

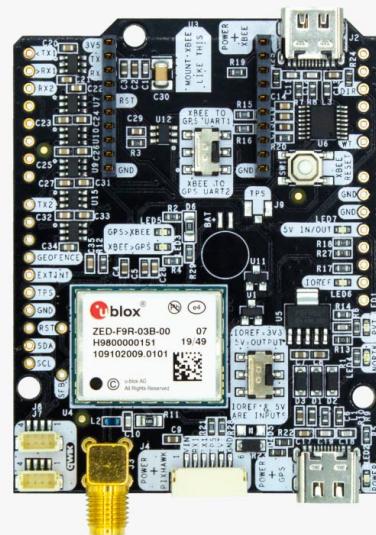
simpleRTK2B Fusion

Includes:

- 1 simpleRTK2B Fusion board (ZED-F9R)



More info about the product!



simpleRTK2B Fusion has several different configurations to provide you with flexibility:

SKU	Variation Name
AS-RTK2B-FUSIONF9R-L1L2-NH-00	Without headers
AS-RTK2B-FUSIONF9R-L1L2-HS-00	Headers soldered (+26€)

Get a discounted bulk price on this product for orders of 50 units or more. Contact us at info@ardusimple.com to get a quote.

Description

DISCLAIMER: This product is for advanced users only. Sensor fusion use and configuration might not be plug and play and requires integration work. Check the [documentation](#) and ask questions if necessary before making your purchase.

simpleRTK2B Fusion is a standalone board that allows to evaluate dual band RTK GNSS technology with Inertial Sensor Fusion. It can output centimeter location, but also full vehicle's attitude (roll, pitch, yaw) thanks to it's integrated IMU. It's based on **u-blox ZED-F9R** module and can be used standalone. Or connected with Arduino, Ardupilot / Pixhawk (JST connector), Raspberry Pi, Nvidia Jetson and STM32 Nucleo platforms, as a shield. It can provide every second with up to 30 RTK positions and attitude angles.

Good to know:

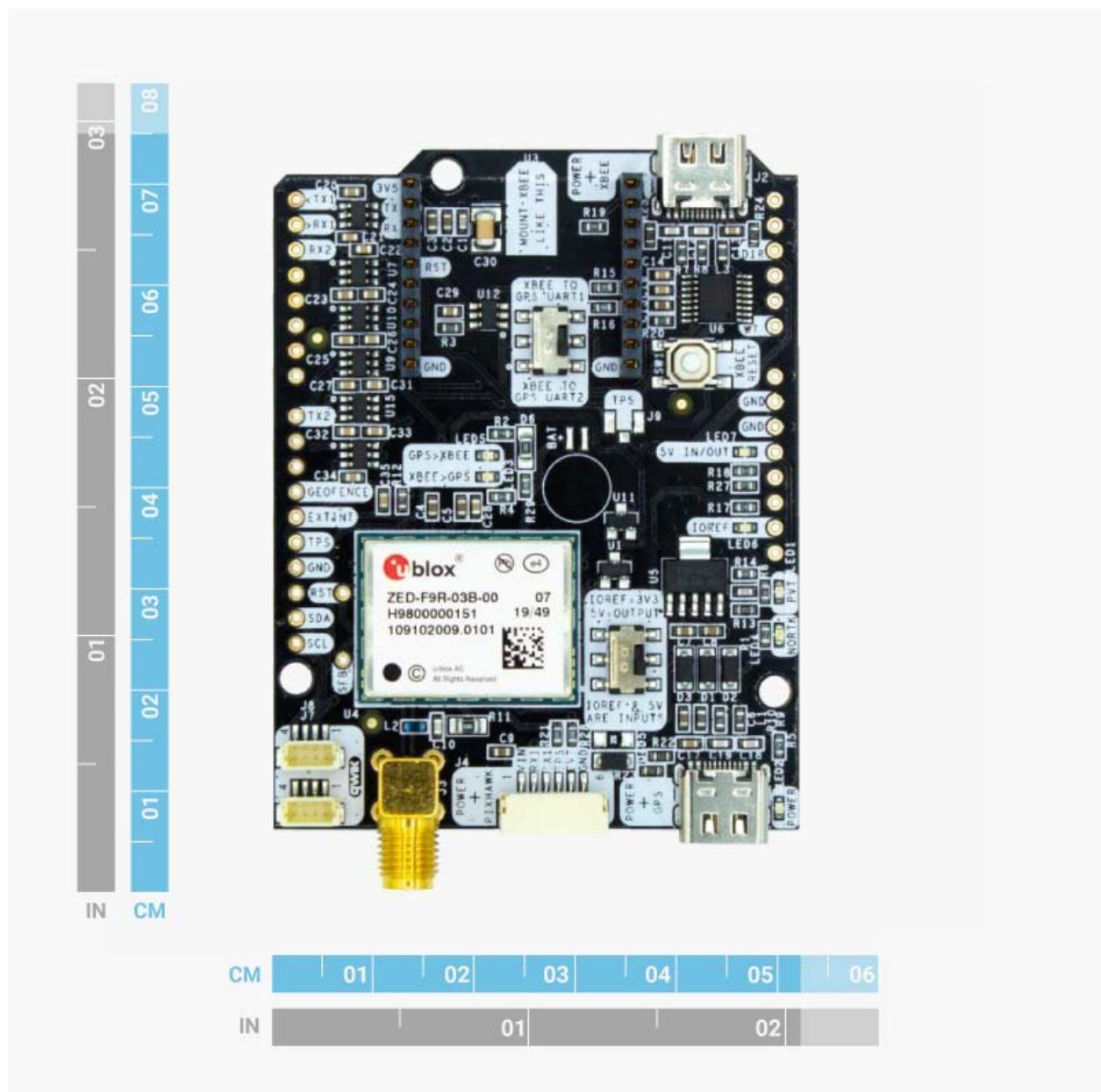
- This product is compatible but doesn't include a [multiband GNSS antenna](#).
- The module will not give good performance with a standard GNSS antenna, requires a L1/L2/E5b antenna.
- This product doesn't have base station functionality.
- This board is recommended if you want to test **u-blox ZED-F9R** performance.
- The onboard XBee socket can be used to expand functionality with Plugin accessories (MR/LR/XLR radios, Bluetooth, WiFi, Dataloggers, Ethernet, RS232, Canbus, L-Band, 4G/3G/2G).
- You can use the Shield for Second Plugin socket to connect 2 plugins at the same time.
- Compatible with ArduSimple plastic case
- This board has the option of mounting a backup battery to speed up the Time to First Fix and store sensor calibration data after a short power down. Note that this will not speed up the Time to First RTK fix, fresh satellite data is needed for that. If you want the board with the onboard V_BCKP battery mounted you can add the [Hand Soldering Service](#) to your cart.
- If you don't provide RTK corrections to this module, it will have the same performance as u-blox ZED-F9L.
- This product has the same performance as ZED-F9K.

Specifications

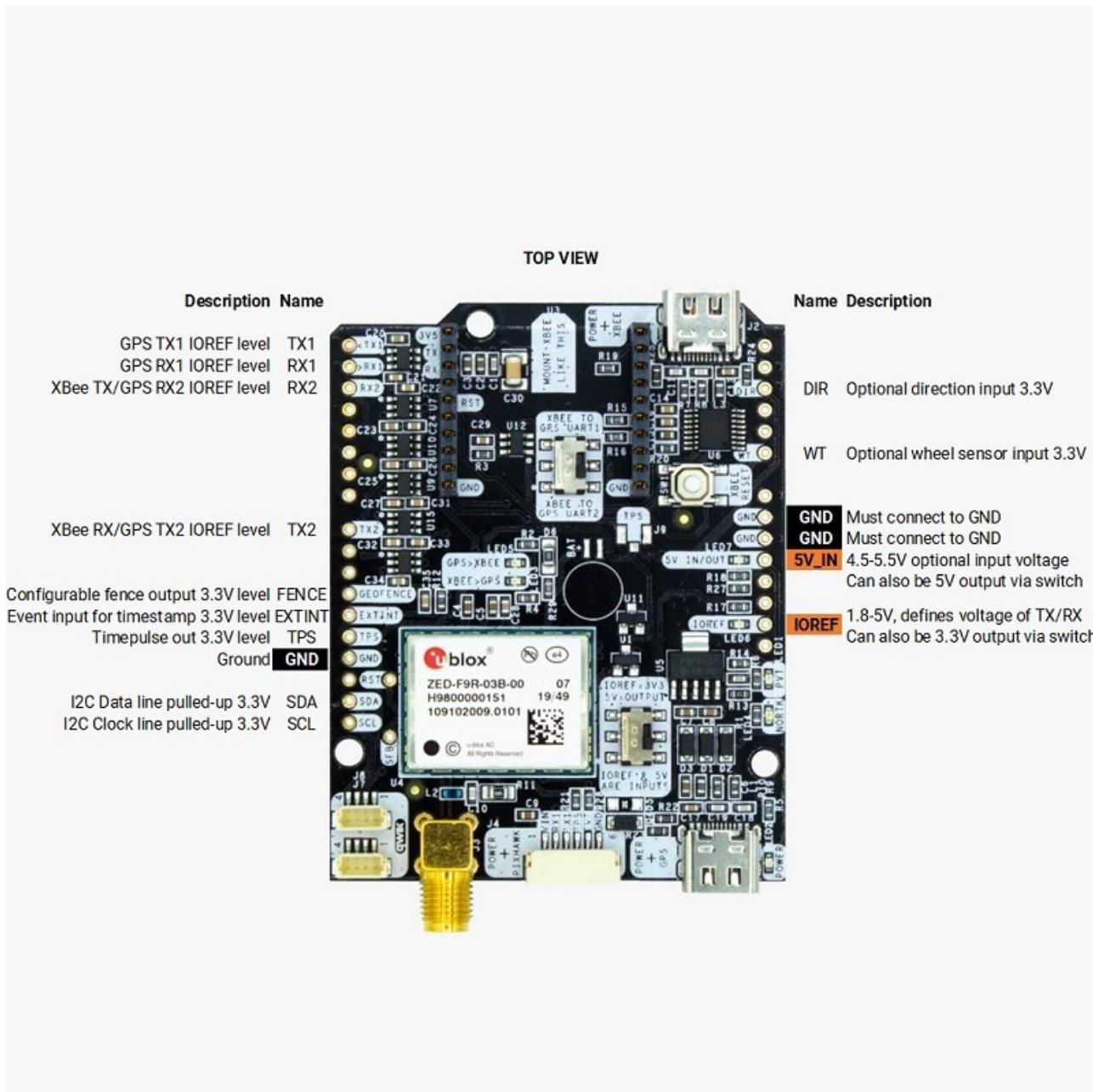
ZED-F9R features

- Centimeter level precision
 - <1cm with a base station up to 35km
 - <1cm with NTRIP up to 35km
 - <4cm with SSR corrections
 - <1.5m in standalone mode
 - <0.9m standalone with SBAS coverage
- Update rate
 - Default: 1Hz
 - Maximum fusion update rate: 30Hz
- Sensor fusion
 - Tilt: 10 mm + 0.7 mm/°tilt (accuracy 2.5 cm within 30°)
 - INS only: 2 % of the distance travelled without GNSS signals
 - IMU RAW data: 100Hz
- Multi band: L1, L2 and E5b support
- Multifrequency and Multiconstellation:
 - GPS: L1C/A L2C
 - GLONASS: L1OF L2OF
 - Galileo: E1-B/C E5b
 - BeiDou: B1I B2I
 - QZSS: L1C/A L2C
 - SBAS: WAAS, EGNOS, MSAS, GAGAN and SouthPAN
- Start-up times:
 - First position fix: 25 seconds (cold), 2 seconds (hot)
 - First RTK fix: 35 seconds (cold)
- Dynamic models: ground vehicle, slow-moving service robots and electric scooters (drones, boats and pedestrians not supported)
- RAW data output in UBX format
- No Base Station function, only RTK Rover
- Operating temperature Range: -40 to +85degC
- Documentation: RED, RoHS

Image Gallery



Pinout



simpleRTK2B Fusion includes free basic technical support. Contact info@ardusimple.com for more information.

Data and descriptions in this document are subject to change without notice. Product photos and pictures are for illustration purposes only and may differ from the real product appearance.