

SPECIFICATIONS:

STEPS PER REVOLUTION: 200	ROTOR INERTIA: 2.7KG-CM^2 (0.0387 OZ-IN-SEC 2) NOM
STEP ANGLE: 1.8°	DETENT TORQUE: 3.56 G-CM (49.5 OZ-IN) MIN
STEP TO STEP ACCURACY: $\pm .09$ DEGREES [1, 2]	INSULATION CLASS: B
POSITIONAL ACCURACY: $\pm .09$ DEGREES [1, 3]	WEIGHT: 3.8 KG (8.4 LBS)
SHAFT RUNOUT: 0.05 mm T.I.R. MAX	TEMP. RISE: 80 °C MAX. [9]
RADIAL PLAY: 0.025mm MAX W/A .5KG RADIAL LOAD	OPERATING TEMP. RANGE: -20 TO +50 °C
END PLAY: 0.075mm MAX W/A 1KG AXIAL LOAD	STORAGE TEMP. RANGE: -40 TO +70 °C
BEARINGS: ABEC 3, DOUBLE SHIELDED	RELATIVE HUMIDITY RANGE: 5 TO 99 %

7 8 1 1

SPECIFICATION CONNECTION	RESISTANCE PER PHASE OHM $\pm 10\%$	INDUCTANCE PER PHASE mH $\pm 20\%$	RATED CURRENT Amp	HOLDING TORQUE Nm Min	HOLDING TORQUE oz-in Min.
BI-POLAR SERIES	2.6	21.6	2.8	8.9	1260
BI-POLAR PARALLEL	0.63	5.4	5.6	8.9	1260
UNI-POLAR	1.29	5.4	4.0	6.4	906

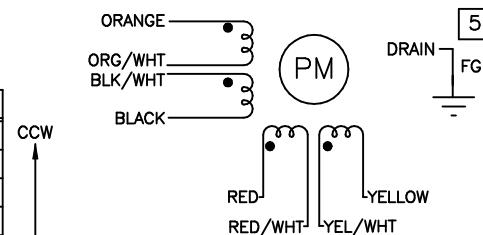
NOTES. UNLESS OTHERWISE SPECIFIED:

- 1. MEASUREMENTS MADE AT RATED CURRENT IN EACH PHASE.
- 2. BETWEEN ANY TWO ADJACENT FULL STEP POSITIONS.
- 3. MAXIMUM ERROR IN 360°.
- 4. HIPOT 1150 VAC, 60 Hz FOR ONE MINUTE.
- 5. LEADS: 8, 22AWG, 7 STRAND MIN.,UL AND CSA APPROVED, 105°C. SHIELDED CABLE, 8 CONDUCTOR W/DRAIN. CABLE 666-2126. DRAIN WIRE TO BE CONNECTED TO INSIDE OF REAR ENDBELL.
- 6. INSULATION RESISTANCE: 100 MEGOHMS MIN AT 500 VDC.
- 7. MEASUREMENTS MADE WITH CABLE.
- 8. MEASURED USING AN A.C. INDUCTANCE BRIDGE, AT 1KHz, WITH CABLE.
- 9. AS MEASURED BY THE CHANGE IN RESISTANCE METHOD, WITH RATED CURRENT APPLIED TO 2 PHASES; WITH MOTOR AT REST.
- 10. THIS MOTOR TO BE MANUFACTURED IN COMPLIANCE WITH EU DIRECTIVE "ROHS 2002/95/EC".
- 11. MOTOR LABEL TO INCLUDE "ROHS" COMPLIANT, 'MADE IN (COUNTRY OF ORIGIN)' AND DATE CODE.
- 12. HIGH TORQUE MOTOR DESIGN, MICROSTEP LAMINATION, INTENDED FOR USE WITH 80VDC DRIVES WHEN WINDINGS CONNECTED IN PARALLEL AND WITH 160VDC DRIVES WHEN WINDINGS CONNECTED IN SERIES.
- 13. ENCODER CABLE SOLD SEPARATELY.
- 14. ENCODER P/N 970-1005.

BIPOLAR, FULL STEP, 2 PHASE ON
PARALLEL CONNECTED

SWITCHING SEQUENCE FOR CW ROTATION
FACING MOUNTING END

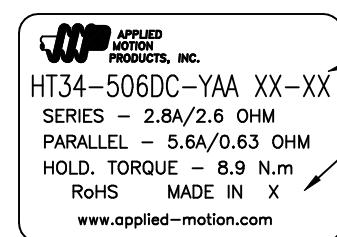
STEP	ORANGE & BLK/WHT	BLACK & ORNG/WHT	RED & YEL/WHT	YELLOW & RED/WHT
0	+	-	+	-
1	-	+	+	-
2	-	+	-	+
3	+	-	-	+
4	+	-	+	-



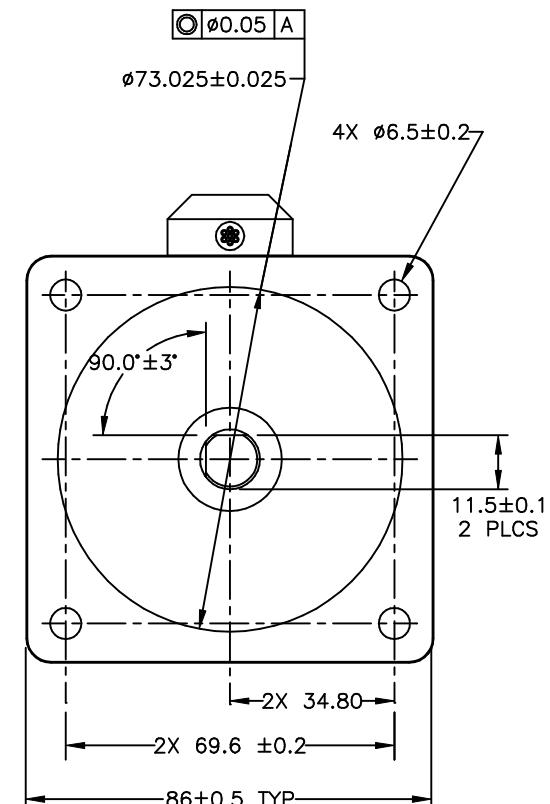
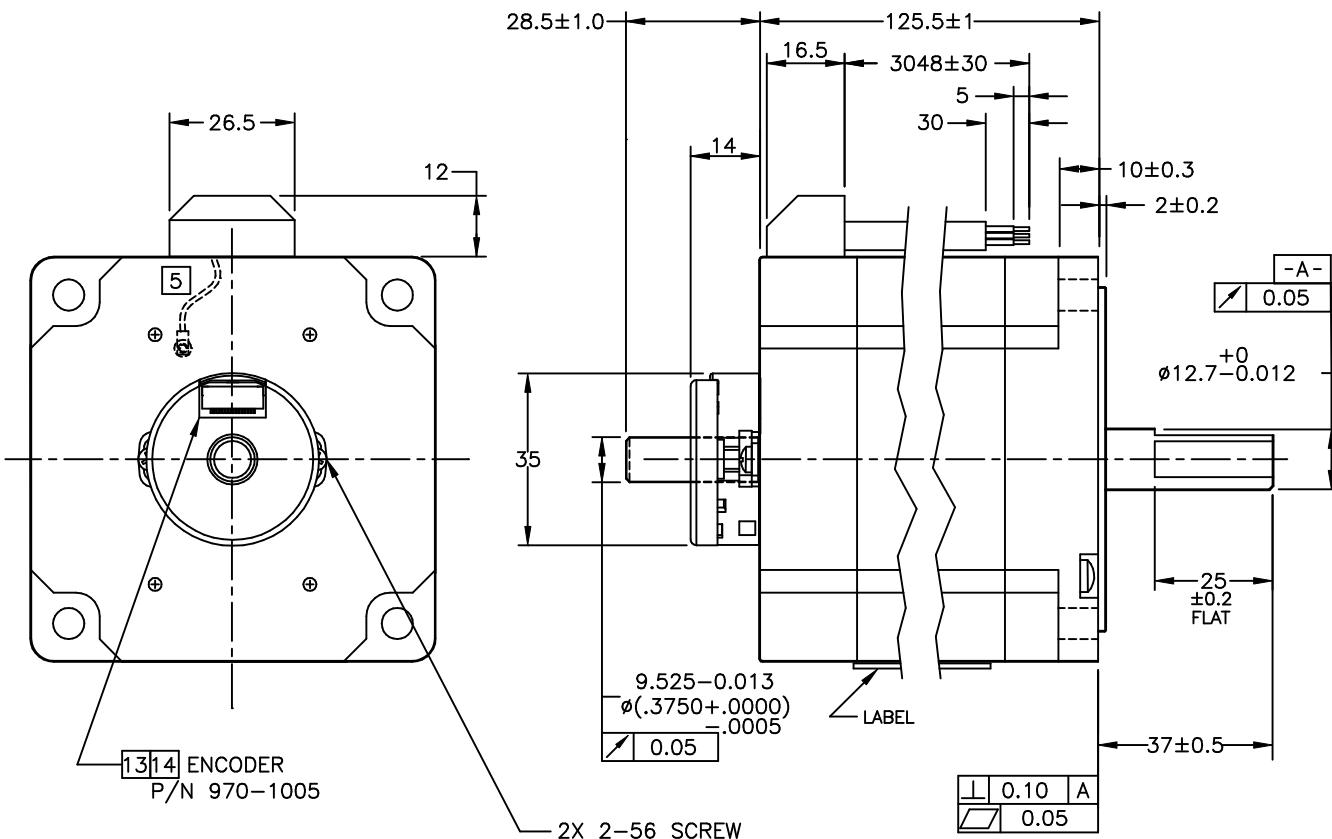
LITERATURE REVIEW

REVISIONS

LABEL DETAIL

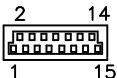


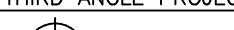
CONTRACT NO. — —		 APPLIED MOTION PRODUCTS, INC.		
APPROVALS DRAWN R.JONEZ	DATE 10/10/13	STEP MOTOR OUTLINE		
CHECKED				
APPROVED		B	COMPUTER DATA BASE DRAWING	DWG NO. HT34-506DC-YAA
APPROVED		SCALE: NONE		SHEET 1 OF 2



ENCODER RESOLUTION: 2000 cpr
WITH MARKER PULSE.

ENCODER PINOUTS	
PIN	SIGNAL
1	CH A
2	CH A-
3	CH B
4	CH B-
5	INDEX
6	INDEX-
7	N/C
8	N/C
9	N/C
10	N/C
11	N/C
12	N/C
13	+Vcc
14	GND
15	N/C



TOLERANCES		THIRD ANGLE PROJECTION		 APPLIED MOTION PRODUCTS, INC.	
DECIMALS: MM (INCH) X.XXX = \pm (.005) X.XX = \pm 0.13 (.010) X.X = \pm 0.25 (.020) ANGLES: MACH. = \pm .5° CHAM. = \pm 5°				STEP MOTOR OUTLINE	
		APPROVALS	DATE		
		DRAWN <i>R.JONEZ</i>	10/10/13	B	DWG NO. HT34-506DC-YAA
		CHECKED		REV	A
COMPUTER DATA BASE DRAWING		APPROVED		SCALE: NONE	SHEET 2 OF 2