Modbus 4in1 Sensor Datasheet

1 Introduction

The Modbus 4in1 Sensor consists of 4 sensors in a compact low-profile design. Temperature, humidity, Passive Infra-Red (PIR) based motion detection and ambient light measurement sensors are incorporated in this multi-sensor device. The device can be flush mounted on ceilings or swivel mounted on walls.

1.1 Features

- 3 levels of motion sensitivity with customizable motion re-trigger interval and wide angle of motion detection
- Measures temperature up to 70°C with accuracy of ±0.2°C
- Measures humidity from 0 to 95% with accuracy of ±2%RH
- Measures ambient light up to 64K Lux
- Implements the Modbus RTU protocol
- Low power consumption 5V, 180mW
- Operating temperature range: 0°C to +70°C
- Swivel mount and Flush mount options

2 Part Numbers / Ordering Information

Part Number	Description
MS-0101-01A	Modbus 4in1 Sensor (Motion, Temperature, Humidity & Brightness)
MA-0101-01A	Modbus RS485-JST Cable (30cm)
MA-0104-01A	Modbus RS485 Termination
LA-1701-01A	LDSBus Sensor Swivel Mount Set

Table 1 - Part Numbers / Ordering Information

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3 Specifications

Features	Sensors	PIR Sensor
		Ambient Light Sensor
		Temperature Sensor
		Humidity Sensor
	Interface	RS485 Modbus RTU
	LED Indicator (RGB)	System Status Indicator (Please refer to LED section)
	Mounting	Flush Mount - Fixed Angle Installation
		Swivel Mount – Adjustable Angle Installation (requires LDSBus Sensor Swivel Mount Set)
Power	Modbus Voltage	9-24V DC Bus Power
	Device Input Voltage	5V DC
	Typical Power	180mW
	Max Power	350mW
PIR Sensor	Detection Range (Swivel)	≤7 Meters (3 configurable motion sensitivity settings 3m, 5m, 7m)
	Max Install Height (Flush)	3 Meters
	Motion Detection FOV	102.6 Degrees
	Motion Re-trigger Interval	0-32 Seconds (Configurable time lapse for motion to be reported again)
Ambient Light Sensor	Range	0 to 64000 Lux
Temperature Sensor	Range	0°C to 70°C (32°F to 158°F)
	Accuracy	±0.2°C (±32.36°F)
	Resolution	0.1°C
Humidity Sensor	Range	0 to 95% RH
	Accuracy	±2% RH
Physical Characteristics	Color	White
	Housing	Polycarbonate
	Dimensions	Φ62mm x H25mm (Flush) or Φ62mm x H60mm (Swivel)
Environmental Limits	Operating Temperature	0 to 70°C
	Storage Temperature	-20 to 85°C
	Ambient Relative Humidity	5 to 95% (non-condensing)
Package Contents	Device	1X Modbus 4in1 Sensor with Flush Mount
	Wire Assembly	1X Modbus RS485-JST Cable(30cm)
	RS485 Termination	1x Modbus RS485 Termination
	Self-Tapping Screws	2X M3*16mm (Thread)
Optional	Mounting Accessories	1x Swivel mount bracket

Table 2 - Modbus 4in1 Sensor Specifications

4 FCC Compliance Statement

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) These devices may not cause harmful interference, and

(2) These devices must accept any interference received, including interference that may cause undesired operation.

NOTE: The equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If the equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Re-orient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

To maintain compliance with FCC's RF exposure guidelines, at least 20cm of separation distance between the device and the user's body must be always maintained.

FCC Radiation Exposure Statement

This device complies with FCC radiation exposure limits set forth for an uncontrolled environment and it also complies with Part 15 of the FCC RF Rules. This equipment must be installed and operated in accordance with the instructions provided, and the antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter. End-users and installers must be provided with antenna installation instructions and consider removing the no-collocation statement.

Caution

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

5 Hardware Features

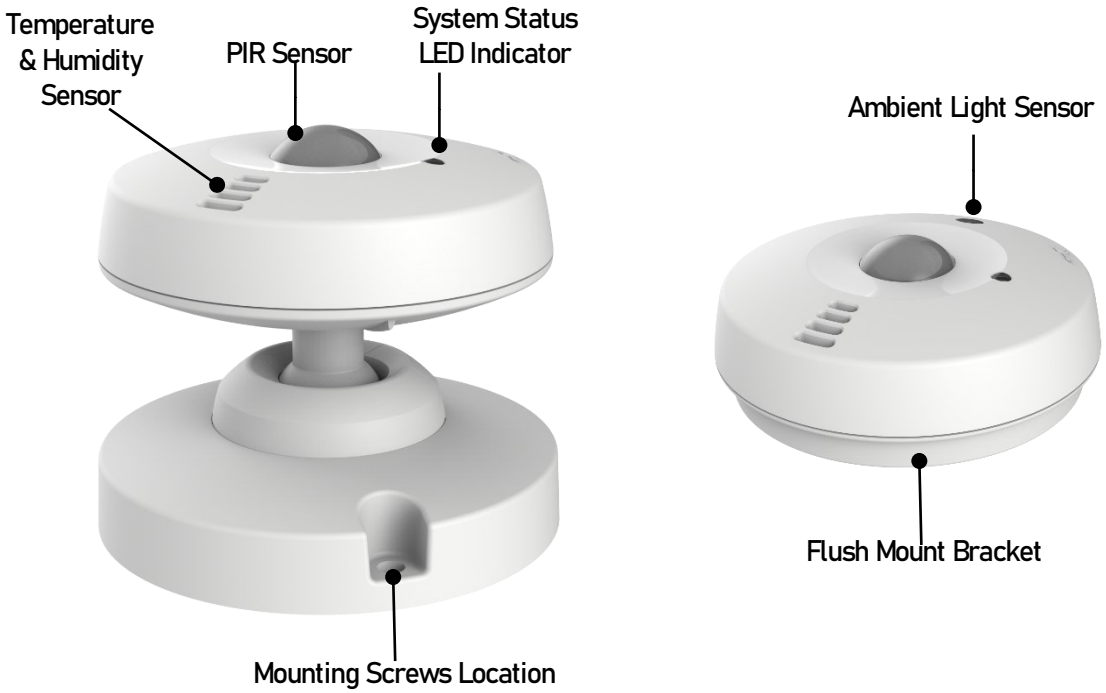


Figure 1 - Modbus 4in1 Sensor Hardware Features

Label	Description
Temperature & Humidity Sensor	Measure temperature and humidity
PIR Sensor	Detect motion
Ambient Light Sensor	Measure the light brightness (lux)
System Status LED Indicator	Modbus status LED. Refer to section 11 for more details

Table 3 - Hardware Labels & Description

6 PIR Sensor Detection Range

6.1 Flush Mount

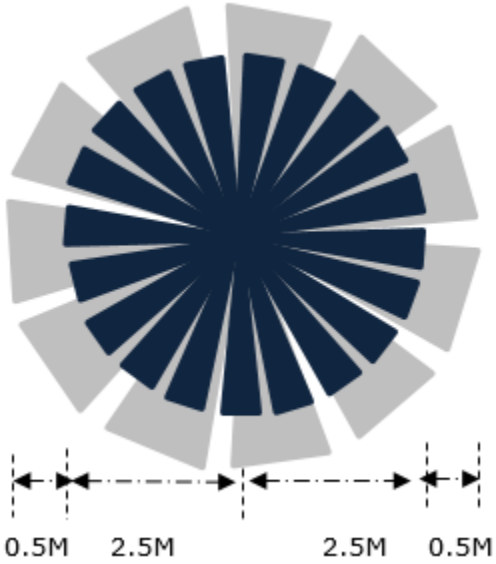


Figure 2 - Modbus 4in1 Sensor - Flush Mount – Top View Projection

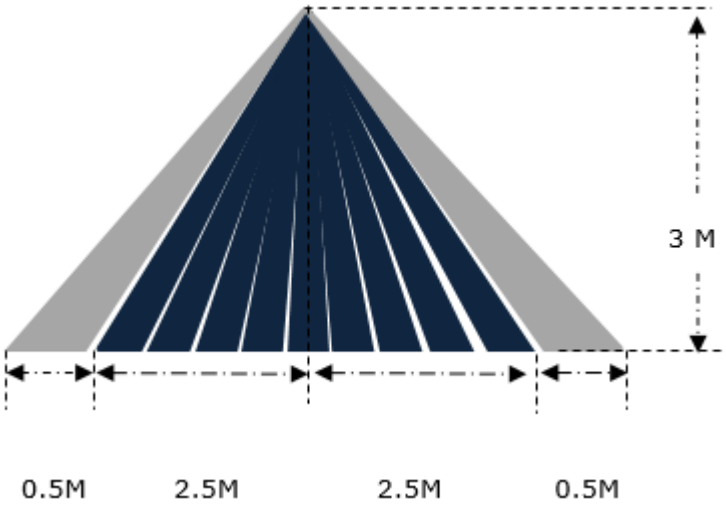


Figure 3 - Modbus 4in1 Sensor - Flush Mount - Side View Projection

Major Motion **Minor Motion**

6.2 Swivel Mount

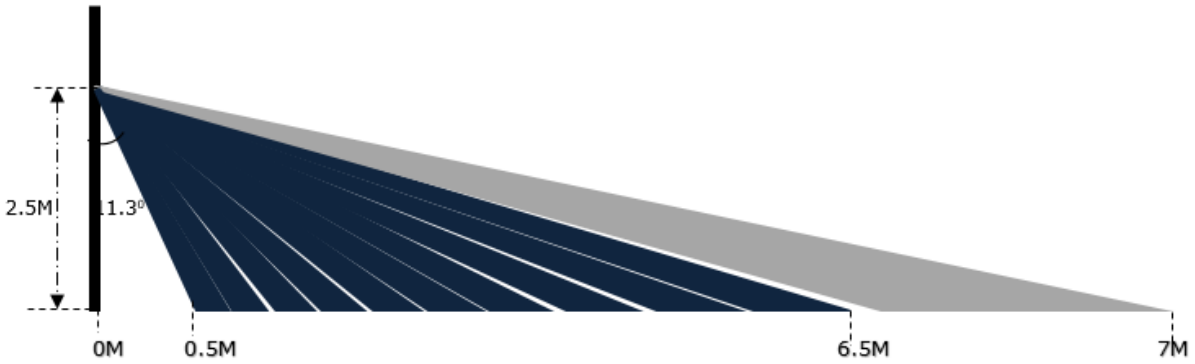


Figure 4 - Modbus 4in1 Sensor - Swivel Mount - Side View Projection

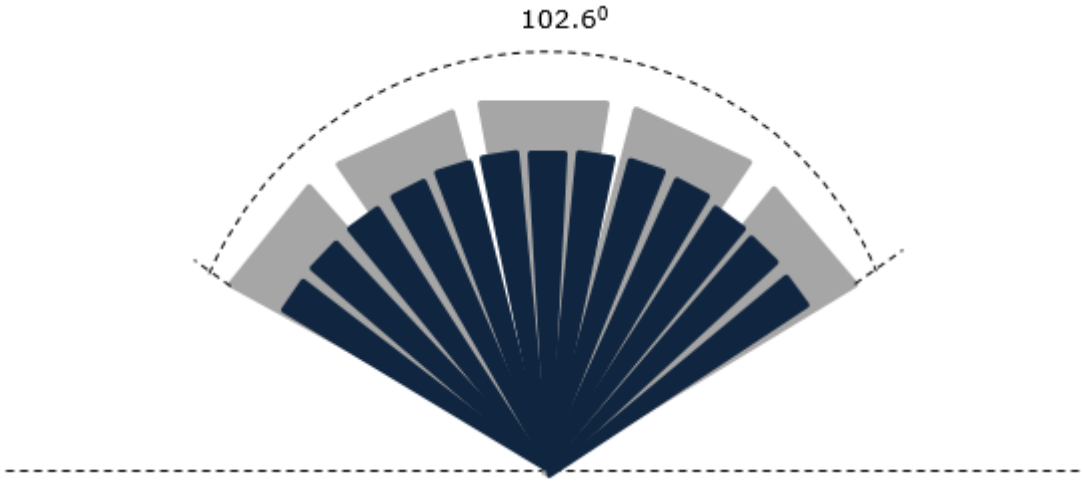


Figure 5 - Modbus 4in1 Sensor - Swivel Mount - Top View Projection

Major Motion **Minor Motion**

Recommendation:

To avoid false motion detection, it is recommended to install the device away from direct light sources and heat generating equipment.

7 Sensor Configuration and Installation

Please visit Software (Utility Tools) - BRT Systems Pte Ltd → Application Note/User Guide > Modbus Configuration Utility User Guide to access the Modbus Configuration Utility guide on how to configure the device name, device address and termination settings before using it for your specific application.

7.1 Connection Diagram for Standard Modbus Power Supply

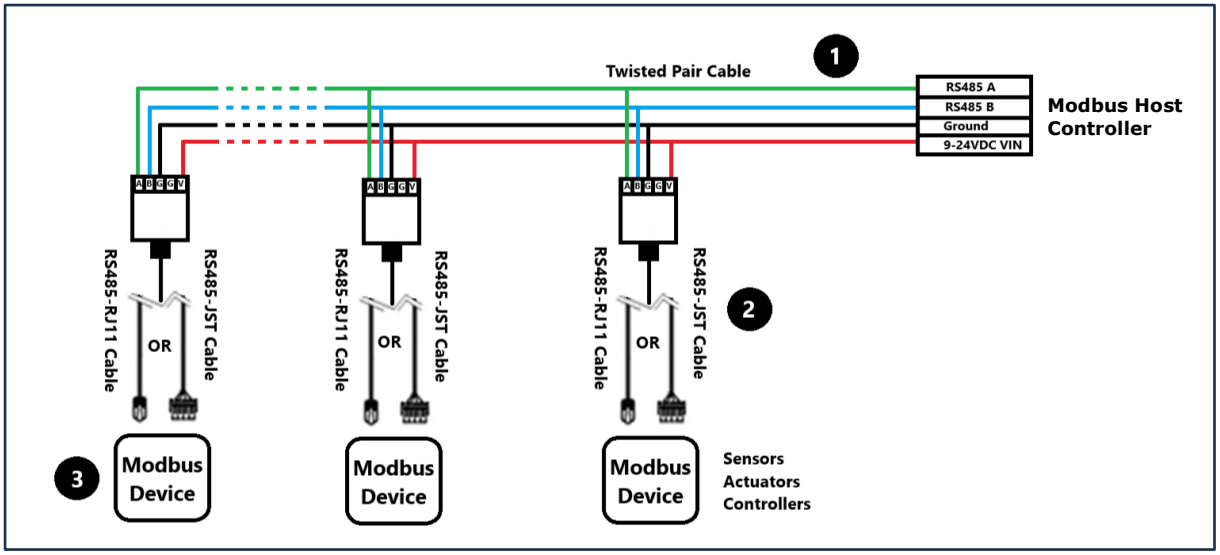


Figure 6 - Connection Diagram for Standard Modbus Power Supply

Setup Instructions:

1. Use a Cat5e/Cat6e RJ45 Twisted Pair Cable to connect the Modbus controller (Host) to the network for RS485 communication and power.

2. Connect each Modbus device to the network using either an RS485-JST cable or an RS485-RJ11 cable, as provided with the device.

3. For the Modbus 4-in-1 sensor, we recommend using the external RS485 termination (MA-0104-01A) provided in the packaging. Connect it between the A and B data lines at the RS485-JST cable terminal block of the last device on the Modbus line, which can be either the 4-in-1 sensor itself or another Modbus device.

   Note that the internal termination should be left in the default state of OFF when using the external RS485 termination (MA-0104-01A).

7.2 RS485-JST Cable(30cm)

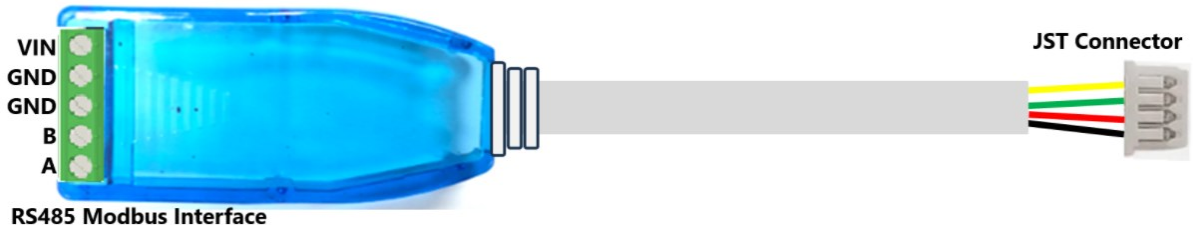


Figure 7 - RS485-JST Cable (30cm)

PIN Legend	Function
VIN	Modbus Input Voltage 9-24VDC
GND	Ground
GND	Ground
B	RS485-B
A	RS485-A

Table 4 - RS485-JST Cable (30cm) Pin Configuration

7.3 RS485 Termination

RS485 termination can be connected across the A and B data lines without regard to polarity and should be added only at the end of the bus.

8 Mounting Instructions

The flush mount is the default sensor setup included in the package. Use the mounting instructions in section 8.1 for the flush mount method.

The swivel mount is an optional setup that requires purchasing the swivel mount bracket. Follow the mounting instructions in section 8.2 for the swivel mount method.

Make sure the device has been configured using the Modbus Configuration Utility before mounting.

8.1 Flush Mount

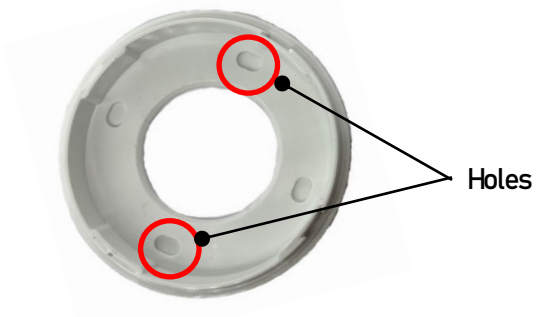
The flush mounting procedure assumes a flat hollow surface behind which the RS485-JST cable is concealed and made accessible through an opening. Figure 8 shows the front face of the Modbus 4in1 Sensor device. Note the lock/unlock direction on the cover.

Figure 8 - Modbus 4in1 Sensor

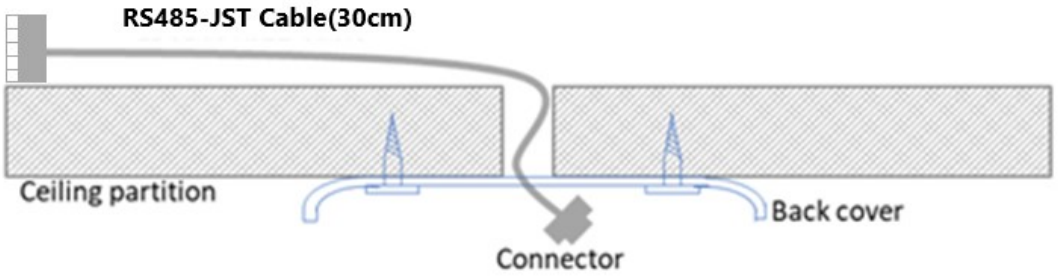
Follow these steps to fix the flush mount –

1. Unlock the back cover. Twist the top cover in the anticlockwise direction to unlock.

2. Make two holes in the back cover using the indentations as guides.

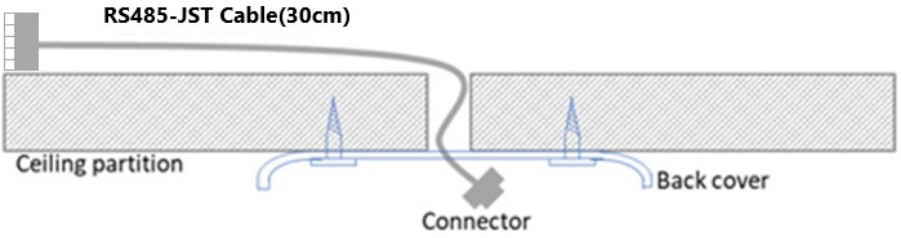


3. Prepare the ceiling and route the RS485-JST cable through the ceiling opening. Run the RS485-JST cable through the centre (hole) of the back cover and fasten the back cover to the ceiling with self-tapping screws as shown in the picture below –



4. Attach the cable to the JST connector of the sensor.

5. Twist lock the front face, in a clockwise direction, to attach it to the back cover.



8.2 Swivel Mount

The swivel mount is shown in Figure 9.

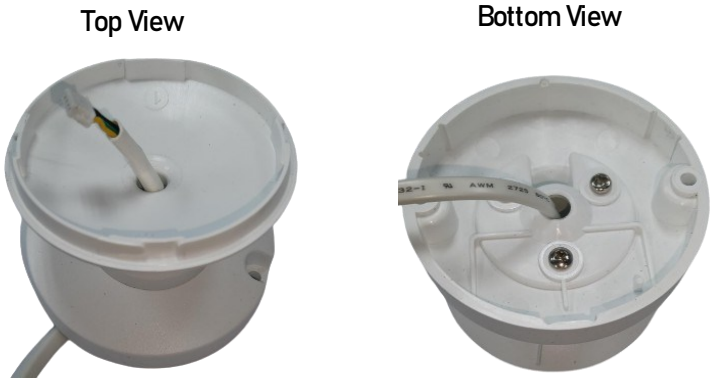


Figure 9 - Modbus 4in1 Sensor - Swivel Mount – Top & Bottom View

Angle of Rotation:

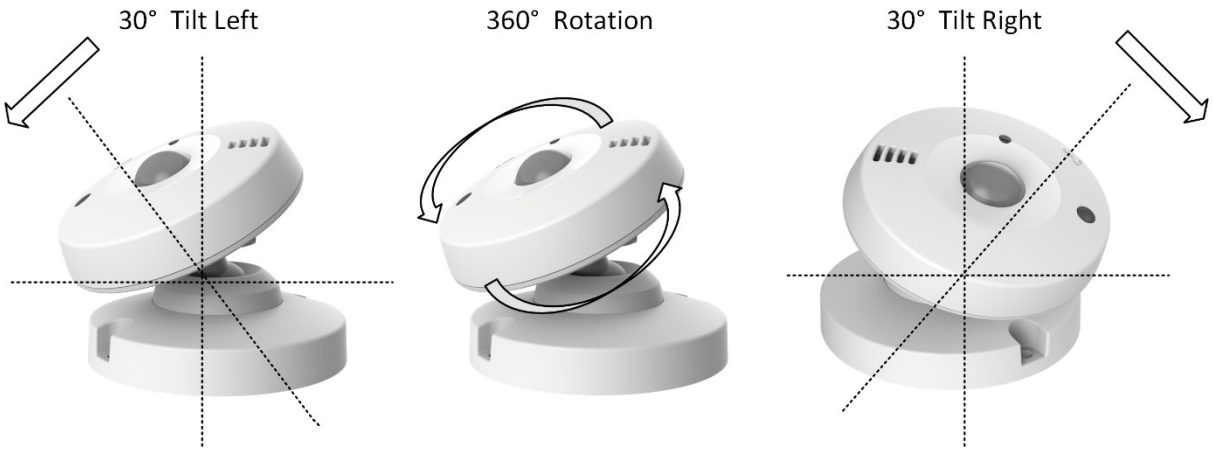
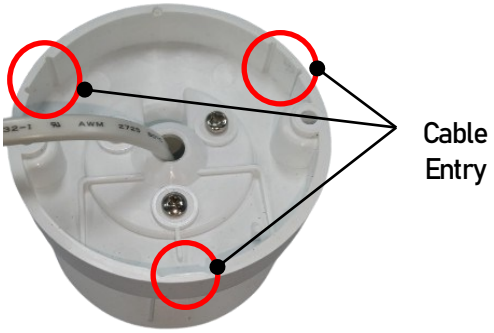


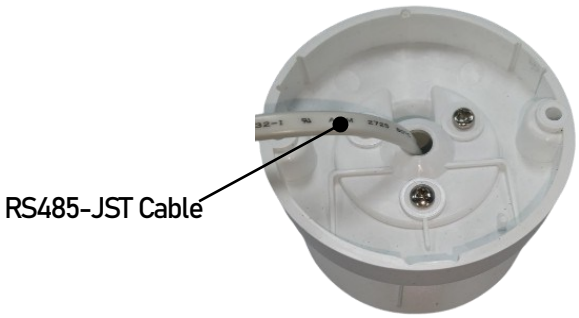
Figure 10 - Modbus 4in1 Sensor – Swivel Mount – Angle of Rotation

Follow these steps to fix the swivel mount –

1. Choose the position for the wall mount and drill holes for mounting the swivel mount on the wall.
2. Route and affix the RS485-JST cable on the wall through a buried or wall mounted conduit to butt against the base of the swivel mount.
3. Break off one of the three cable entry locations on the base plate for cable routing.



4. Push through the RS485-JST cable in the bottom hole (Swivel Mount bottom section) as shown in the picture below.



5. Fasten the swivel mount to the wall using the mounting screws. Ensure that the cable is sitting in the cable entry slot.

6. Unlock the back cover. Twist the top cover in the anticlockwise direction to unlock.

7. Connect the JST cable from the top section of the swivel mount to the JST connector located on the back of the device.

8. Attach the device to the top section of the swivel mount.

9. Turn the device clockwise to secure it to the swivel mount.

9 Modbus Registers

Parameter	Starting Address	Quantity of Registers	Supported Function Code	Parameter Range and Description	Default
Address(1)	0000H	1	0x03/0x10	1 to 126	126
RS485 Termination(1)	0001H	1	0x03/0x10	0 - Termination OFF 1 - Termination ON	Termination OFF
Baud Rate(1)	0002H	1	0x03/0x10	*0 to 2 - Reserved* 3 - 9600 bps 4 - 19200 bps 5 - 38400 bps 6 -115200 bps	9600 bps
Parity(1)	0003H	1	0x03/0x10	0 – None 1 – Odd 2 – Even	Even
Status LED Enable(1)	0004H	1	0x03/0x10	0 - LED OFF 1 - LED ON	LED ON
PIR Sensitivity	0005H	1	0x03/0x10	Configures motion detection sensitivity 0x00 – 3 Meters 0x01 – 5 Meters 0x02 – 7 Meters **Note:** When an invalid value is set by the host, the device ignores it and retains its previous settings.	7 Meters
Motion Detection Hold Duration	0006H	1	0x03/0x10	Sets the duration for holding motion detection state, 1 – 31 Seconds	5 Seconds
Device UUID	0026H	8	0x03	MSxxxxxxxxxxxxyy where x is ASCII character and yy is 16-bit running number	N/A
Device Firmware Version	002EH	1	0x03	0xXXMN XX – Not concerned M – Major N - Minor	N/A
Device Part Number	002FH	1	0x03	Device ID	0x8000
Reserved	0030H				
Motion	0031H	1	0x03	0 - 1	N/A
Temperature	0032H	1	0x03	0 to 7000 (0°C to 70°C)	N/A
Humidity	0033H	1	0x03	0 to 9999 (0% to 99.99%)	N/A
Luminance	0034H	1	0x03	0 to 65535 lux	N/A
Reset	0150H	1	0x06	Write 1 to reset	N/A
Reserved	0151H	N/A	N/A	Reserved	N/A
Identify	0152H	1	0x06	Write 1 to start blinking the device @1Hz for 10 seconds	N/A

Table 5 - Modbus Registers

(1)This indicates that any updates to these communication/status register(s) will only take effect after the device has been rebooted.

10 Mechanical Dimensions

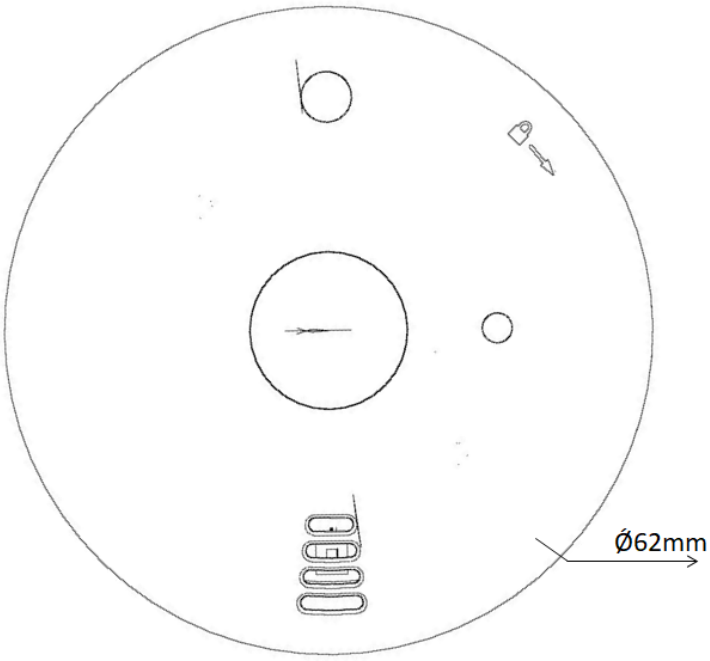


Figure 11 - Modbus 4in1 Sensor Dimension – Top View

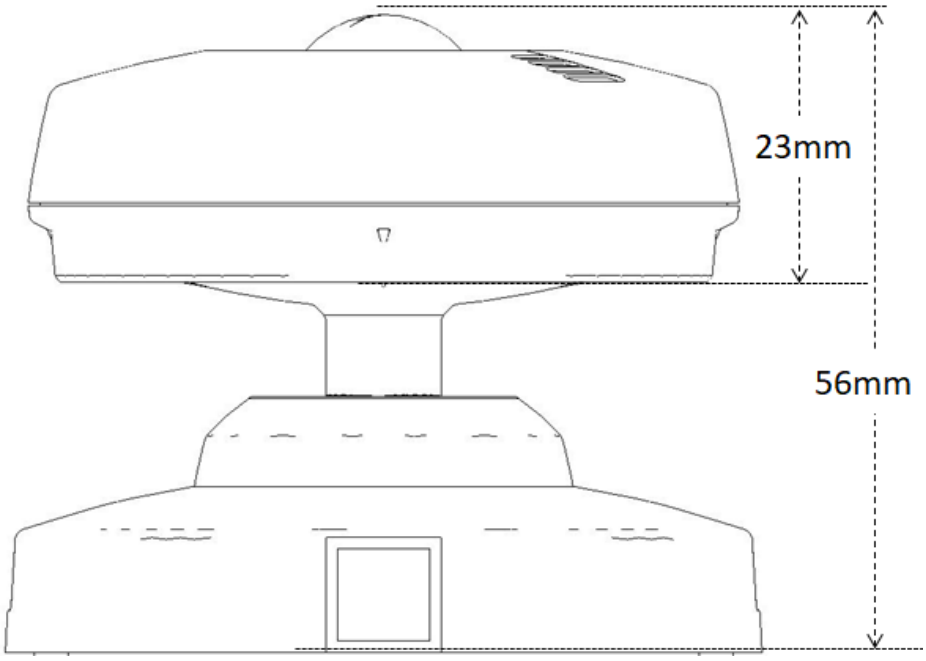


Figure 12 - Modbus 4in1 Sensor Dimension – Side View

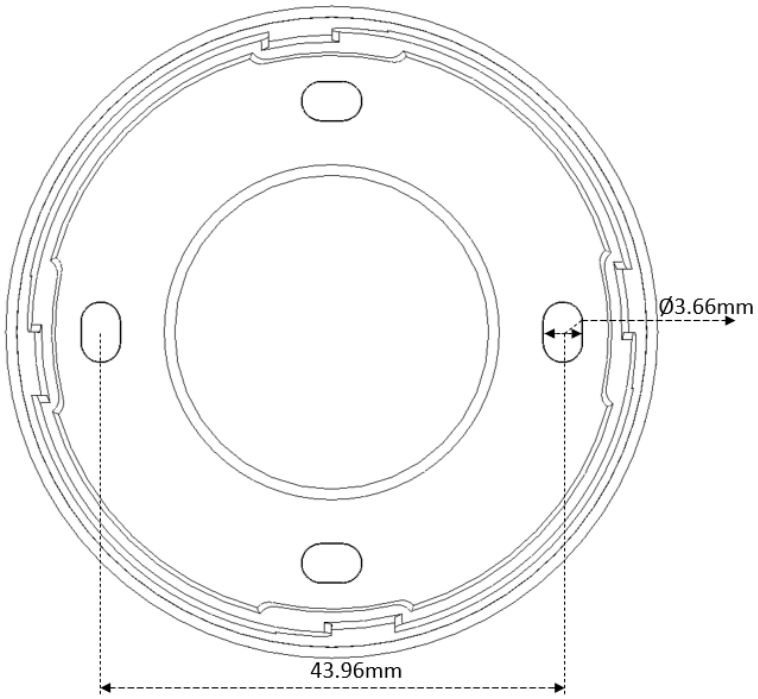


Figure 13 - Modbus 4in1 Sensor Mounting Holes – Flush Mount

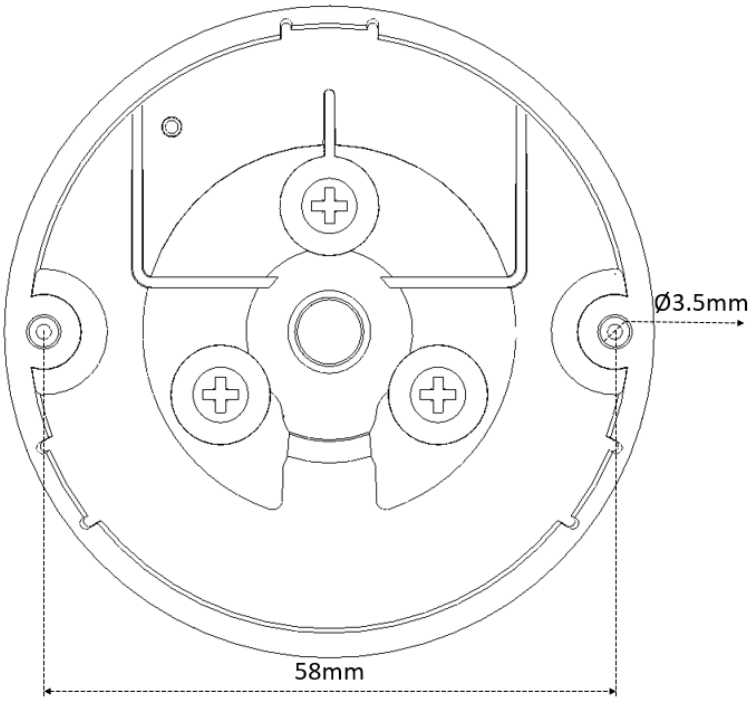


Figure 14 - Modbus 4in1 Sensor Mounting Holes – Swivel Mount

Note: All dimensions are in millimeters.

11 System Status LED Indicators

Device Status	LED Color		Flashing Frequency	Description
Termination ON	BLUE		Steady – Non-flashing	
Termination OFF	GREEN		Steady – Non-flashing	
Motion Detection*	RED		Steady – Non-flashing	
Device Configuration Error	RED		Steady – Non-flashing	Device configuration error
Communication	RED/GREEN/ BLUE/YELLOW	-	Blink twice (Short blink)	Device in communication
Firmware update	YELLOW		Steady – Non-flashing	Device firmware update.

Table 6 - System Status LED Indicators

*When motion is detected, the Status LED turns **red** and stays **steady** for the configured **Motion Detection Hold Duration (1–31 seconds)**. After this duration, the LED reverts to its **normal state** (green or blue). The LED behaviour repeats with each new motion detection event. In the event of a device error, the LED will remain **steadily red** without blinking.

Note:

1. For reliable communication, ensure that the power supply and the RS485 termination settings are correct.
2. Ensure that the Modbus address and baud rate are configured correctly before deployment.

12 Contact Information

Refer to https://brtchip.com/contact-us/ for contact information.

Distributor and Sales Representatives

Please visit the Distribution Network – IC & Module (brtchip.com) page for the contact details of our distributor(s) and sales representative(s) in your country.

Appendix A – References

Document References

Software (Utility Tools) - BRT Systems Pte Ltd → Application Note/User Guide > Modbus Configuration Utility User Guide

Software (Utility Tools) - BRT Systems Pte Ltd → Application Note/User Guide > Modbus Device Configuration

Acronyms and Abbreviations

Terms	Description
DC	Direct Current
LED	Light Emitting Diode
PIR	Passive infrared sensor
FOV	Field of view
UUID	Universally Unique Identifier
RH	Relative Humidity

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Appendix C – Revision History

Document Title: Modbus 4in1 Sensor Datasheet

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Document Feedback: Send Feedback

Revision	Changes	Date
Version 1.0	Initial release under Bridgetek	16-10-2025