use a comparator with hysteresis. The switching ON / OFF takes place in a defined region, set by the thresholds  $V_{IN(L)}$  Max. and  $V_{IN(H)}$  Min. The exact value where the ON and OFF take place are unknown and depends on the process, as well as the temperature. To avoid cross talk and parasitic turn ON and OFF, a hysteresis is implemented. This ensures a certain immunity to noise.

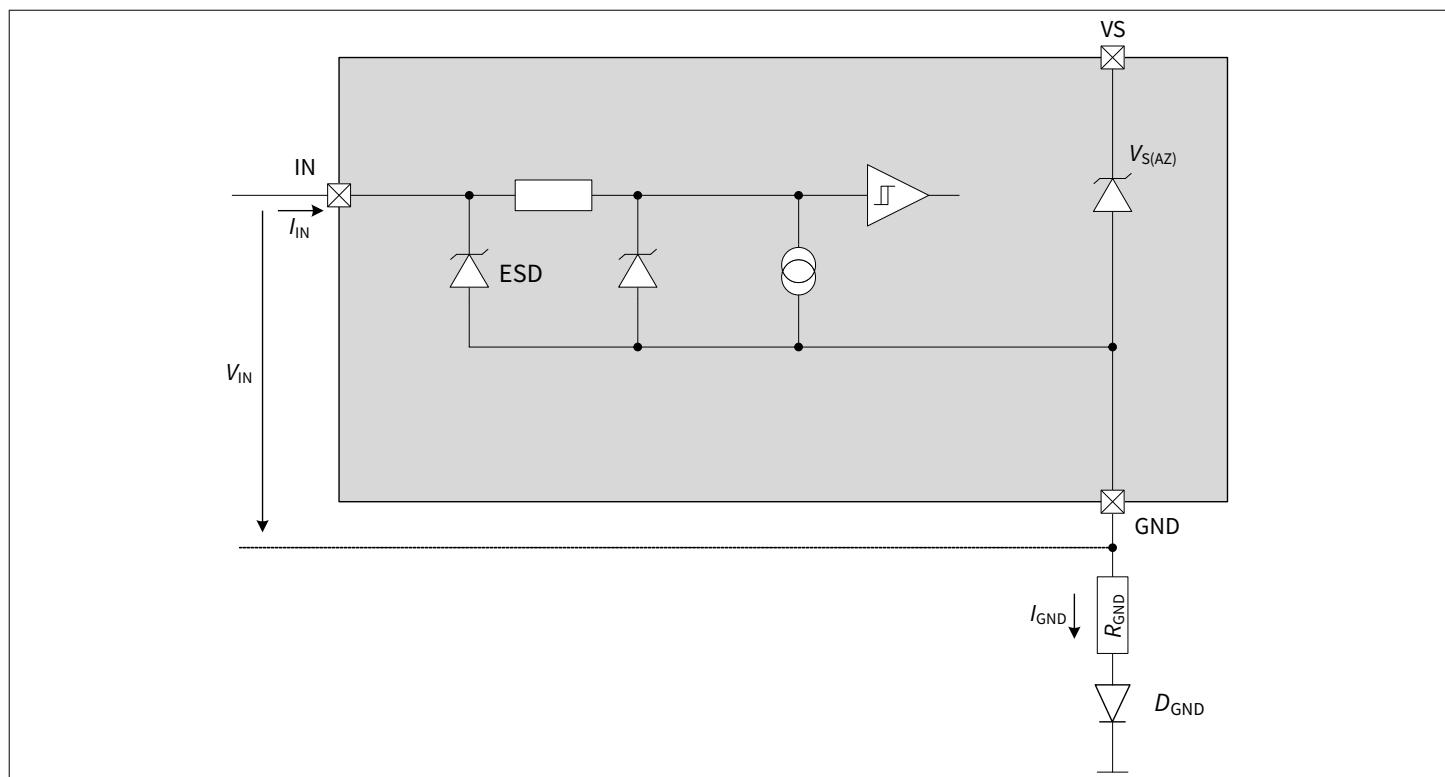


Figure 29

Input Pin Circuitry

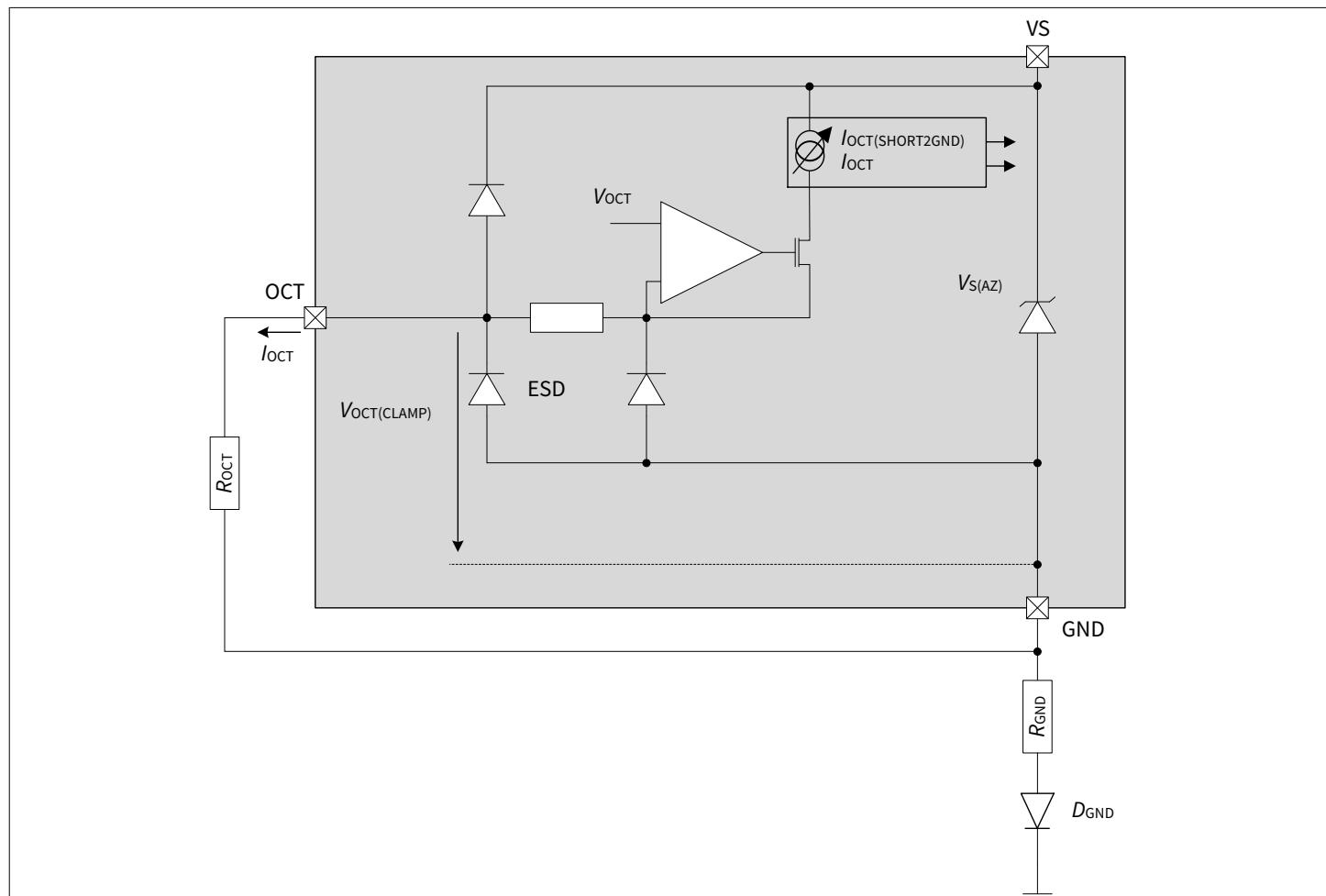
## 8.2 DEN Pin

The DEN pin enables and disables the diagnostic functionality of the device. The pin has the same structure as the INput pin, please refer to [Figure 29](#).

### 8.3 OCT Pin

The device has one analog pin for direct control.

To be able to adjust the overcurrent threshold for the OUT pin, the device offers an OCT pin. The pin needs to be connected to device ground via an external resistor  $R_{OCT}$ . The external adjustable current limit allows the flexibility to adjust to overcurrent limitation as defined in the [Table 10](#). This improves the reliability of the system by limiting the inrush or overload current. The electrical equivalent of the overcurrent pin circuitry is shown in [Figure 30](#) below.



**Figure 30**

## Overcurrent pin circuit

## 8.4 Electrical Characteristics

**Table 10 Electrical Characteristics: Input Pins**

$V_S = 8 \text{ V to } 36 \text{ V}$ ,  $T_J = -40^\circ\text{C to } +150^\circ\text{C}$  (unless otherwise specified)

Typical values are given at  $V_S = 28 \text{ V}$ ,  $T_J = 25^\circ\text{C}$

Parameter	Symbol	Values			Unit	Note or Test Condition	Number
		Min.	Typ.	Max.			

### Input Pins Characteristics

Low level input voltage range	$V_{IN(L)}$	-0.3	-	0.8	V	-	P_8.4.1
High level input voltage range	$V_{IN(H)}$	2	-	6	V	-	P_8.4.2
Input voltage hysteresis	$V_{IN(HYS)}$	-	250	-	mV	<sup>1)</sup>	P_8.4.3
Low level input current	$I_{IN(L)}$	1	10	25	$\mu\text{A}$	$V_{IN} = 0.8 \text{ V}$	P_8.4.4
High level input current	$I_{IN(H)}$	2	10	25	$\mu\text{A}$	$V_{IN} = 5.5 \text{ V}$	P_8.4.5

### DEN Pin

Low level input voltage range	$V_{DEN(L)}$	-0.3	-	0.8	V	-	P_8.4.6
High level input voltage range	$V_{DEN(H)}$	2	-	6	V	-	P_8.4.7
Input voltage hysteresis	$V_{DEN(HYS)}$	-	250	-	mV	<sup>1)</sup>	P_8.4.8
Low level input current	$I_{DEN(L)}$	1	10	25	$\mu\text{A}$	$V_{DEN} = 0.8 \text{ V}$	P_8.4.9
High level input current	$I_{DEN(H)}$	2	10	25	$\mu\text{A}$	$V_{DEN} = 5.5 \text{ V}$	P_8.4.10

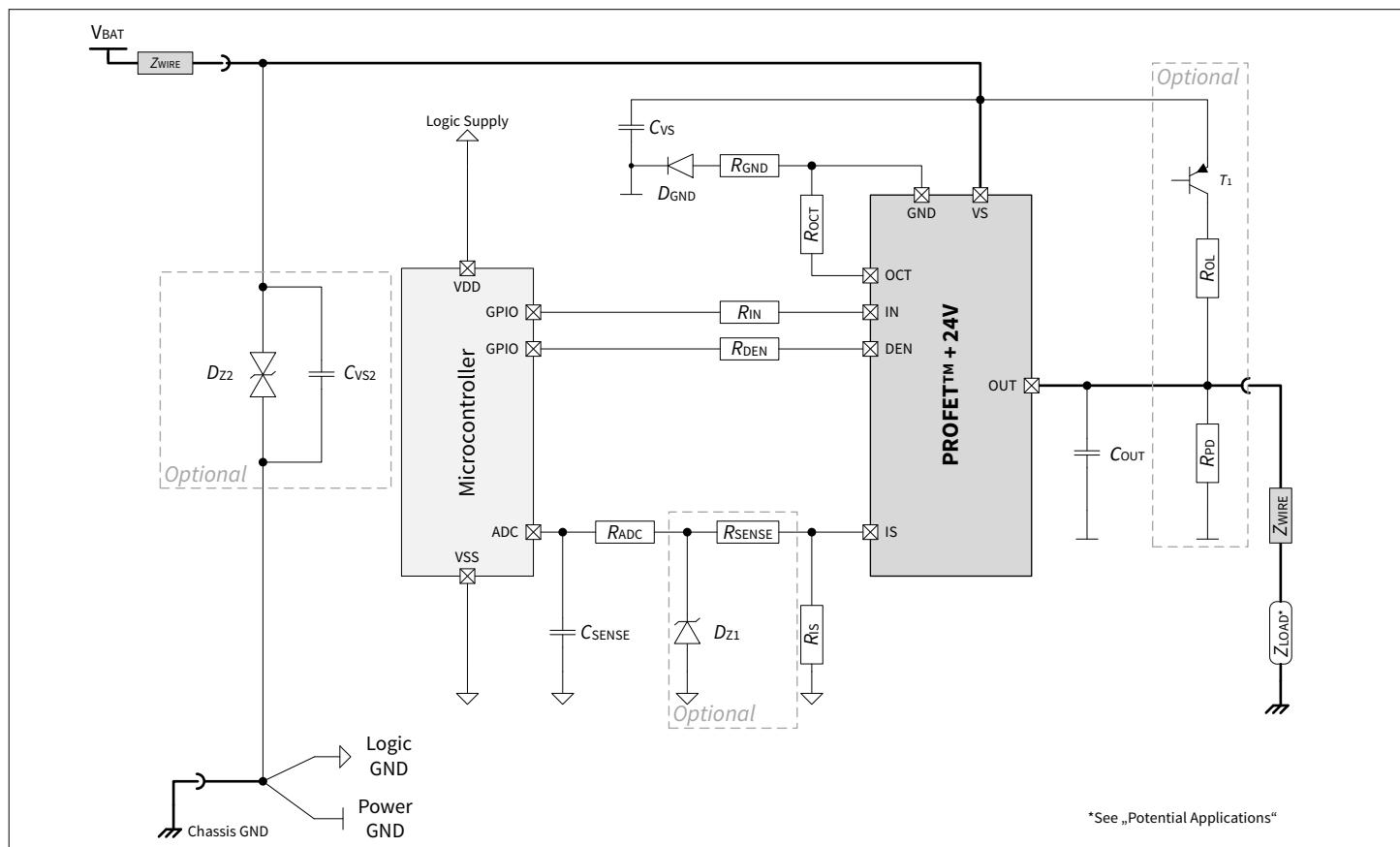
### OCT Pin

Analog Input Clamping	$V_{OCT(CLAMP)}$	-	$V_S$	-	V	<sup>1)</sup> $I_{OCT} = 1\text{mA}$	P_8.4.11
Voltage of Pin OCT							
Analog Overcurrent Reference Voltage	$V_{OCT}$	0.46	0.51	0.56	V	<sup>1)</sup> $I_{OCT,MIN} \leq I_{OCT} \leq I_{OCT,MAX}$ IN = "high"	P_8.4.12
Analog Adjustable Overcurrent Range	$I_{OCT}$	6.67	-	97.84	$\mu\text{A}$	<sup>1)</sup> IN = "high"	P_8.4.13
OCT short to device ground detection current	$I_{OCT(SHORT2GND)}$	150	-	240	$\mu\text{A}$	<sup>1)</sup> DEN = "high" IN = "low"	P_8.4.14

1) Not subject to production test, specified by design

## 9 Application Information

**Note:** The following information is given as a hint for the implementation of the device only and shall not be regarded as a description or warranty of a certain functionality, condition or quality of the device.



**Figure 31 Application Diagram with BTT6080-1ERL**

**Note:** This is a very simplified example of an application circuit. The function must be verified in the real application.

**Table 11 Bill of Material**

Reference	Value	Purpose
$R_{IN}$	10 kΩ	Protection of the microcontroller during overvoltage, reverse polarity. Guarantee BTT6080-1ERL channel is OFF during loss of ground
$R_{DEN}$	10 kΩ	Protection of the microcontroller during overvoltage, reverse polarity
$R_{PD}$	47 kΩ	Polarization of the output for short circuit to $V_S$ detection
$R_{OL}$	1.5 kΩ	Ensures polarization of the BTT6080-1ERL output during open load in OFF diagnostic
$R_{IS}$	1.2 kΩ	Sense resistor
$R_{SENSE}$	4.7 kΩ	Overvoltage, reverse polarity, loss of ground. Value to be tuned with micro controller specification
$R_{OCT}$	5.3 kΩ - 75 kΩ	Adjustable overcurrent threshold with different resistors

**(table continues...)**

**Table 11 (continued) Bill of Material**

Reference	Value	Purpose
$C_{SENSE}$	100 pF	Sense signal filtering
$C_{OUT}$	10 nF	Protection of the device during ESD and BCI
$R_{GND}$	27 $\Omega$	Protection of the BTT6080-1ERL during overvoltage
$D_{GND}$	BAS21	Protection of the BTT6080-1ERL during reverse polarity
$D_{Z2}$	58 V TVS diode	Protection of the device during overvoltage
$C_{VS}$	100 nF	Filtering of voltage spikes at the battery line
T1	Dual NPN/PNP	Switch the battery voltage for open load in OFF diagnostic
$D_{Z1}$	7 V Zener diode	Protection of microcontroller during overvoltage. Value to be tuned according to microcontroller specifications
$R_{ADC}$	4.7 k $\Omega$	Protection of microcontroller ADC input during overvoltage, reverse polarity, loss of ground. Value to be tuned according to microcontroller specifications
$C_{VS2}$	-	Filtering/buffer capacitor located at $V_{BAT}$ connector. Value to be tuned according to application requirements

## 9.1 Further Application Information

- For further information you may visit [www.infineon.com](http://www.infineon.com)
- Please contact us for information regarding the pin behavior assessment

## 10

## Package Outlines

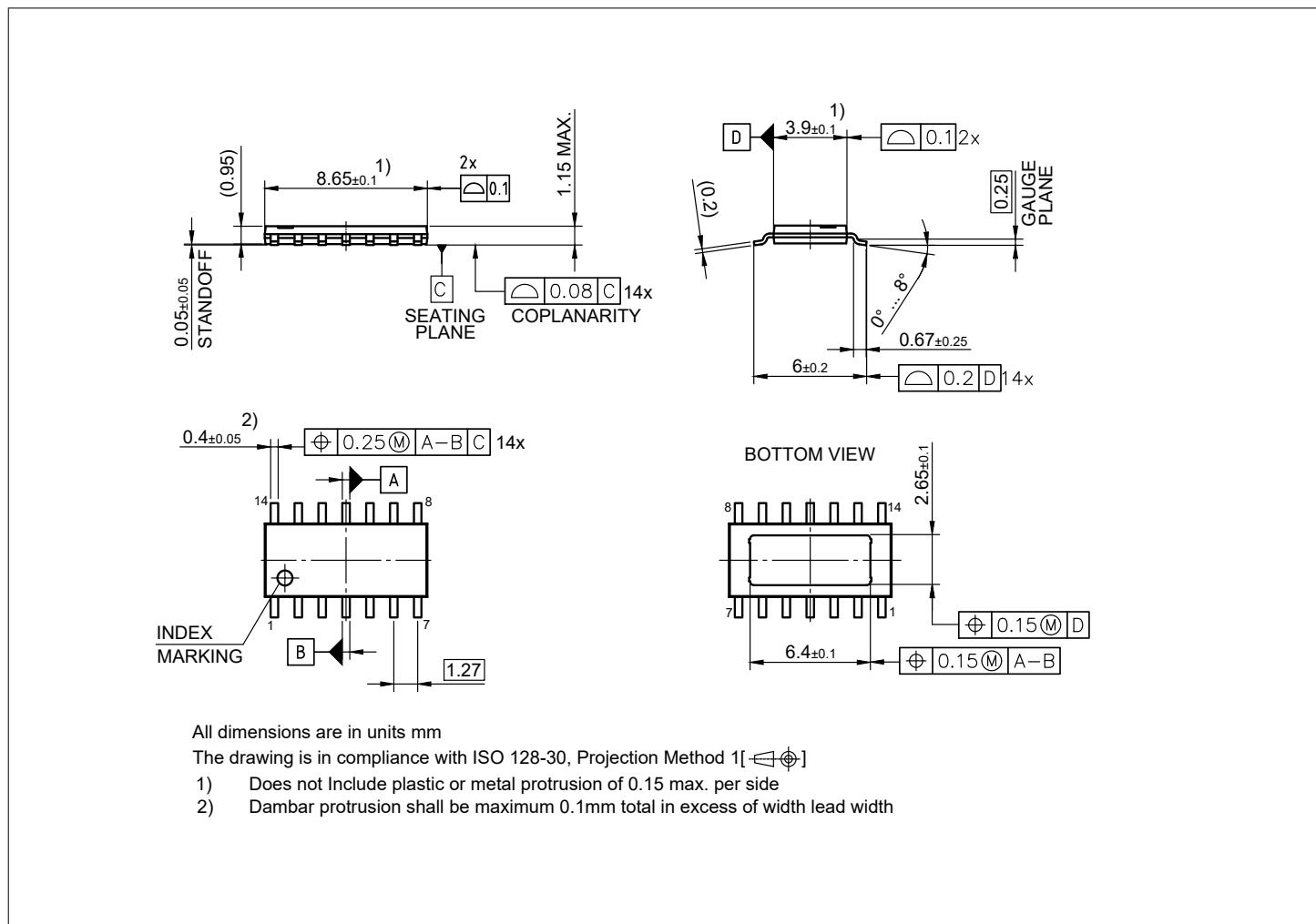


Figure 32 PG-TDSO-14<sup>1)</sup> (Plastic Dual Small Outline Package) (RoHS-Compliant)

### Green Product (RoHS compliant)

To meet the world-wide customer requirements for environmentally friendly products and to be compliant with government regulations the device is available as a green product. Green products are RoHS-Compliant (i.e Pb-free finish on leads and suitable for Pb-free soldering according to IPC/JEDEC J-STD-020).

### Legal Disclaimer for Short-Circuit Capability

Infineon disclaims any warranties and liabilities, whether expressed or implied, for any short-circuit failures below the threshold limit.

### Further information on packages

<https://www.infineon.com/packages>

<sup>1</sup> Dimensions in mm

## 11 Revision History

**11 Revision History**

Version	Date	Changes
Rev. 1.10	2025-07-17	Change of datasheet template Editorial changes P_5.5.16 updated P_8.4.13 updated Table "Sense Signal, Function of Operation Mode" updated P_6.6.2 updated <a href="#">Inverse Current Capability</a> updated <a href="#">SENSE Signal in Case of Inverse Current</a> updated P_8.4.12 parameter renamed
Rev. 1.00	2024-10-16	Datasheet release

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**Email: [erratum@infineon.com](mailto:erratum@infineon.com)**

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