

Product data sheet

Specifications



variable speed drive, Altivar Machine ATV340, 18kW, heavy duty, 400V, 3 phases

ATV340D18N4

Main

Range of product	Altivar Machine ATV340
Product or component type	Variable speed drive
Product specific application	Machine
Mounting mode	Cabinet mount
Variant	Standard version
Communication port protocol	Modbus serial
Option card	Communication module, Profibus DP V1 Communication module, PROFINET Communication module, DeviceNet Communication module, CANopen Communication module, EtherCAT
Network number of phases	3 phases
Supply frequency	50...60 Hz +/- 5 %
[Us] rated supply voltage	380...480 V - 15...10 %
nominal output current	39.0 A
Motor power kW	22 kW for normal duty 18.5 kW for heavy duty
Motor power hp	30 hp for normal duty 25 hp for heavy duty
EMC filter	Class C3 EMC filter integrated
IP degree of protection	IP20

Complementary

Discrete input number	5
Discrete input type	PTI programmable as pulse input: 0...30 kHz, 24 V DC (30 V) DI1...DI5 safe torque off, 24 V DC (30 V), impedance: 3.5 kOhm programmable
number of preset speeds	16 preset speeds
Discrete output number	2.0
Discrete output type	Programmable output DQ1, DQ2 30 V DC 100 mA
Analogue input number	2
Analogue input type	A11 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits A11 software-configurable temperature probe or water level sensor A11 software-configurable voltage: 0...10 V DC, impedance: 31.5 kOhm, resolution 12 bits A12 software-configurable voltage: - 10...10 V DC, impedance: 31.5 kOhm, resolution 12 bits

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Analogue output number	1
Analogue output type	Software-configurable voltage AQ1: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1: 0...20 mA impedance 500 Ohm, resolution 10 bits
Relay output number	2
Output voltage	<= power supply voltage
Relay output type	Relay outputs R1A Relay outputs R1C electrical durability 100000 cycles Relay outputs R2A Relay outputs R2C electrical durability 100000 cycles
Maximum switching current	Relay output R1C on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2C on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Minimum switching current	Relay output R1B: 5 mA at 24 V DC Relay output R2C: 5 mA at 24 V DC
Physical interface	2-wire RS 485
Connector type	1 RJ45
Method of access	Slave Modbus RTU
Transmission rate	4.8 kbit/s 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s
Transmission frame	RTU
Number of addresses	1...247
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
4 quadrant operation possible	True
Asynchronous motor control profile	Optimized torque mode Variable torque standard Constant torque standard
Synchronous motor control profile	Reluctance motor Permanent magnet motor
Pollution degree	2 conforming to IEC 61800-5-1
Maximum output frequency	0.599 kHz
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.01...9999 s
Motor slip compensation	Adjustable Automatic whatever the load Can be suppressed Not available in permanent magnet motor law
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	True

Line current	43.4 A at 380 V (normal duty) 35.0 A at 480 V (normal duty) 54.7 A at 380 V (heavy duty) 43.4 A at 480 V (heavy duty)
Line current	54.7 A at 380 V without line choke (heavy duty) 43.4 A at 480 V without line choke (heavy duty) 49.9 A at 380 V with external line choke (normal duty) 40.2 A at 480 V with external line choke (normal duty) 54.5 A at 480 V with external line choke (heavy duty) 43.5 A at 380 V with external line choke (heavy duty)
Maximum input current	54.7 A
Maximum output voltage	480 V
Apparent power	33.4 kVA at 480 V (normal duty) 36.1 kVA at 480 V (heavy duty)
Maximum transient current	50.6 A during 60 s (normal duty) 59 A during 60 s (heavy duty) 62.1 A during 2 s (normal duty) 70 A during 2 s (heavy duty)
Electrical connection	Screw terminal, clamping capacity: 0.2...2.5 mm ² for control Screw terminal, clamping capacity: 10...25 mm ² for line side Screw terminal, clamping capacity: 10...25 mm ² for DC bus Screw terminal, clamping capacity: 6...25 mm ² for motor
Prospective line I_{sc}	22 kA
Base load current at high overload	39.0 A
Base load current at low overload	46.0 A
Power dissipation in W	Natural convection: 21 W at 380 V, switching frequency 4 kHz (heavy duty) Forced convection: 410 W at 380 V, switching frequency 4 kHz (heavy duty) Natural convection: 23 W at 380 V, switching frequency 4 kHz (normal duty) Forced convection: 464 W at 380 V, switching frequency 4 kHz (normal duty)
Electrical connection	Control: screw terminal 0.2...2.5 mm ² /AWG 24...AWG 12 Line side: screw terminal 10...25 mm ² /AWG 8...AWG 3 DC bus: screw terminal 10...25 mm ² /AWG 8...AWG 3 Motor: screw terminal 6...25 mm ² /AWG 8...AWG 3
With safety function Safely Limited Speed (SLS)	True
With safety function Safe brake management (SBC/SBT)	True
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False

Protection type	Thermal protection: motor Safe torque off: motor Motor phase loss: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent: drive Output overcurrent between motor phase and earth: drive Output overcurrent between motor phases: drive Short-circuit between motor phase and earth: drive Short-circuit between motor phases: drive Motor phase loss: drive DC Bus overvoltage: drive Line supply overvoltage: drive Line supply undervoltage: drive Input supply loss: drive Exceeding limit speed: drive Break on the control circuit: drive
Width	180.0 mm
Height	385.0 mm
Depth	249.0 mm
Product weight	10.2 kg
Continuous output current	46 A at 4 kHz for normal duty 39 A at 4 kHz for heavy duty

Environment

Operating altitude	<= 3000 m with current derating above 1000m
Operating position	Vertical +/- 10 degree
Product certifications	UL CSA TÜV EAC CTick
Marking	CE
Standards	IEC 61800-3 IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1 UL 618000-5-1 UL 508C
Assembly style	With heat sink
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	70 m/s² at 22 ms
Maximum acceleration under vibrational stress (during operation)	5 m/s² at 9...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...9 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	128.0 m3/h
Type of cooling	Forced convection
Overvoltage category	Class III

Regulation loop	Adjustable PID regulator
Noise level	56.7 dB
Pollution degree	2
Ambient air transport temperature	-40...70 °C
Ambient air temperature for operation	-15...50 °C without derating (vertical position) 50...60 °C with derating factor (vertical position)
Ambient air temperature for storage	-40...70 °C
Isolation	Between power and control terminals

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	34.000 cm
Package 1 Width	30.500 cm
Package 1 Length	56.000 cm
Package 1 Weight	11.900 kg
Unit Type of Package 2	P06
Number of Units in Package 2	2
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	36.800 kg

Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)

Environmental footprint	
Total lifecycle Carbon footprint	13080
Environmental Disclosure	Product Environmental Profile

Use Better

Materials and Substances	
Packaging made with recycled cardboard	Yes
Packaging without single use plastic	No
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)
SCIP Number	B464d3d8-3d68-42fb-96c3-c1eaf1b135e1
REACH Regulation	REACH Declaration
California proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov

Energy efficiency	
Product contributes to saved and avoided emissions	Yes

Use Again

Repack and remanufacture	
End of life manual availability	End of Life Information
Take-back	No
WEEE Label	 The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

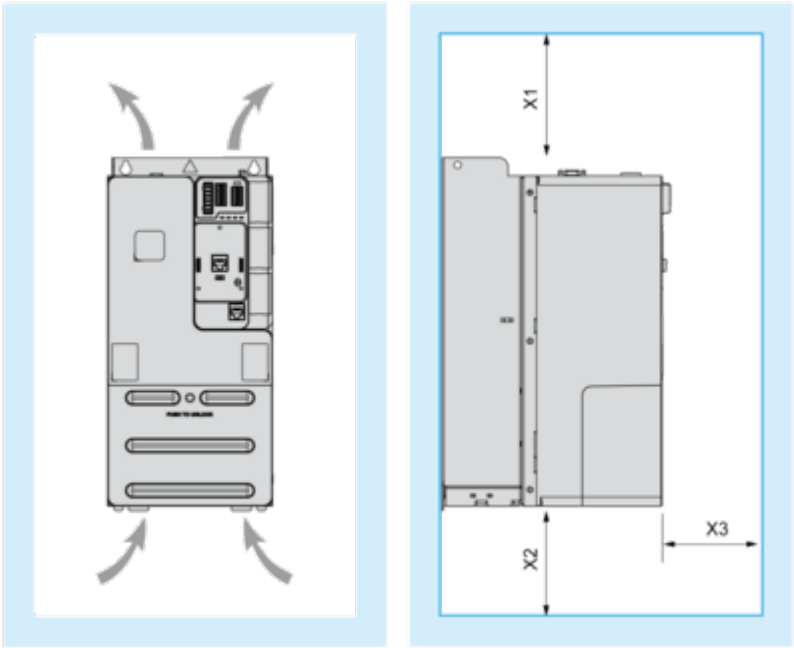
Dimensions Drawings

Dimensions

Views: Front - Left - Rear

Mounting and Clearance

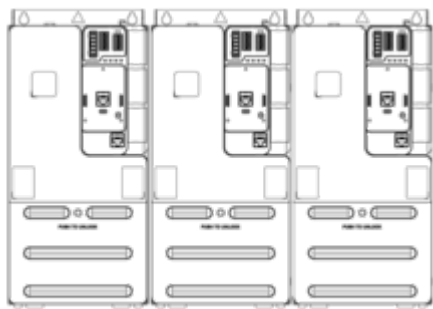
Clearance



X1	X2	X3			
mm	in.	mm	in.	mm	in.
≥ 100	≥ 3.94	≥ 100	≥ 3.94	≥ 60	≥ 2.36

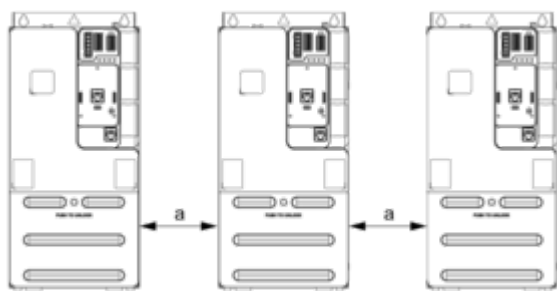
Mounting Types

Mounting Type A: Side by Side IP20



Possible, at ambient temperature $\leq 50\text{ }^{\circ}\text{C}$ (122 $^{\circ}\text{F}$)

Mounting Type B: Individual IP20

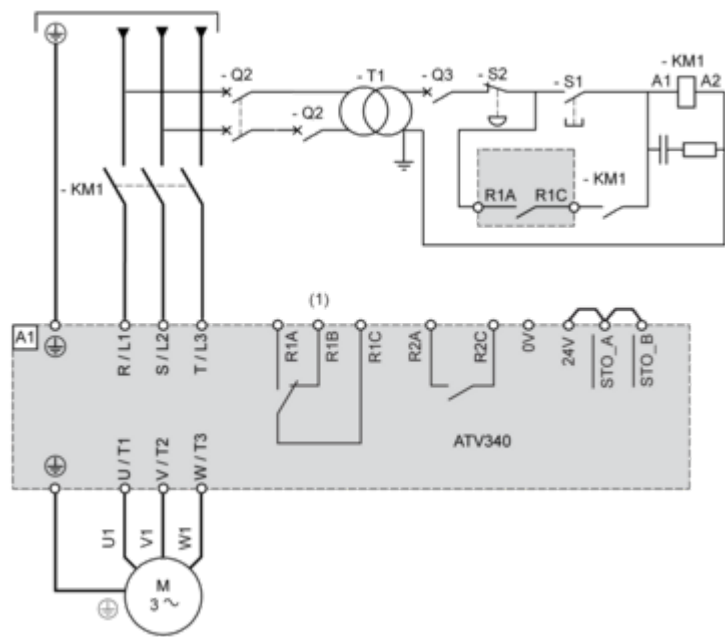


$a \geq 50\text{ mm}$ (1.97 in.) from 50...60 $^{\circ}\text{C}$, no restriction below 50 $^{\circ}\text{C}$

Connections and Schema

Connections and Schema

Three-phase Power Supply - Diagram With Line Contactor

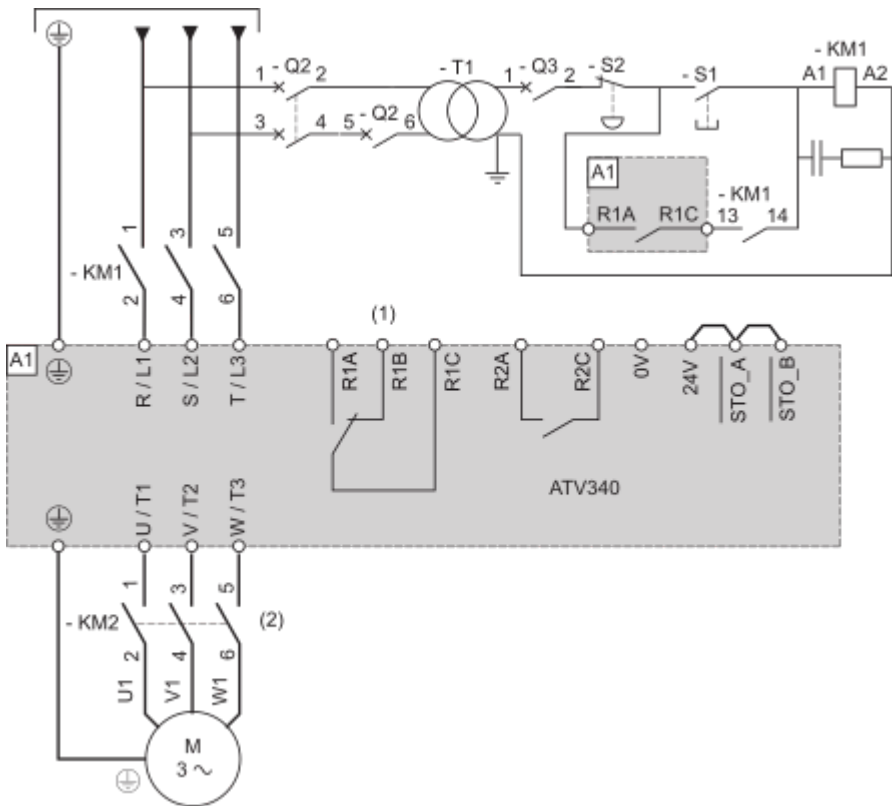


(1) : Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

NOTE :

- Press S1 until the initialization of the drive is finished.
- An external 24V power supply can be connected so that the control part of the drive is always power supplied.

Three-phase Power Supply - Diagram With Downstream Contactor

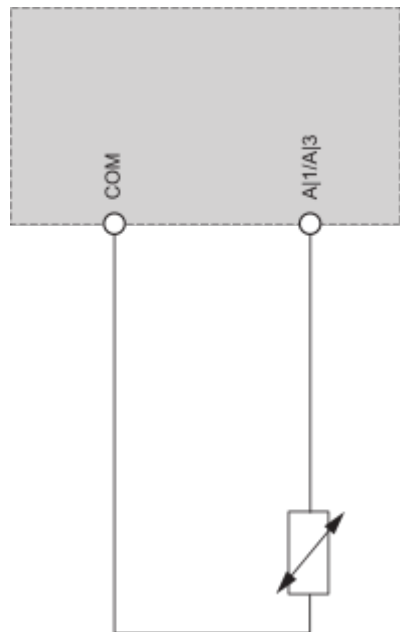


- (1) : Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
- (2) : Command of KM2 can be done by using the **[Output contactor cmd]** OCC function. For more information, refer to the programming manual.

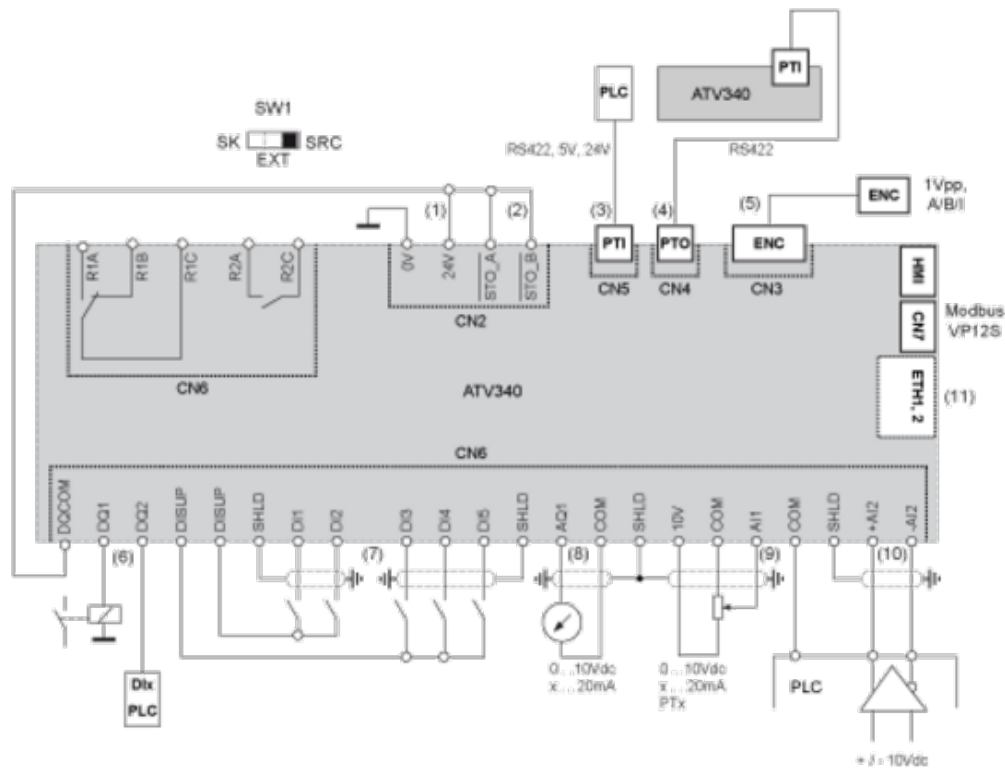
NOTE :

- Close upstream contactor, then press S1 after the initialization of the drive is finished.
- An external 24V power supply can be connected so that the control part of the drive is always power supplied.

Sensor Connection



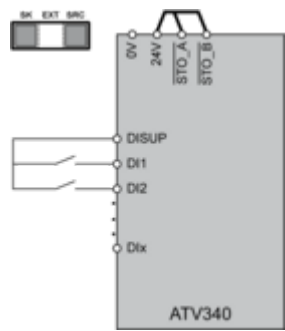
Control Block Wiring Diagram



- (1) : 24V In, Out, maximum supply current 200 mA is provided,
- (2) : STO - Safe Torque Off, see ATV340 Embedded safety function manual NVE64143
- (3) : PTI - Pulse Train In, from external source (eg.PLC) Pulse - Direction or A-B signals can be connected
- (4) : PTO - Pulse Train Out, can be used to connect to a 2nd ATV340 PTI
- (5) : To connect a motor position feedback encoder
- (6) : Digital output, e.g. to connect a contactor, also usable as DI
- (7) : Digital inputs
- (8) : Analog output, e.g. to connect a meter
- (9) : Analog input, e.g. from potentiometer
- (10) : Differential analog input, e.g. as speed reference from external PLC differential, +/- 10 V
- (11) : 2 advanced Ethernet ports ETH1, ETH2 (ATV340.....E) or 2 Sercos III ports S3P1, S3P2 (ATV340.....S)

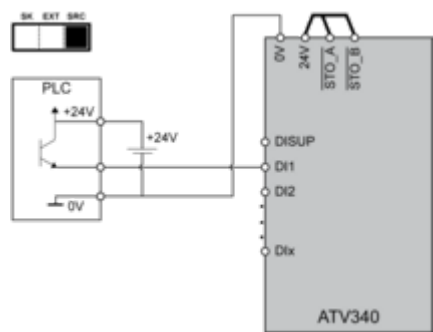
Digital Inputs Wiring

Digital Inputs: Internal Supply
Using DISUP Signal

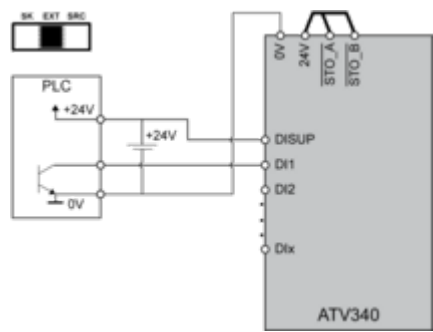


In SRC position DISUP outputs 24 V. In SK position DISUP is connected to 0 V.

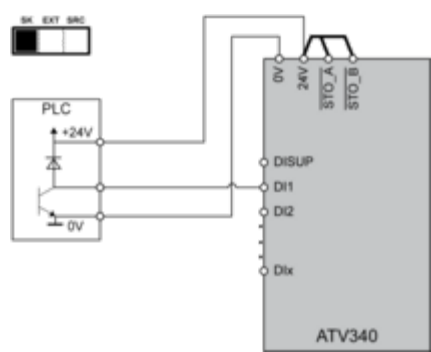
Digital Inputs: External Supply
Positive Logic, Source, European Style



Negative Logic, Sink, Asian Style



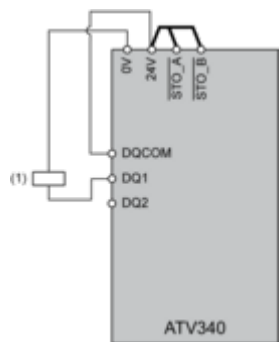
Digital Inputs: Internal supply
Negative Logic, Sink, Asian Style



Digital Outputs Wiring

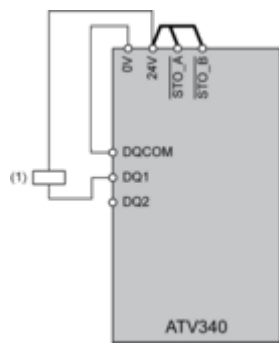
Digital Outputs: Internal Supply

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

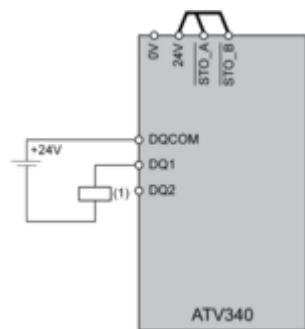
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

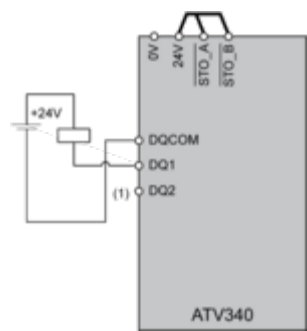
Digital Outputs: External Supply

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

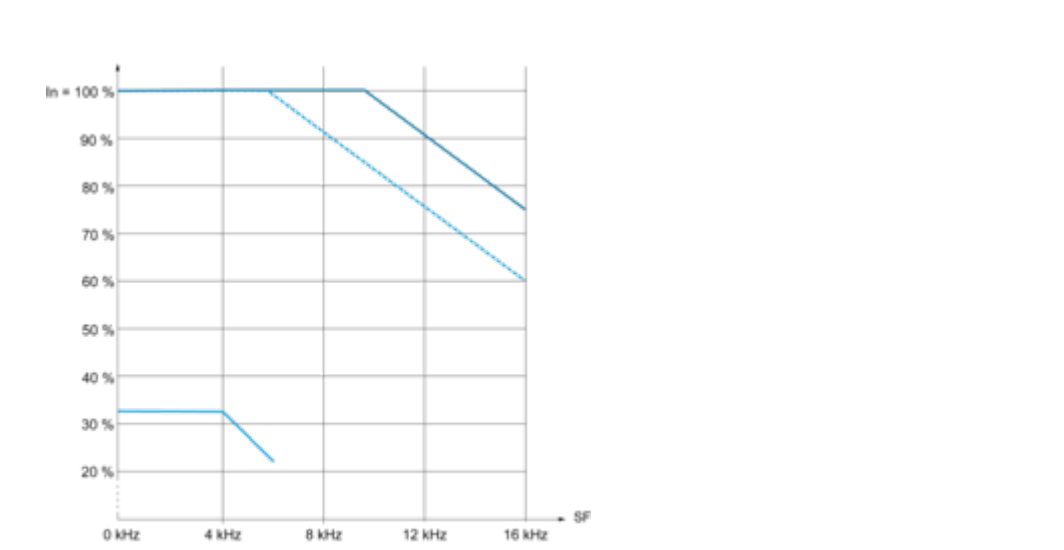
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

Performance Curves

Derating Curves



- 40 °C (104 °F) - Mounting type A and B
 - 50 °C (122 °F) - Mounting type B
 - 60 °C (140 °F) - Mounting type B
- In : Nominal Drive Current
SF : Switching Frequency

Technical Illustration

Dimensions

