

Dual 2-A High-Speed, Low-Side Gate Drivers

FAN3216 / FAN3217

The FAN3216 and FAN3217 dual 2 A gate drivers are designed to drive N-channel enhancement-mode MOSFETs in low-side switching applications by providing high peak current pulses during the short switching intervals. They are both available with TTL input thresholds. Internal circuitry provides an under-voltage lockout function by holding the output LOW until the supply voltage is within the operating range. In addition, the drivers feature matched internal propagation delays between A and B channels for applications requiring dual gate drives with critical timing, such as synchronous rectifiers. This also enables connecting two drivers in parallel to effectively double the current capability driving a single MOSFET.

The FAN3216/17 drivers incorporate MillerDrive™ architecture for the final output stage. This bipolar-MOSFET combination provides high current during the Miller plateau stage of the MOSFET turn-on / turn-off process to minimize switching loss, while providing rail-to-rail voltage swing and reverse current capability.

The FAN3216 offers two inverting drivers and the FAN3217 offers two non-inverting drivers. Both are offered in a standard 8-pin SOIC package.

Features

- Industry-Standard Pinouts
- 4.5 V to 18 V Operating Range
- 3 A Peak Sink/Source at $V_{DD} = 12\text{ V}$
- 2.4 A Sink / 1.6 A Source at $V_{OUT} = 6\text{ V}$
- Inverting Configuration (FAN3216) and Non-Inverting Configuration (FAN3217)
- Internal Resistors Turn Driver Off If No Inputs
- 12 ns / 9 ns Typical Rise/Fall Times (1 nF Load)
- 20 ns Typical Propagation Delay Matched within 1 ns to the Other Channel
- TTL Input Thresholds
- MillerDrive™ Technology
- Double Current Capability by Paralleling Channels
- Standard SOIC-8 Package
- Rated from -40°C to $+125^{\circ}\text{C}$ Ambient
- These are Pb-Free Devices

Applications

- Switch-Mode Power Supplies
- High-Efficiency MOSFET Switching
- Synchronous Rectifier Circuits
- DC-to-DC Converters
- Motor Control



SOIC8
CASE 751EB

PACKAGE OUTLINE

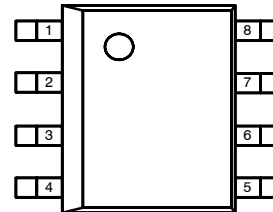
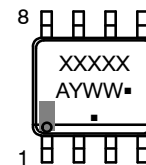


Figure 1. SOIC-8 (Top View)

MARKING DIAGRAM



SOIC8

A	= Assembly Lot Code
L	= Wafer Lot
Y	= Year
W	= Work Week
■	= Pb-Free Package

(Note: Microdot may be in either location)

*This information is generic. Please refer to device data sheet for actual part marking.
Pb-Free indicator, "G" or microdot "■", may or may not be present.

ORDERING INFORMATION

See detailed ordering and shipping information on page 14 of this data sheet.

FAN3216 / FAN3217

PIN CONFIGURATIONS

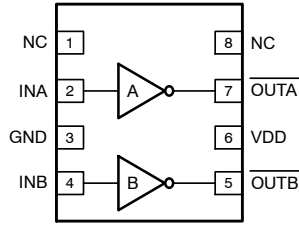


Figure 2. FAN3216 Pin Configuration

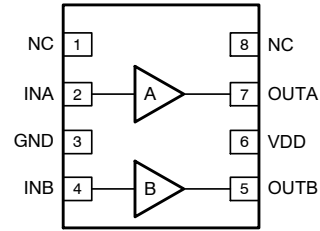


Figure 3. FAN3217 Pin Configuration

THERMAL CHARACTERISTICS (Note 1)

Package	θ_{JL} (Note 2)	θ_{JT} (Note 3)	θ_{JA} (Note 4)	Ψ_{JB} (Note 5)	Ψ_{JT} (Note 6)	Unit
8-Pin Small Outline Integrated Circuit (SOIC)	40	31	89	43	3.0	°C/W

- Estimates derived from thermal simulation; actual values depend on the application.
- θ_{JL} (θ_{JL}): Thermal resistance between the semiconductor junction and the bottom surface of all the leads (including any thermal pad) that are typically soldered to a PCB.
- θ_{JT} (θ_{JT}): Thermal resistance between the semiconductor junction and the top surface of the package, assuming it is held at a uniform temperature by a top-side heatsink.
- θ_{JA} (θ_{JA}): Thermal resistance between junction and ambient, dependent on the PCB design, heat sinking, and airflow. The value given is for natural convection with no heatsink using a 2S2P board, as specified in JEDEC standards JESD51-2, JESD51-5, and JESD51-7, as appropriate.
- Ψ_{JB} (Ψ_{JB}): Thermal characterization parameter providing correlation between semiconductor junction temperature and an application circuit board reference point for the thermal environment defined in Note 4. For the SOIC-8 package, the board reference is defined as the PCB copper adjacent to pin 6.
- Ψ_{JT} (Ψ_{JT}): Thermal characterization parameter providing correlation between the semiconductor junction temperature and the center of the top of the package for the thermal environment defined in Note 4.

PIN DEFINITIONS

Pin	Name	Pin Description
1	NC	No Connect. This pin can be grounded or left floating.
2	INA	Input to Channel A.
3	GND	Ground. Common ground reference for input and output circuits.
4	INB	Input to Channel B.
5 (FAN3216)	OUTB	Gate Drive Output B (inverted from the input): Held LOW unless required input is present and V_{DD} is above UVLO threshold.
5 (FAN3217)	OUTB	Gate Drive Output B: Held LOW unless required input(s) are present and V_{DD} is above UVLO threshold.
6	VDD	Supply Voltage. Provides power to the IC.
7 (FAN3216)	OUTA	Gate Drive Output A (inverted from the input): Held LOW unless required input is present and V_{DD} is above UVLO threshold.
7 (FAN3217)	OUTA	Gate Drive Output A: Held LOW unless required input(s) are present and V_{DD} is above UVLO threshold.
8	NC	No Connect. This pin can be grounded or left floating.

OUTPUT LOGIC

FAN3216 (x = A or B)		FAN3217 (x = A or B)	
INx	OUTx	INx	OUTx
0	1	0 (Note 7)	0
1 (Note 7)	0	1	1

- Default input signal if no external connection is made.

FAN3216 / FAN3217

BLOCK DIAGRAMS

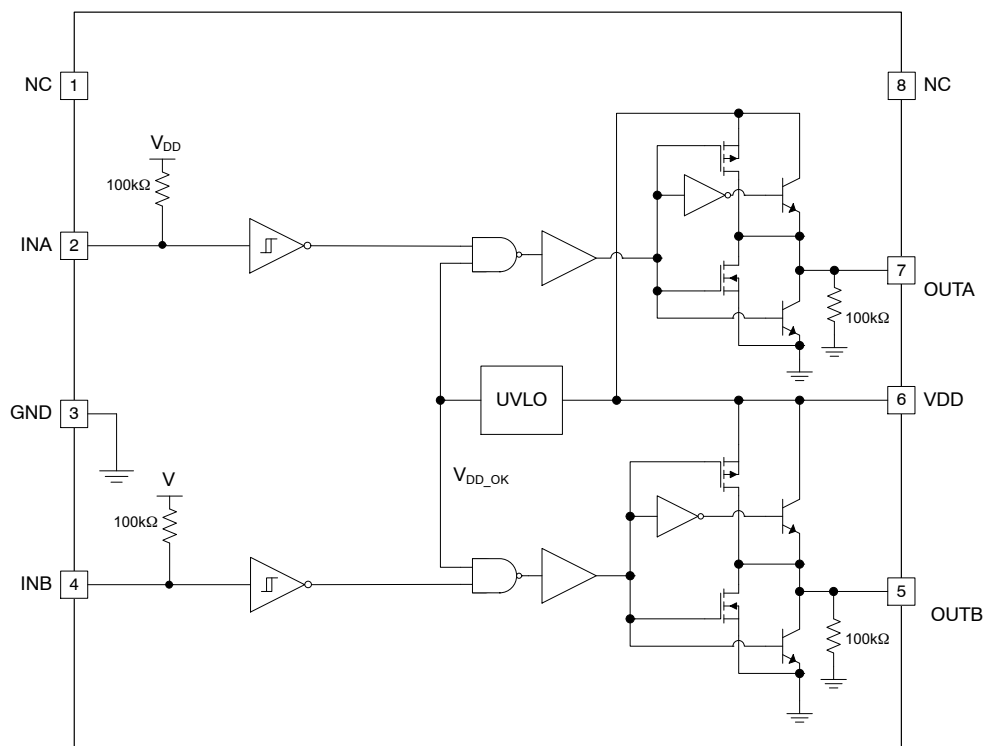


Figure 4. FAN3216 Block Diagram

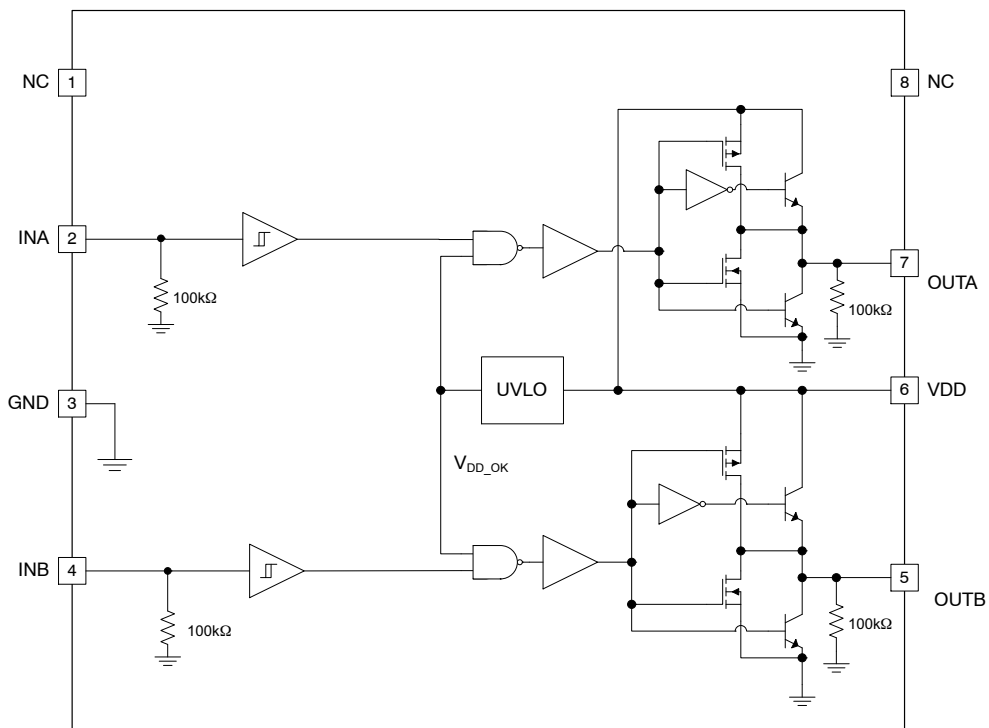


Figure 5. FAN3217 Block Diagram

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Min.	Max.	Unit
V_{DD}	VDD to PGND	-0.3	20.0	V
V_{IN}	INA and INB to GND	GND - 0.3	$V_{DD} + 0.3$	V
V_{OUT}	OUTA and OUTB to GND	GND - 0.3	$V_{DD} + 0.3$	V
T_L	Lead Soldering Temperature (10 Seconds)		260	°C
T_J	Junction Temperature	-55	150	°C
T_{STG}	Storage Temperature	-65	150	°C

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Min.	Max.	Unit
V_{DD}	Supply Voltage Range	4.5	18.0	V
V_{IN}	Input Voltage INA and INB	0	V_{DD}	V
T_A	Operating Ambient Temperature	-40	125	°C

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.



ELECTRICAL CHARACTERISTICS

(Unless otherwise noted, $V_{DD} = 12\text{ V}$, $T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$. Currents are defined as positive into the device and negative out of the device.)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
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SUPPLY

V_{DD}	Operating Range		4.5		18.0	V
I_{DD}	Supply Current, Inputs Not Connected			0.75	1.2	mA
V_{ON}	Turn-On Voltage	$I_{NA} = V_{DD}$, $I_{NB} = 0\text{ V}$	3.45	3.9	4.35	V
V_{OFF}	Turn-Off Voltage	$I_{NA} = V_{DD}$, $I_{NB} = 0\text{ V}$	3.25	3.7	4.15	V

INPUTS

V_{IL_T}	INx Logic Low Threshold		0.8	1.2		V
V_{IH_T}	INx Logic High Threshold			1.6	2.0	V
V_{HYS_T}	TTL Logic Hysteresis Voltage		0.2	0.4	0.8	V
I_{IN+}	Non-Inverting Input Current	IN from 0 to V_{DD}	-1.0		175	μA
I_{IN-}	Inverting Input Current	IN from 0 to V_{DD}	-175		1.0	μA

OUTPUTS

I_{SINK}	OUT Current, Mid-Voltage, Sinking (Note 8)	OUTx at $V_{DD}/2$, $C_{LOAD} = 0.22\text{ }\mu\text{F}$, $f = 1\text{ kHz}$		2.4		A
I_{SOURCE}	OUT Current, Mid-Voltage, Sourcing (Note 8)	OUTx at $V_{DD}/2$, $C_{LOAD} = 0.1\text{ }\mu\text{F}$, $f = 1\text{ kHz}$		-1.6		A
I_{PK_SINK}	OUT Current, Peak, Sinking (Note 8)	$C_{LOAD} = 0.1\text{ }\mu\text{F}$, $f = 1\text{ kHz}$		3		A
I_{PK_SOURCE}	OUT Current, Peak, Sourcing (Note 8)	$C_{LOAD} = 0.1\text{ }\mu\text{F}$, $f = 1\text{ kHz}$		-3		A
t_{RISE}	Output Rise Time (Note 9)	$C_{LOAD} = 1000\text{ pF}$		12	22	ns
t_{FALL}	Output Fall Time (Note 9)	$C_{LOAD} = 1000\text{ pF}$		9	17	ns
t_{D1}, t_{D2}	Output Propagation Delay, TTL Inputs (Note 9)	0 – 5 V_{IN} , 1 V/ns Slew Rate	10	19	34	ns
t_{DEL_MATCH}	Propagation Matching Between Channels	$I_{NA} = I_{NB}$, OUTA and OUTB at 50% Point		1	2	ns
I_{RVS}	Output Reverse Current Withstand (Note 8)			500		mA

8. Not tested in production.

9. See Timing Diagrams of Figure 6 and Figure 7.

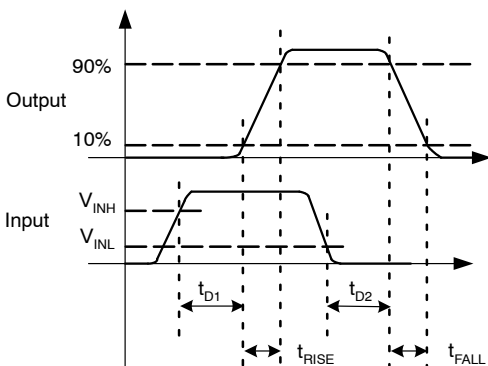
TIMING DIAGRAMS

Figure 6. Non-Inverting Timing Diagram

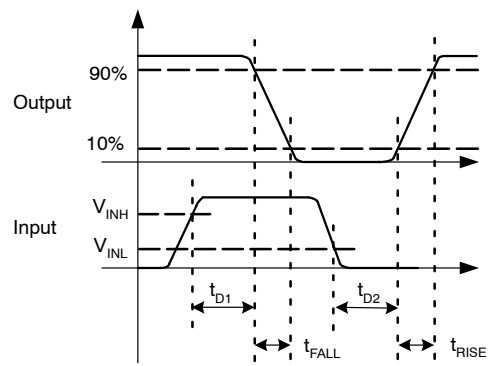


Figure 7. Inverting Timing Diagram

TYPICAL PERFORMANCE CHARACTERISTICS

Typical characteristics are provided at $T_A = 25^\circ\text{C}$ and $V_{DD} = 12\text{ V}$ unless otherwise noted.

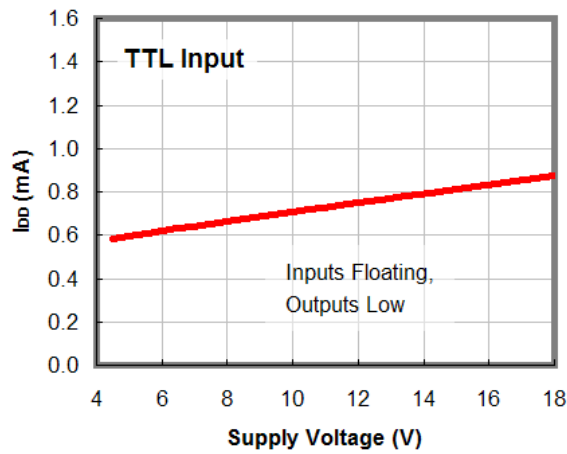
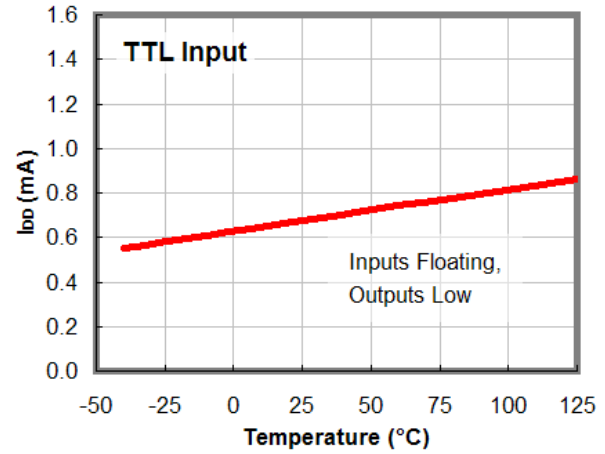
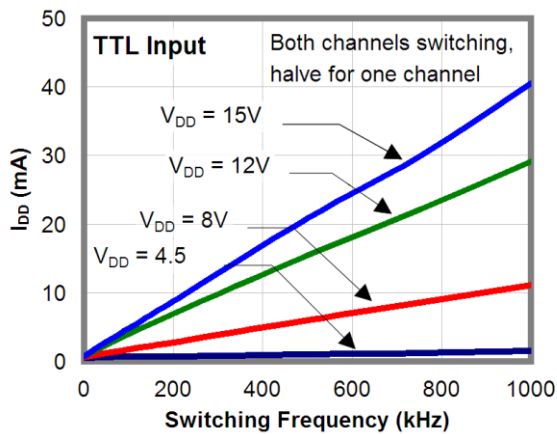
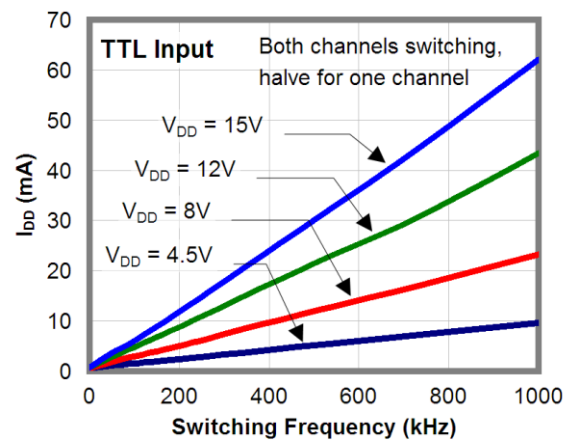
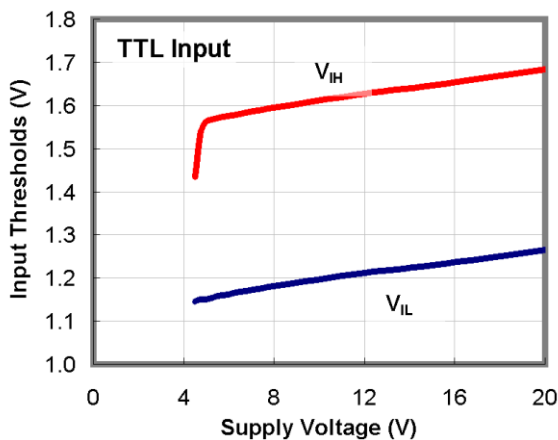
Figure 8. I_{DD} (Static) vs. Supply Voltage (Note 10)Figure 9. I_{DD} (Static) vs. Temperature (Note 10)Figure 10. I_{DD} (Static) vs. FrequencyFigure 11. I_{DD} (1 nF Load) vs. Frequency

Figure 12. Input Thresholds vs. Supply Voltage

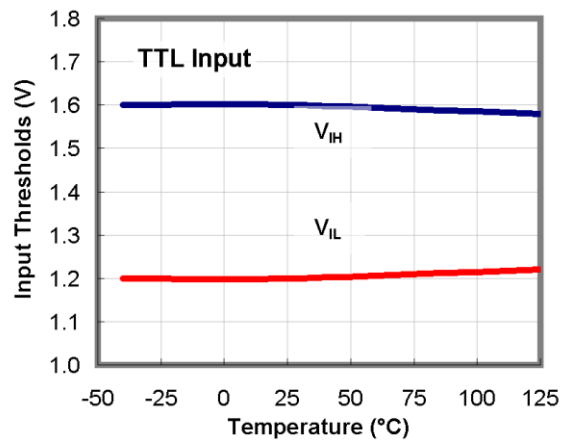


Figure 13. Input Thresholds vs. Temperature

TYPICAL PERFORMANCE CHARACTERISTICS

Typical characteristics are provided at $T_A = 25^\circ\text{C}$ and $V_{DD} = 12\text{ V}$ unless otherwise noted. (continued)

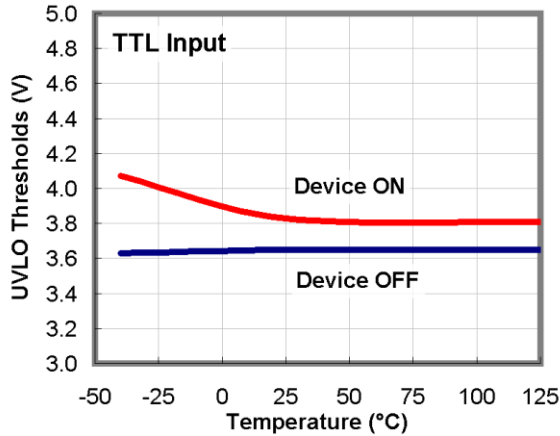


Figure 14. UVLO Threshold vs. Temperature

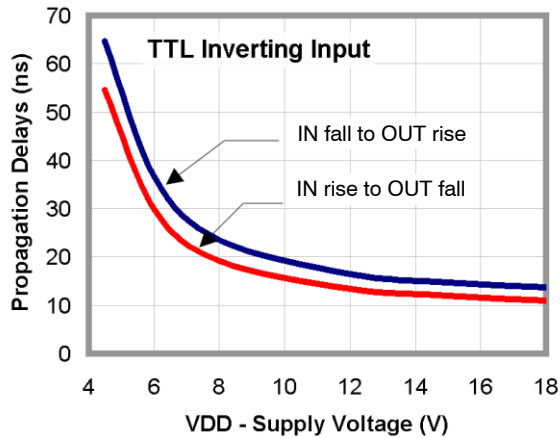


Figure 15. Propagation Delay vs. Supply Voltage

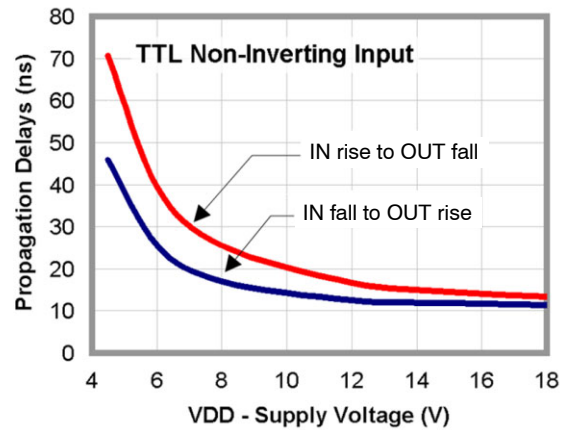


Figure 16. Propagation Delay vs. Supply Voltage

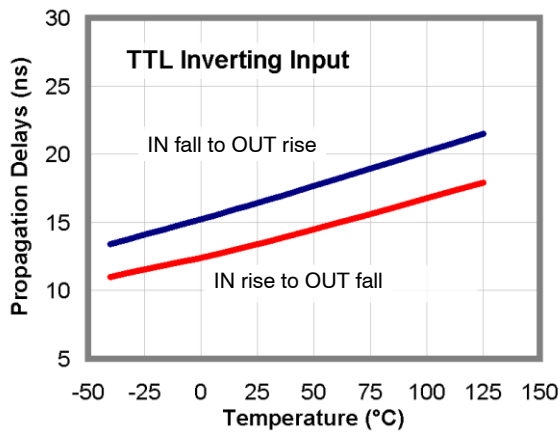


Figure 17. Propagation Delays vs. Temperature

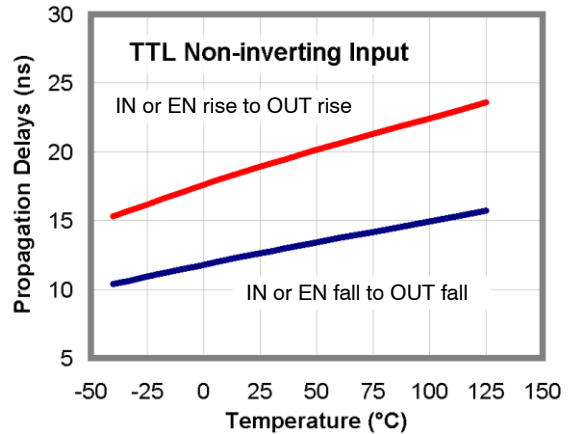


Figure 18. Propagation Delays vs. Temperature

TYPICAL PERFORMANCE CHARACTERISTICS

Typical characteristics are provided at $T_A = 25^\circ\text{C}$ and $V_{DD} = 12\text{ V}$ unless otherwise noted. (continued)

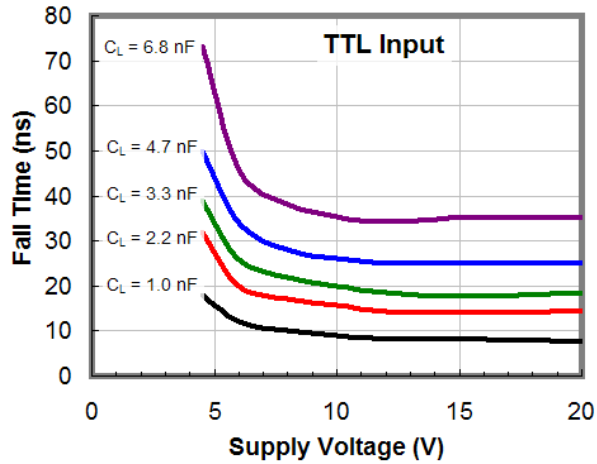


Figure 19. Fall Time vs. Supply Voltage

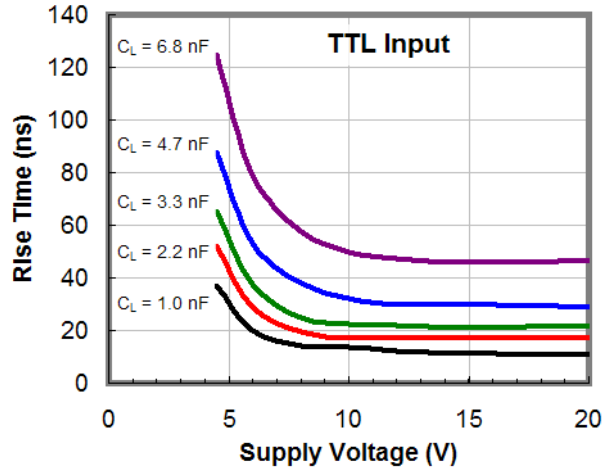


Figure 20. Rise Time vs. Supply Voltage

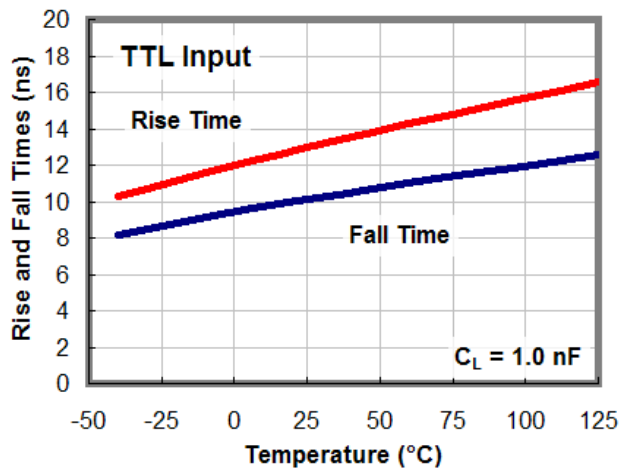


Figure 21. Rise and Fall Times vs. Temperature

TYPICAL PERFORMANCE CHARACTERISTICS

Typical characteristics are provided at $T_A = 25^\circ\text{C}$ and $V_{DD} = 12\text{ V}$ unless otherwise noted. (continued)

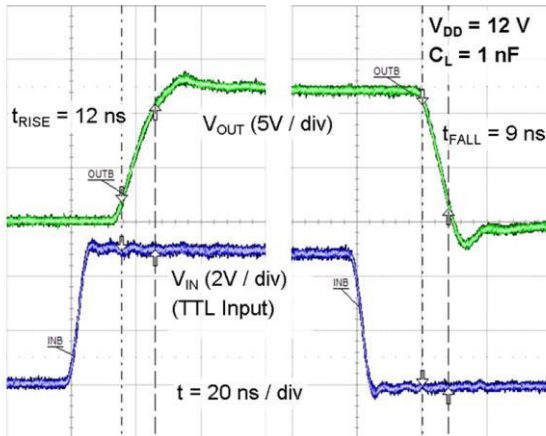


Figure 22. Rise/Fall Waveforms with 2.2 nF Load

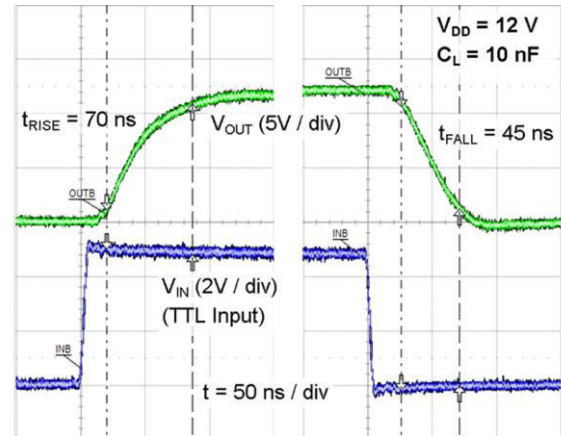


Figure 23. Rise/Fall Waveforms with 10 nF Load

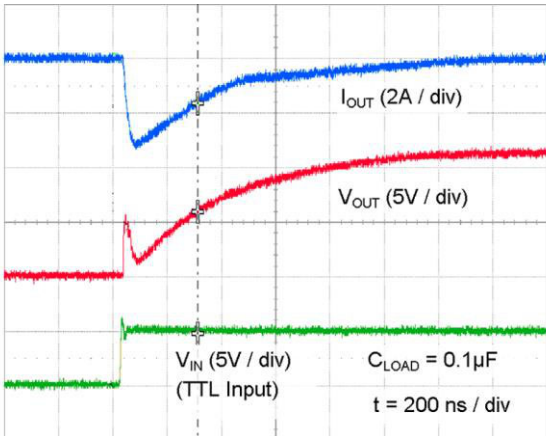


Figure 24. Quasi-Static Source Current with $V_{DD} = 12\text{ V}$ (Note 11)

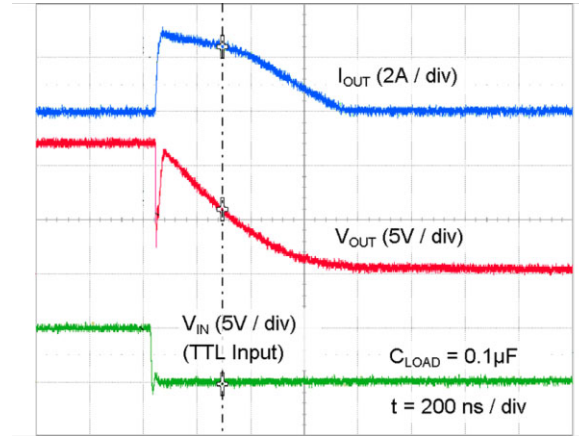


Figure 25. Quasi-Static Sink Current with $V_{DD} = 12\text{ V}$ (Note 11)

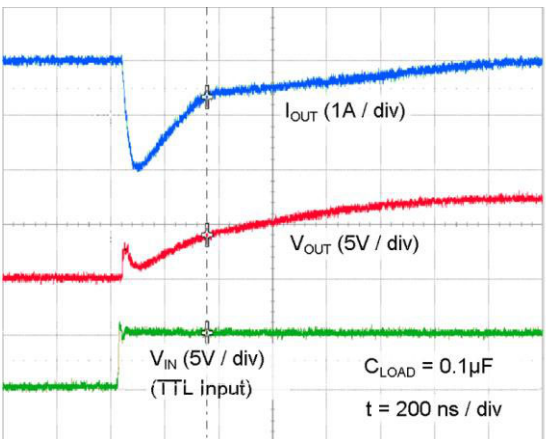


Figure 26. Quasi-Static Source Current with $V_{DD} = 8\text{ V}$ (Note 11)

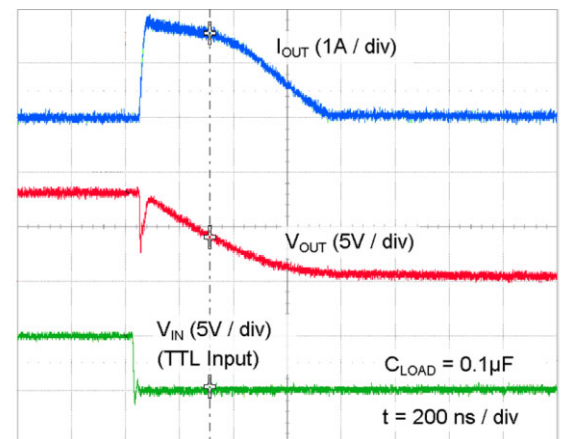
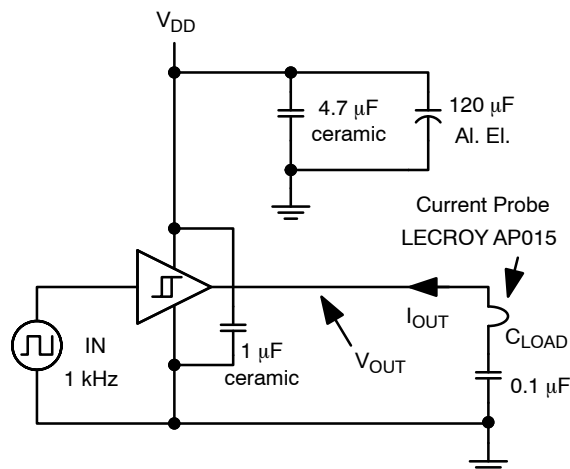


Figure 27. Quasi-Static Sink Current with $V_{DD} = 8\text{ V}$ (Note 11)

10. For any inverting inputs pulled low, non-inverting inputs pulled high, or outputs driven high, static I_{DD} increases by the current flowing through the corresponding pull-up/down resistor shown in Figure 6 and Figure 7.

11. The initial spike in each current waveform is a measurement artifact caused by the stray inductance of the current-measurement loop.

TEST CIRCUIT

Figure 28. Quasi-Static I_{OUT} / V_{OUT} Test Circuit

APPLICATIONS INFORMATION

Input Thresholds

The FAN3216 and the FAN3217 drivers consist of two identical channels that may be used independently at rated current or connected in parallel to double the individual current capacity.

The input thresholds meet industry-standard TTL-logic thresholds independent of the V_{DD} voltage, and there is a hysteresis voltage of approximately 0.4 V. These levels permit the inputs to be driven from a range of input logic signal levels for which a voltage over 2 V is considered logic HIGH. The driving signal for the TTL inputs should have fast rising and falling edges with a slew rate of 6 V/ μ s or faster, so a rise time from 0 to 3.3 V should be 550 ns or less. With reduced slew rate, circuit noise could cause the driver input voltage to exceed the hysteresis voltage and retrigger the driver input, causing erratic operation.

Static Supply Current

In the I_{DD} (static) typical performance characteristics shown in Figure 8 and Figure 9, each curve is produced with both inputs floating and both outputs LOW to indicate the lowest static I_{DD} current. For other states, additional current flows through the 100 k Ω resistors on the inputs and outputs shown in the block diagram of each part (see Figure 6 and Figure 7). In these cases, the actual static I_{DD} current is the value obtained from the curves plus this additional current.

MillerDrive Gate Drive Technology

FAN3216 and FAN3217 gate drivers incorporate the MillerDrive architecture shown in Figure 29. For the output stage, a combination of bipolar and MOS devices provide large currents over a wide range of supply voltage and temperature variations. The bipolar devices carry the bulk of

the current as OUT swings between 1/3 to 2/3 V_{DD} and the MOS devices pull the output to the HIGH or LOW rail.

The purpose of the MillerDrive™ architecture is to speed up switching by providing high current during the Miller plateau region when the gate-drain capacitance of the MOSFET is being charged or discharged as part of the turn-on / turn-off process.

For applications with zero voltage switching during the MOSFET turn-on or turn-off interval, the driver supplies high peak current for fast switching even though the Miller plateau is not present. This situation often occurs in synchronous rectifier applications because the body diode is generally conducting before the MOSFET is switched ON.

The output pin slew rate is determined by V_{DD} voltage and the load on the output. It is not user adjustable, but a series resistor can be added if a slower rise or fall time at the MOSFET gate is needed.

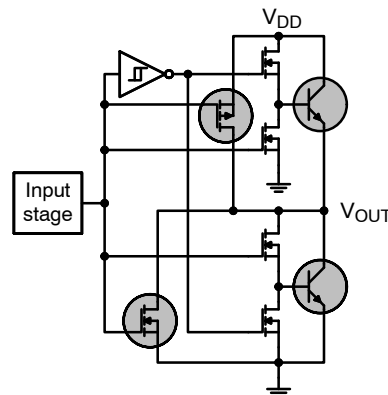


Figure 29. MillerDrive Output Architecture

Under-Voltage Lockout

The FAN321x startup logic is optimized to drive ground-referenced N-channel MOSFETs with an under-voltage lockout (UVLO) function to ensure that the IC starts up in an orderly fashion. When V_{DD} is rising, yet below the 3.9 V operational level, this circuit holds the output LOW, regardless of the status of the input pins. After the part is active, the supply voltage must drop 0.2 V before the part shuts down. This hysteresis helps prevent chatter when low V_{DD} supply voltages have noise from the power switching. This configuration is not suitable for driving high-side P-channel MOSFETs because the low output voltage of the driver would turn the P-channel MOSFET on with V_{DD} below 3.9 V.

V_{DD} Bypass Capacitor Guidelines

To enable this IC to turn a device ON quickly, a local high-frequency bypass capacitor, C_{BYP} , with low ESR and ESL should be connected between the V_{DD} and GND pins with minimal trace length. This capacitor is in addition to the bulk electrolytic capacitance of 10 μ F to 47 μ F commonly found on driver and controller bias circuits.

A typical criterion for choosing the value of C_{BYP} is to keep the ripple voltage on the V_{DD} supply to $\leq 5\%$. This is often achieved with a value ≥ 20 times the equivalent load capacitance C_{EQV} , defined here as Q_{GATE}/V_{DD} . Ceramic capacitors of 0.1 μ F to 1 μ F or larger are common choices, as are dielectrics, such as X5R and X7R with good temperature characteristics and high pulse current capability.

If circuit noise affects normal operation, the value of C_{BYP} may be increased to 50–100 times the C_{EQV} , or C_{BYP} may be split into two capacitors. One should be a larger value, based on equivalent load capacitance, and the other a smaller value, such as 1–10 nF mounted closest to the V_{DD} and GND pins to carry the higher frequency components of the current pulses. The bypass capacitor must provide the pulsed current from both of the driver channels and, if the drivers are switching simultaneously, the combined peak current sourced from the C_{BYP} would be twice as large as when a single channel is switching.

Layout and Connection Guidelines

The FAN3216 and FAN3217 gate drivers incorporate fast-reacting input circuits, short propagation delays, and powerful output stages capable of delivering current peaks over 2 A to facilitate voltage transition times from under 10 ns to over 150 ns. The following layout and connection guidelines are strongly recommended:

- Keep high-current output and power ground paths separate from logic input signals and signal ground paths. This is especially critical for TTL-level logic thresholds at driver input pins

- Keep the driver as close to the load as possible to minimize the length of high-current traces. This reduces the series inductance to improve high-speed switching, while reducing the loop area that can radiate EMI to the driver inputs and surrounding circuitry.
- If the inputs to a channel are not externally connected, the internal 100 k Ω resistors indicated on block diagrams command a low output. In noisy environments, it may be necessary to tie inputs of an unused channel to V_{DD} or GND using short traces to prevent noise from causing spurious output switching.
- Many high-speed power circuits can be susceptible to noise injected from their own output or other external sources, possibly causing output re-triggering. These effects can be obvious if the circuit is tested in breadboard or non-optimal circuit layouts with long input or output leads. For best results, make connections to all pins as short and direct as possible.
- FAN3216 and FAN3217 are pin-compatible with many other industry-standard drivers.
- The turn-on and turn-off current paths should be minimized, as discussed in the following section.

Figure 30 shows the pulsed gate drive current path when the gate driver is supplying gate charge to turn the MOSFET on. The current is supplied from the local bypass capacitor, C_{BYP} , and flows through the driver to the MOSFET gate and to ground. To reach the high peak currents possible, the resistance and inductance in the path should be minimized. The localized C_{BYP} acts to contain the high peak current pulses within this driver-MOSFET circuit, preventing them from disturbing the sensitive analog circuitry in the PWM controller.

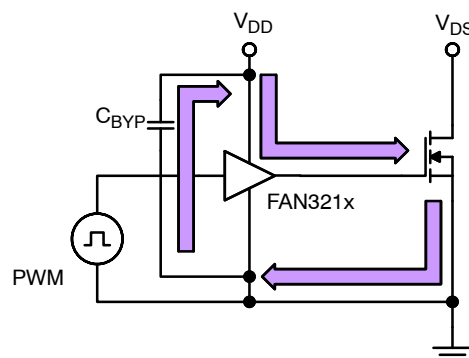


Figure 30. Current Path for MOSFET Turn-On

Figure 31 shows the current path when the gate driver turns the MOSFET OFF. Ideally, the driver shunts the current directly to the source of the MOSFET in a small circuit loop. For fast turn-off times, the resistance and inductance in this path should be minimized.

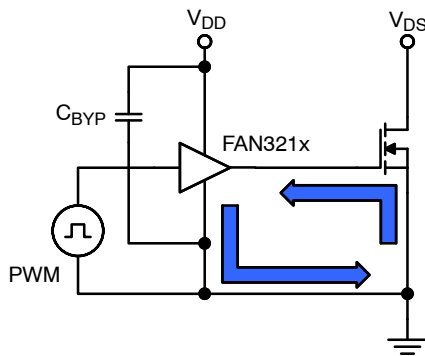


Figure 31. Current Path for MOSFET Turn-Off

Operational Waveforms

At power-up, the driver output remains LOW until the V_{DD} voltage reaches the turn-on threshold. The magnitude of the OUT pulses rises with V_{DD} until steady-state V_{DD} is reached. The non-inverting operation illustrated in Figure 32 shows that the output remains LOW until the UVLO threshold is reached, then the output is in-phase with the input.

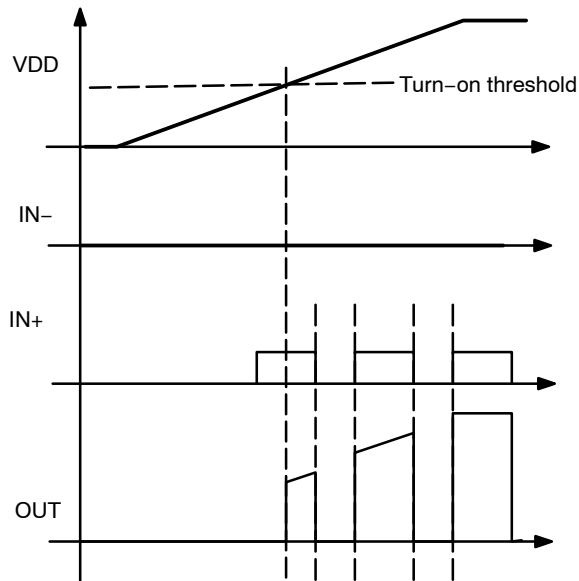


Figure 32. Non-Inverting Startup Waveforms

The inverting configuration of startup waveforms are shown in Figure 33. With $IN+$ tied to V_{DD} and the input signal applied to $IN-$, the OUT pulses are inverted with respect to the input. At power-up, the inverted output remains LOW until the V_{DD} voltage reaches the turn-on threshold, then it follows the input with inverted phase.

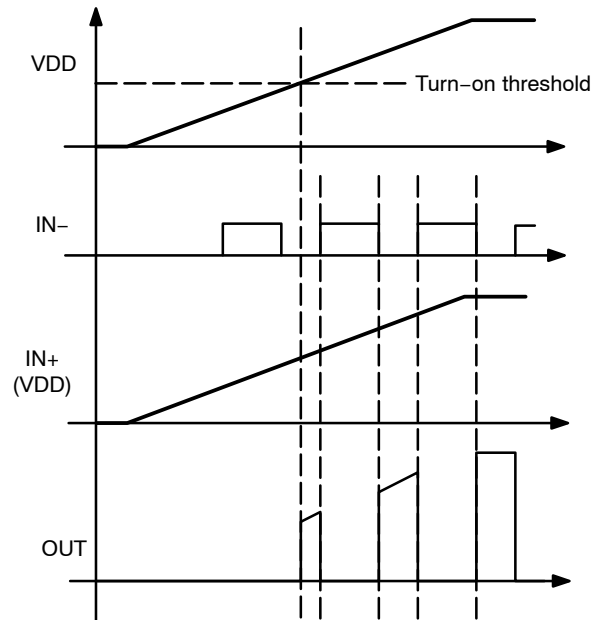


Figure 33. Inverting Startup Waveforms

Thermal Guidelines

Gate drivers used to switch MOSFETs and IGBTs at high frequencies can dissipate significant amounts of power. It is important to determine the driver power dissipation and the resulting junction temperature in the application to ensure that the part is operating within acceptable temperature limits.

The total power dissipation in a gate driver is the sum of two components, P_{GATE} and $P_{DYNAMIC}$:

$$P_{TOTAL} = P_{GATE} + P_{DYNAMIC} \quad (\text{eq. 1})$$

P_{GATE} (Gate Driving Loss): The most significant power loss results from supplying gate current (charge per unit time) to switch the load MOSFET on and off at the switching frequency. The power dissipation that results from driving a MOSFET at a specified gate-source voltage, V_{GS} , with gate charge, Q_G , at switching frequency, f_{SW} , is determined by:

$$P_{GATE} = Q_G \times V_{GS} \times f_{SW} \times n \quad (\text{eq. 2})$$

where n is the number of driver channels in use (1 or 2).

$P_{DYNAMIC}$ (Dynamic Pre-Drive / Shoot-through Current): A power loss resulting from internal current consumption under dynamic operating conditions, including pin pull-up / pull-down resistors, can be obtained using the graphs in the Typical Performance Characteristics to determine the current $I_{DYNAMIC}$ drawn from V_{DD} under actual operating conditions:

$$P_{\text{DYNAMIC}} = I_{\text{DYNAMIC}} \times V_{\text{DD}} \times n \quad (\text{eq. 3})$$

Once the power dissipated in the driver is determined, the driver junction rise with respect to circuit board can be evaluated using the following thermal equation, assuming Ψ_{JB} was determined for a similar thermal design (heat sinking and air flow):

$$T_{\text{J}} = P_{\text{TOTAL}} \times \Psi_{\text{JB}} + T_{\text{B}} \quad (\text{eq. 4})$$

where:

T_{J} = driver junction temperature;

Ψ_{JB} = (psi) thermal characterization parameter relating temperature rise to total power dissipation; and

T_{B} = board temperature in location as defined in the Thermal Characteristics table.

In the forward converter with synchronous rectifier shown in the typical application diagrams, the FDMS8660S is a reasonable MOSFET selection. The gate charge for each SR MOSFET would be 60 nC with $V_{\text{GS}} = V_{\text{DD}} = 7 \text{ V}$. At a

switching frequency of 500 kHz, the total power dissipation is:

$$P_{\text{GATE}} = 60\text{nC} \times 7 \text{ V} \times 500 \text{ kHz} \times 2 = 0.42 \text{ W} \quad (\text{eq. 5})$$

$$P_{\text{DYNAMIC}} = 3 \text{ mA} \times 7 \text{ V} \times 2 = 0.042 \text{ W} \quad (\text{eq. 6})$$

$$P_{\text{TOTAL}} = 0.46 \text{ W} \quad (\text{eq. 7})$$

The SOIC-8 has a junction-to-board thermal characterization parameter of $\Psi_{\text{JB}} = 43^\circ\text{C/W}$. In a system application, the localized temperature around the device is a function of the layout and construction of the PCB along with airflow across the surfaces. To ensure reliable operation, the maximum junction temperature of the device must be prevented from exceeding the maximum rating of 150°C ; with 80% derating, T_{J} would be limited to 120°C . Rearranging Equation 4 determines the board temperature required to maintain the junction temperature below 120°C :

$$T_{\text{B}} = T_{\text{J}} - P_{\text{TOTAL}} \times \Psi_{\text{JB}} \quad (\text{eq. 8})$$

$$T_{\text{B}} = 120^\circ\text{C} - 0.46 \text{ W} \times 43^\circ\text{C/W} = 100^\circ\text{C} \quad (\text{eq. 9})$$

TYPICAL APPLICATION DIAGRAMS

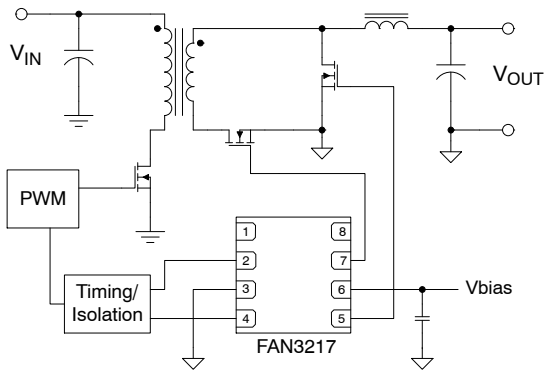


Figure 34. Forward Converter with Synchronous Rectification

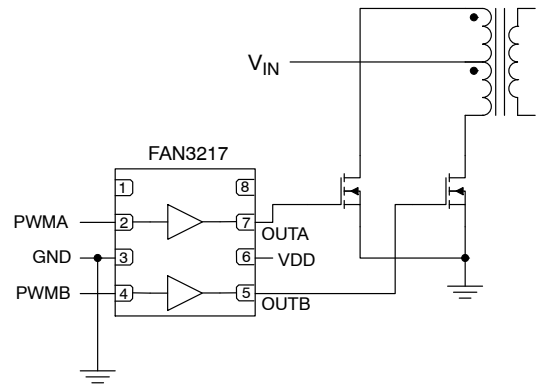


Figure 35. Primary-Side Dual Driver in a Push-Pull Converter

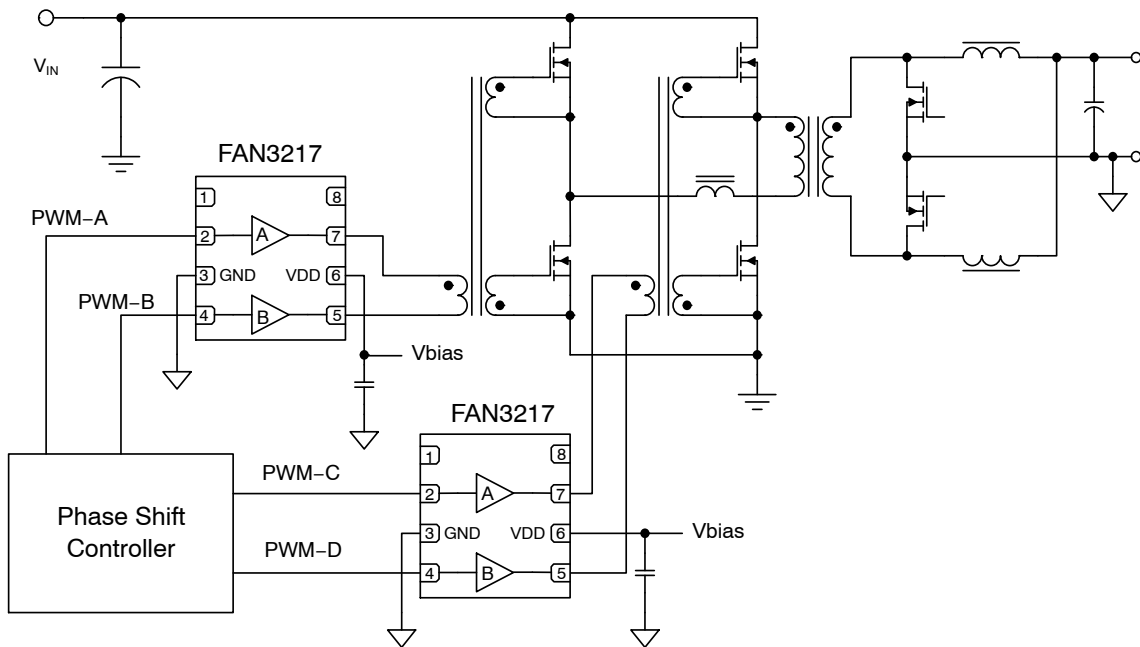


Figure 36. Phase-Shifted Full-Bridge with Two Gate Drive Transformers (Simplified)

ORDERING INFORMATION

Part Number	Logic	Input Threshold	Package	Packing Method	Quantity per Reel
FAN3216TMX	Dual Inverting Channels	TTL	SOIC-8	Tape & Reel	2,500
FAN3217TMX	Dual Non-Inverting Channels	TTL	SOIC-8	Tape & Reel	2,500

FAN3216 / FAN3217

RELATED PRODUCTS

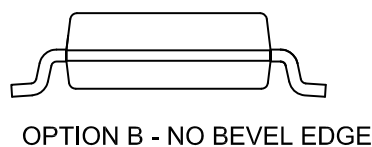
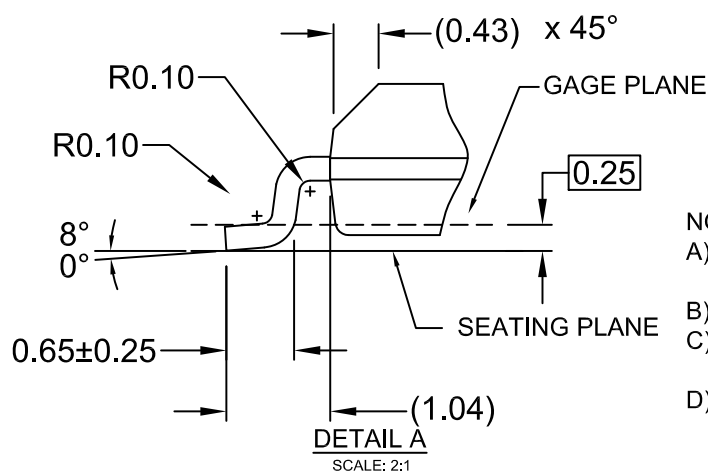
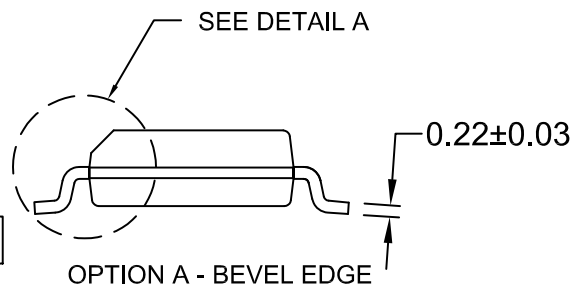
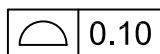
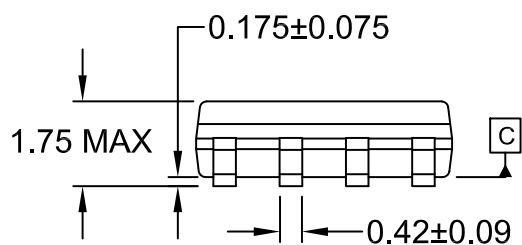
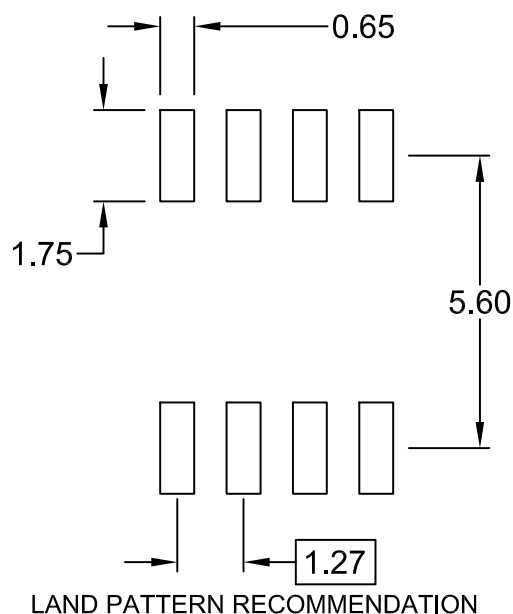
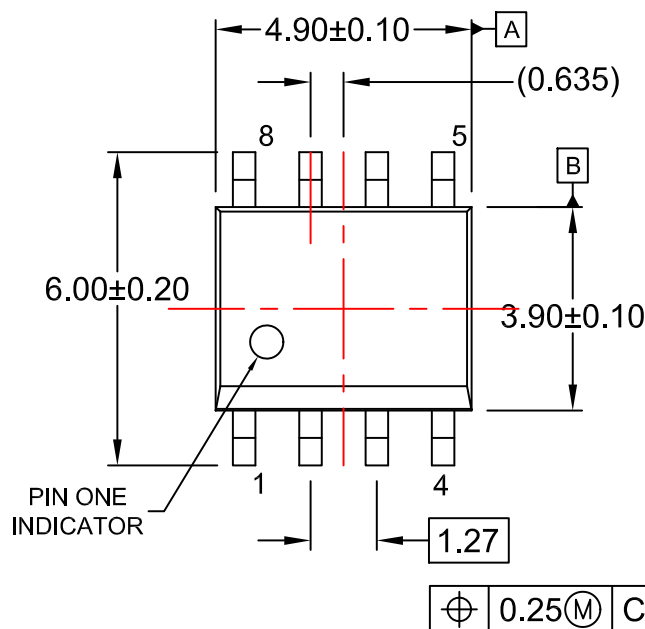
Type	Part Number	Gate Drive (Note 13) (Sink/Src)	Input Threshold	Logic	Package
Single 1 A	FAN3111C	+1.1 A / -0.9 A	CMOS	Single Channel of Dual-Input/Single-Output	SOT23-5, MLP6
Single 1 A	FAN3111E	+1.1 A / -0.9 A	External (Note 13)	Single Non-Inverting Channel with External Reference	SOT23-5, MLP6
Single 2 A	FAN3100C	+2.5 A / -1.8 A	CMOS	Single Channel of Two-Input/One-Output	SOT23-5, MLP6
Single 2 A	FAN3100T	+2.5 A / -1.8 A	TTL	Single Channel of Two-Input/One-Output	SOT23-5, MLP6
Single 2 A	FAN3180	+2.4 A / -1.6 A	TTL	Single Non-Inverting Channel + 3.3 V LDO	SOT23-5
Dual 2 A	FAN3216T	+2.4 A / -1.6 A	TTL	Dual Inverting Channels	SOIC8
Dual 2 A	FAN3217T	+2.4 A / -1.6 A	TTL	Dual Non-Inverting Channels	SOIC8
Dual 2 A	FAN3226C	+2.4 A / -1.6 A	CMOS	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3226T	+2.4 A / -1.6 A	TTL	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3227C	+2.4 A / -1.6 A	CMOS	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3227T	+2.4 A / -1.6 A	TTL	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3228C	+2.4 A / -1.6 A	CMOS	Dual Channels of Two-Input/One-Output, Pin Config.1	SOIC8, MLP8
Dual 2 A	FAN3228T	+2.4 A / -1.6 A	TTL	Dual Channels of Two-Input/One-Output, Pin Config.1	SOIC8, MLP8
Dual 2 A	FAN3229C	+2.4 A / -1.6 A	CMOS	Dual Channels of Two-Input/One-Output, Pin Config.2	SOIC8, MLP8
Dual 2 A	FAN3229T	+2.4 A / -1.6 A	TTL	Dual Channels of Two-Input/One-Output, Pin Config.2	SOIC8, MLP8
Dual 2 A	FAN3268T	+2.4 A / -1.6 A	TTL	20 V Non-Inverting Channel (NMOS) and Inverting Channel (PMOS) + Dual Enables	SOIC8
Dual 2 A	FAN3278T	+2.4 A / -1.6 A	TTL	30 V Non-Inverting Channel (NMOS) and Inverting Channel (PMOS) + Dual Enables	SOIC8
Dual 4 A	FAN3213T	+4.3 A / -2.8 A	TTL	Dual Inverting Channels	SOIC8
Dual 4 A	FAN3214T	+4.3 A / -2.8 A	TTL	Dual Non-Inverting Channels	SOIC8
Dual 4 A	FAN3223C	+4.3 A / -2.8 A	CMOS	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3223T	+4.3 A / -2.8 A	TTL	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3224C	+4.3 A / -2.8 A	CMOS	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3224T	+4.3 A / -2.8 A	TTL	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3225C	+4.3 A / -2.8 A	CMOS	Dual Channels of Two-Input/One-Output	SOIC8, MLP8
Dual 4 A	FAN3225T	+4.3 A / -2.8 A	TTL	Dual Channels of Two-Input/One-Output	SOIC8, MLP8
Single 9 A	FAN3121C	+9.7 A / -7.1 A	CMOS	Single Inverting Channel + Enable	SOIC8, MLP8
Single 9 A	FAN3121T	+9.7 A / -7.1 A	TTL	Single Inverting Channel + Enable	SOIC8, MLP8
Single 9 A	FAN3122T	+9.7 A / -7.1 A	TTL	Single Non-Inverting Channel + Enable	SOIC8, MLP8
Single 9 A	FAN3122C	+9.7 A / -7.1 A	CMOS	Single Non-Inverting Channel + Enable	SOIC8, MLP8
Dual 12 A	FAN3240	+12.0 A	TTL	Dual-Coil Relay Driver, Timing Config. 0	SOIC8
Dual 12 A	FAN3241	+12.0 A	TTL	Dual-Coil Relay Driver, Timing Config. 1	SOIC8

12. Typical currents with OUTx at 6 V and $V_{DD} = 12$ V.

13. Thresholds proportional to an externally supplied reference voltage.

SOIC8
CASE 751EB
ISSUE A

DATE 24 AUG 2017



NOTES:

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