# Precision, Micropower, High Current Output Voltage Reference

## FEATURES

▶ Maximum temperature coefficient
  ▶ 3 ppm/°C (B grade)
  ▶ 6 ppm/°C (A grade)
▶ Output current capacity (typical): 70 mA sourcing/20 mA sinking
▶ Low quiescent current: 65 µA
▶ Low shutdown current: 1.5 µA
▶ Output voltage noise (0.1 Hz to 10 Hz): 3 ppm p-p
▶ Maximum initial output voltage error
  ▶ ±0.04% (B grade)
  ▶ ±0.08% (A grade)
▶ Operating temperature range: −40°C to +125°C
▶ Maximum input voltage: 16 V
▶ Low dropout voltage: 0.25 V
▶ 1.8 V logic compatible
▶ 8-Lead MSOP package

## APPLICATIONS

▶ Precision power supplies
▶ Portable instrumentation
▶ Process transmitters
▶ Remote sensors
▶ Medical instrumentation
▶ Auto battery monitors

## GENERAL DESCRIPTION

The ADR3625 is a low power, high precision voltage reference that features a maximum temperature coefficient of 3 ppm/°C for the B grade in an 8-lead MSOP. Capable of sourcing up to 70 mA, the ADR3625 is an exceptional replacement to standard low dropout (LDO) regulators. For high accuracy, the output voltage and temperature coefficient are trimmed during production using the Analog Devices, Inc., proprietary DigiTrim® technology.

The low thermal hysteresis (–7 ppm) and low long-term drift (160 ppm at 4500 Hr) improve system lifetime accuracy. A minimum load capacitance of 0.1 µF is required for operation. The ADR3625 is specified over the –40°C to +125°C operating temperature range.
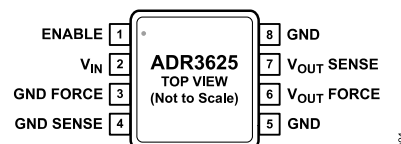
## PIN CONFIGURATION



Figure 1. 8-Lead MSOP Pin Configuration

Table 1. Voltage Reference Choices from Analog Devices

| Micropower | Low Power | High Current |
|---|---|---|
| LT6656 | ADR391 | LT6658 |
| ADR291 | LT1460 | LT1461 |
| REF192 | ADR361 | ADR431 |
| LT1461 | ADR421 | REF192 |
| LT1790 | LTC6652 | LT1460 |

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## REVISION HISTORY

**10/2022—Revision 0: Initial Version**

## SPECIFICATIONS

### ELECTRICAL CHARACTERISTICS

Input voltage ($V_{IN}$) = 3 V to 16 V, output current capacity ($I_L$) = 0 mA, load capacitance ($C_L$) = 1 µF, ENABLE voltage ($V_{EN}$) = $V_{IN}$, and –40°C ≤ $T_A$ ≤ +125°C, unless otherwise noted.

*Table 2.*

| Parameter | Symbol | Test Conditions/Comments | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| OUTPUT VOLTAGE | $V_{OUT}$ | $T_A$ = 25°C | | | | |
| A Grade | | | 2.498 | 2.500 | 2.502 | V |
| B Grade | | | 2.499 | 2.500 | 2.501 | V |
| INITIAL OUTPUT VOLTAGE ERROR | $V_{OUT\_ERR}$ | $T_A$ = 25°C | | | | |
| A Grade | | | | | ±0.08 | % |
| B Grade | | | | | ±0.04 | % |
| SOLDER HEAT RESISTANCE SHIFT[1] | | | | –0.06 | | % |
| TEMPERATURE COEFFICIENT | $TCV_{OUT}$ | See the Terminology section | | | | |
| A Grade | | | | 4 | 6 | ppm/°C |
| B Grade | | | | 2 | 3 | ppm/°C |
| LINE REGULATION | $\Delta V_{OUT}/\Delta V_{IN}$ | $V_{IN}$ = 3.0 V to 16 V | | 0.5 | 2 | ppm/V |
| LOAD REGULATION | $\Delta V_{OUT}/\Delta I_L$ | | | | | |
| Sourcing | | $I_L$ = 0 mA to 10 mA, $V_{IN}$ = 3 V | | 10 | 15 | ppm/mA |
| | | $I_L$ = 0 mA to 50 mA, $V_{IN}$ = 4 V | | 3 | 5 | ppm/mA |
| Sinking | | $I_L$ = 0 mA to 10 mA, $V_{IN}$ = 3 V | | 20 | 30 | ppm/mA |
| OUTPUT CURRENT CAPACITY | $I_L$ | | | | | |
| Sourcing | | $V_{IN}$ = 4 V to 16 V | 50 | 70 | | mA |
| Sinking | | $V_{IN}$ = 3 V to 16 V | 10 | 20 | | mA |
| Short Circuit to GND | | $V_{IN}$ = 16 V | | 90 | | mA |
| Short Circuit to $V_{IN}$ | | $V_{IN}$ = 16 V | | 70 | | mA |
| QUIESCENT CURRENT | $I_Q$ | | | | | |
| Normal Operation | | $V_{EN}$ ≥ 1.17 V | | 65 | 75 | µA |
| Shutdown | | $V_{EN}$ ≤ 0.63 V | | 1.5 | 3 | µA |
| DROPOUT VOLTAGE | $V_{DO}$ | $I_L$ = 10 mA | | 0.25 | 0.5 | V |
| | | $I_L$ = 50 mA | | 0.8 | 1 | V |
| ENABLE PIN | | $T_A$ = 25°C | | | | |
| Input High Voltage | $V_{ENH}$ | | 1.17 | | | V |
| Input Low Voltage | $V_{ENL}$ | | | | 0.63 | V |
| Leakage Current | $V_{ENLEAK}$ | | | 0.3 | 1 | µA |
| OUTPUT VOLTAGE NOISE | $e_N$ p-p | $T_A$ = 25°C | | | | |
| | | 0.1 Hz to 10 Hz | | 3 | | ppm p-p |
| | | | | 0.55 | | ppm$_{RMS}$ |
| | | 10 Hz to 1 kHz | | 4 | | ppm$_{RMS}$ |
| OUTPUT VOLTAGE NOISE DENSITY | $e_N$ | $T_A$ = 25°C, 1 kHz | | 300 | | nV/√Hz |
| THERMAL HYSTERESIS | $\Delta V_{OUT\_HYS}$ | +25°C to +125°C to –40°C to +25°C (full cycle) | | –7 | | ppm |
| | | 25°C to 125°C to 25°C (half cycle) | | 15 | | ppm |
| RIPPLE REJECTION RATIO | RRR | $T_A$ = 25°C, input frequency ($f_{IN}$) = 60 Hz | | 64 | | dB |
| LONG-TERM DRIFT | $\Delta V_{OUT\_LTD}$ | $T_A$ = 25°C, relative humidity = 30% | | | | |
| | | 250 hours (early life drift) | | 90 | | ppm |
| | | 1000 hours | | 140 | | ppm |
| | | 4500 hours | | 160 | | ppm |
| TURN-ON SETTLING TIME | $t_R$ | $T_A$ = 25°C, output capacitor ($C_{OUT}$) = 0.1 µF, input capacitor ($C_{IN}$) = 0.1 µF, load resistance ($R_L$) = 1 kΩ | | 600 | | µs |

## SPECIFICATIONS

*Table 2.*

| Parameter | Symbol | Test Conditions/Comments | Min | Typ | Max | Unit |
|---|---|---|---|---|---|---|
| LOAD CAPACITANCE RANGE | | Minimum load capacitance | | 0.1 | | µF |
| | | Maximum load capacitance | | 10 | | µF |

[1] Initial accuracy does not include shift due to solder heat effect (see the Applications Information section.)

## ABSOLUTE MAXIMUM RATINGS

*Table 3.*

| Parameter | Rating |
|---|---|
| $V_{IN}$ to GND SENSE | –0.3 V to +18 V |
| ENABLE to GND SENSE | –0.3 V to +18 V |
| $V_{OUT}$ FORCE to GND SENSE | –0.3 V to $V_{IN}$ + 0.3 V |
| $V_{OUT}$ SENSE to $V_{OUT}$ FORCE | –0.3 V to +0.3 V |
| GND FORCE to GND SENSE | –0.3 V to +0.3 V |
| Temperature | |
| Storage Range | –65°C to +150°C |
| Operating Range | –40°C to +125°C |
| Junction Range | –65°C to +150°C |
| Lead, Soldering (10 sec) | 300°C |

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

## THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Close attention to PCB thermal design is required.

$\theta_{JA}$ is the natural convection junction-to-ambient thermal resistance measured in a one cubic foot sealed enclosure, and $\theta_{JC}$ is the junction-to-case thermal resistance.

*Table 4. Thermal Resistance*

| Package Type | $\theta_{JA}$ | $\theta_{JC}$ | Unit |
|---|---|---|---|
| RM-8 | 132.5 | 43.9 | °C/W |

## ELECTROSTATIC DISCHARGE (ESD) RATINGS

The following ESD information is provided for handling of ESD-sensitive devices in an ESD protected area only.

Human body model (HBM) per ANSI/ESDA/JEDEC JS-001.

## ESD Ratings for ADR3625

*Table 5. ADR3625, 8-Lead MSOP*

| ESD Model | Withstand Threshold (kV) | Class |
|---|---|---|
| HBM | 1 | 1C |

## ESD CAUTION

**ESD (electrostatic discharge) sensitive device**. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.
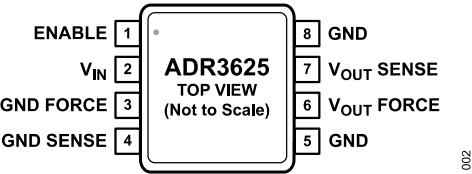
## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



*Figure 2. Pin Configuration*

*Table 6. Pin Function Descriptions*

| Pin No. | Mnemonic | Description |
|---|---|---|
| 1 | ENABLE | Enable Connection. The ENABLE pin enables or disables the device. |
| 2 | $V_{IN}$ | Input Voltage Connection. |
| 3 | GND FORCE | GND Connection. |
| 4 | GND SENSE | GND Sensing Connection. Connect GND SENSE directly to the GND connection of the load device. |
| 5 | GND | Connect to GND FORCE. |
| 6 | $V_{OUT}$ FORCE | Reference Voltage Output. |
| 7 | $V_{OUT}$ SENSE | Reference Voltage Output Sensing Connection. Connect $V_{OUT}$ SENSE directly to the voltage input of the load device. |
| 8 | GND | Connect to GND FORCE. |

## TYPICAL PERFORMANCE CHARACTERISTICS

$T_A$ = 25°C, unless otherwise noted.

**ADR3625**
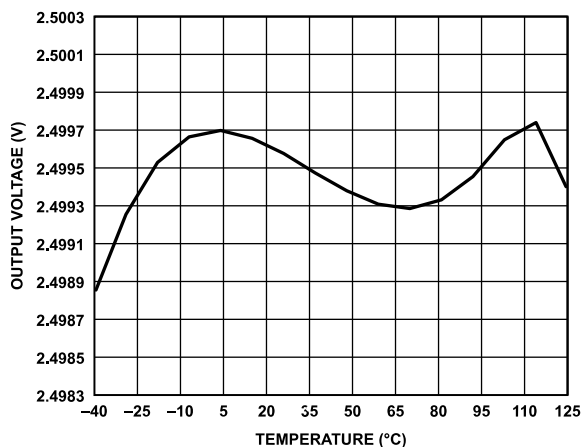


Figure 3. Output Voltage vs. Temperature
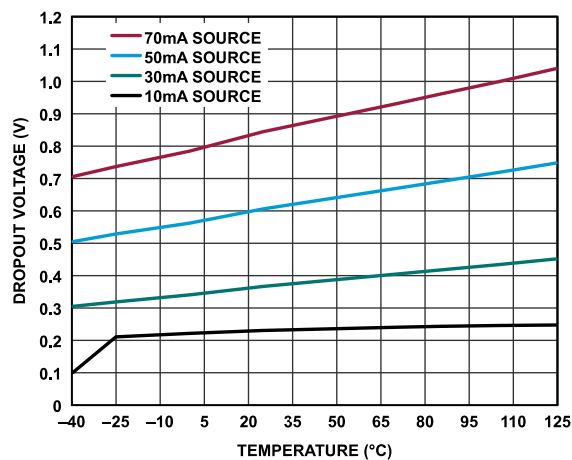


Figure 6. Dropout Voltage vs. Temperature
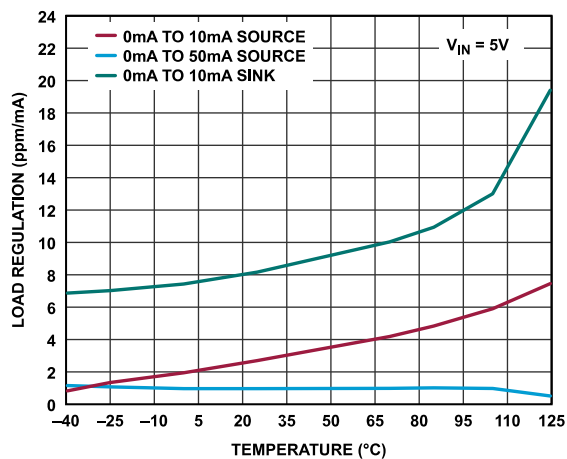


Figure 4. Load Regulation vs. Temperature
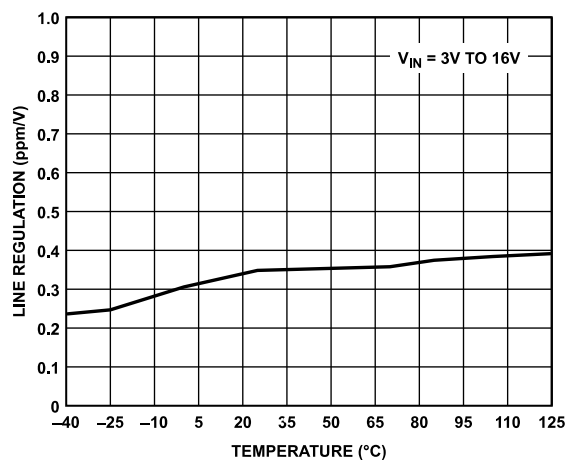


Figure 7. Line Regulation vs. Temperature
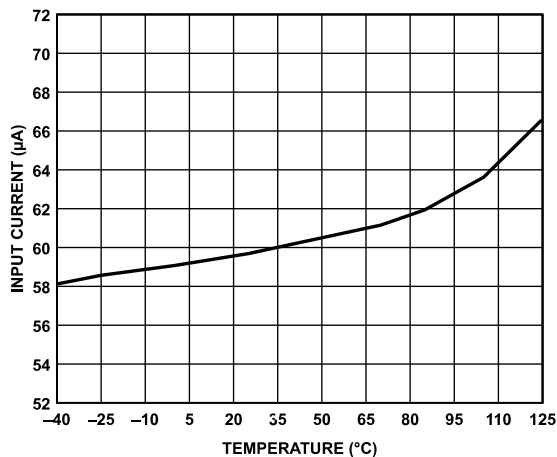


Figure 5. Input Current vs. Temperature
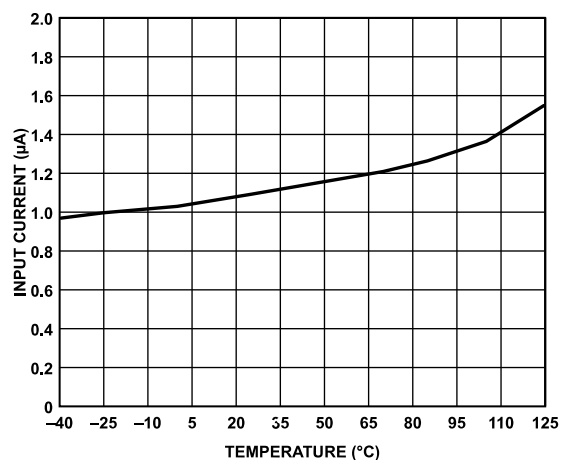


Figure 8. Input Current (Shutdown) vs. Temperature

## TYPICAL PERFORMANCE CHARACTERISTICS
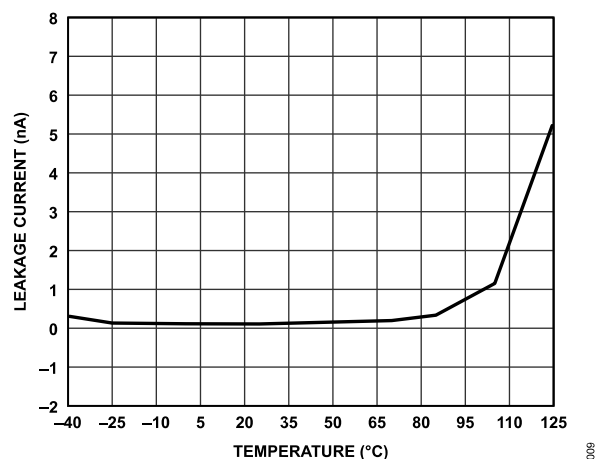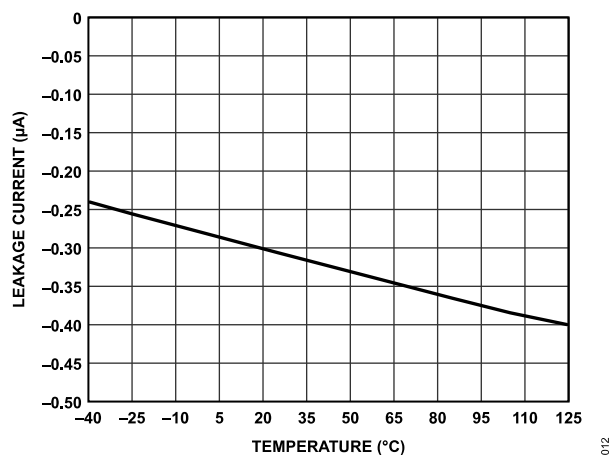


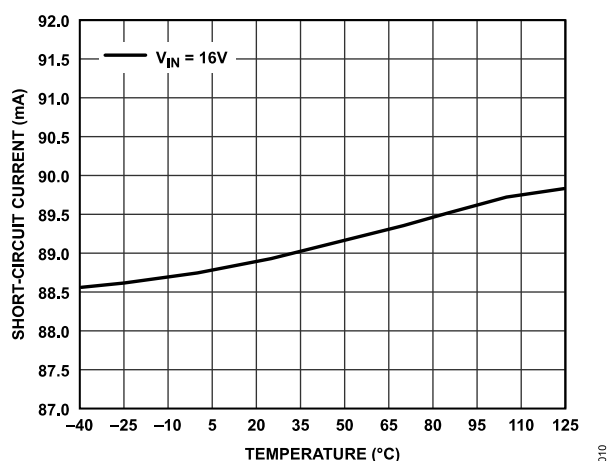Figure 9. Leakage Current vs. Temperature



Figure 12. Leakage Current (Shutdown) vs. Temperature



Figure 10. Short-Circuit Current (Source) vs. Temperature
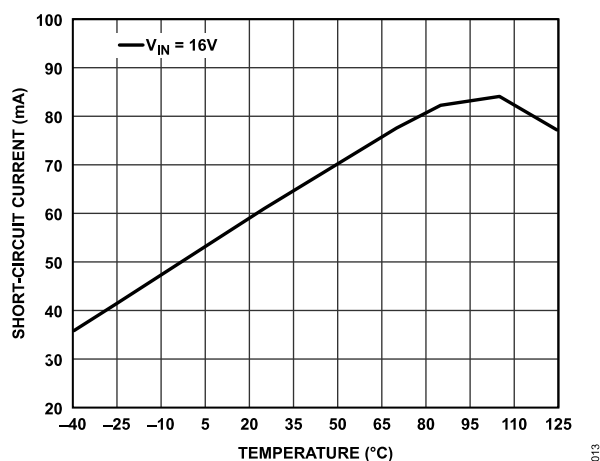


Figure 13. Short-Circuit Current (Sink) vs. Temperature
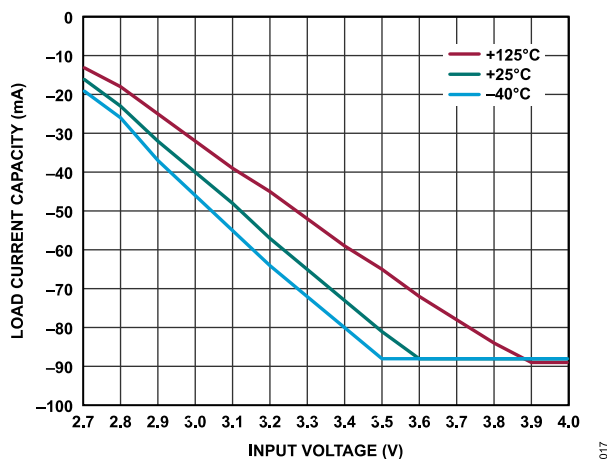


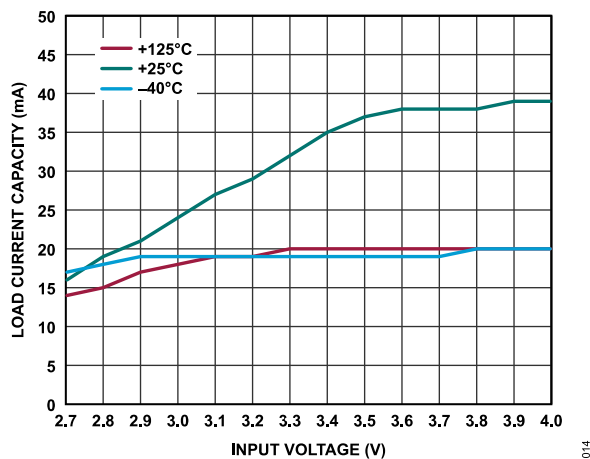Figure 11. Load Current Capacity (Source) vs. Input Voltage



Figure 14. Load Current Capacity (Sink) vs. Input Voltage
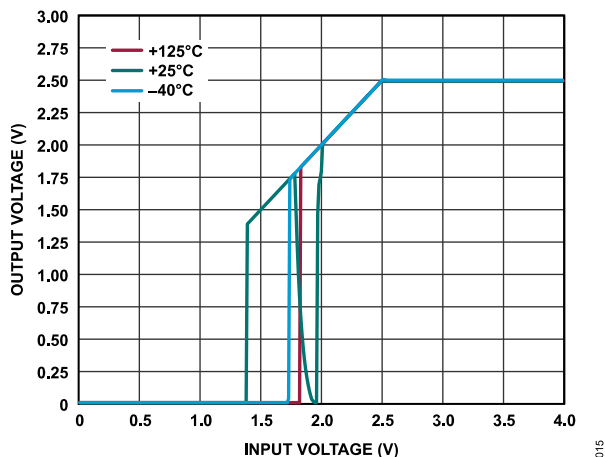
## TYPICAL PERFORMANCE CHARACTERISTICS



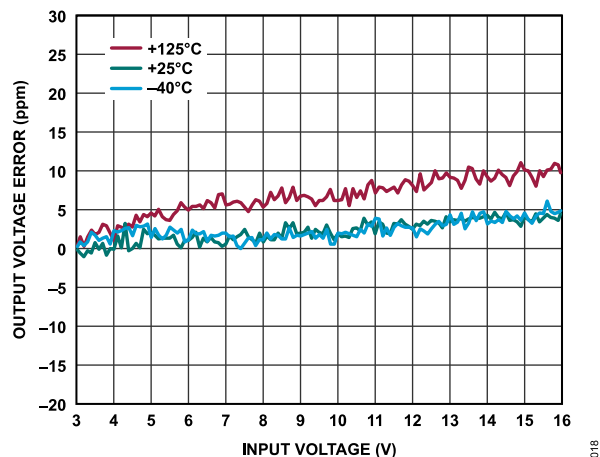*Figure 15. Output Voltage vs. Input Voltage*



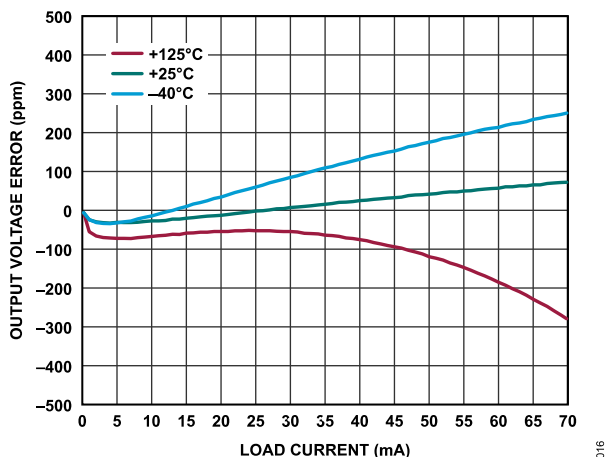*Figure 18. Output Voltage Error vs. Input Voltage*



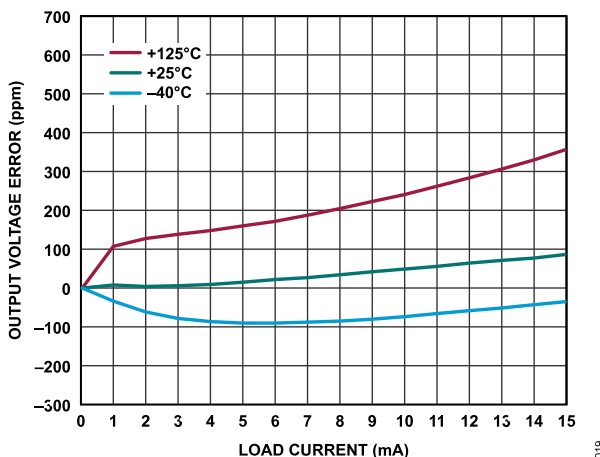*Figure 16. Output Voltage Error vs. Load Current (Source)*



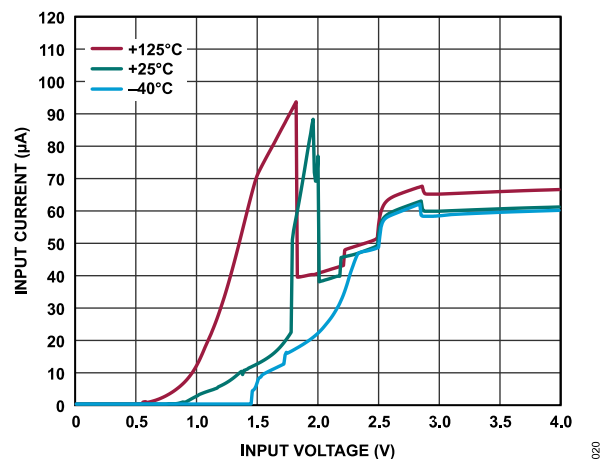*Figure 19. Output Voltage Error vs. Load Current (Sink)*
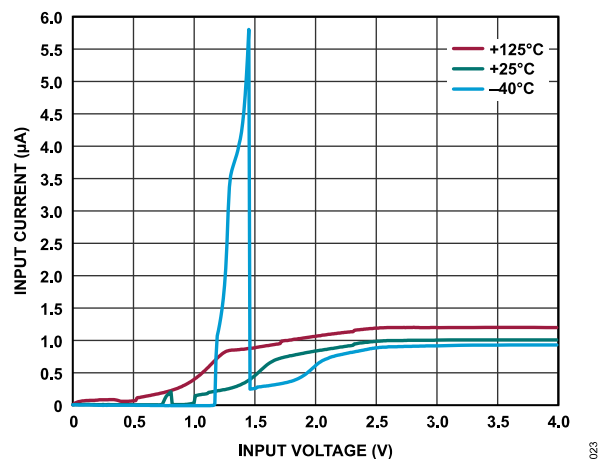


*Figure 17. Input Current vs. Input Voltage*



*Figure 20. Input Current vs. Input Voltage (Shutdown)*
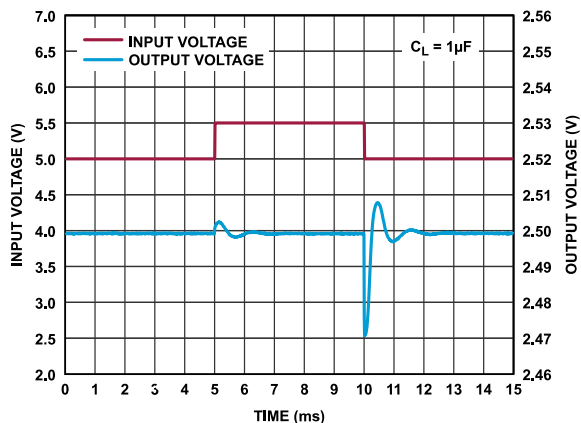
## TYPICAL PERFORMANCE CHARACTERISTICS
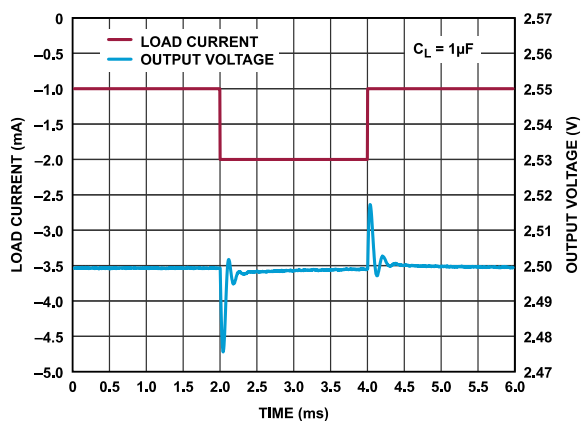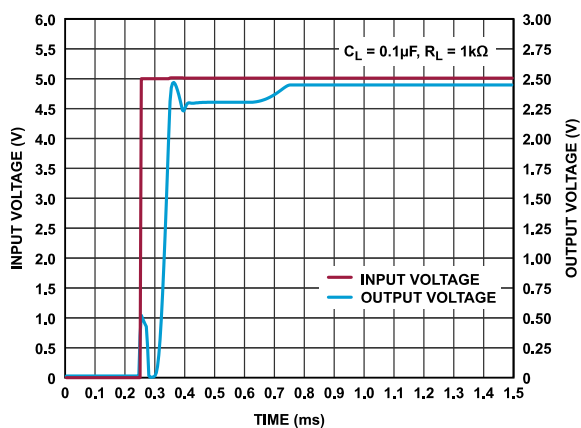


Figure 21. Line Transient Response



Figure 24. Enable Voltage vs. Temperature



Figure 22. Load Transient Response (Source)



Figure 25. Load Transient Response (Sink)
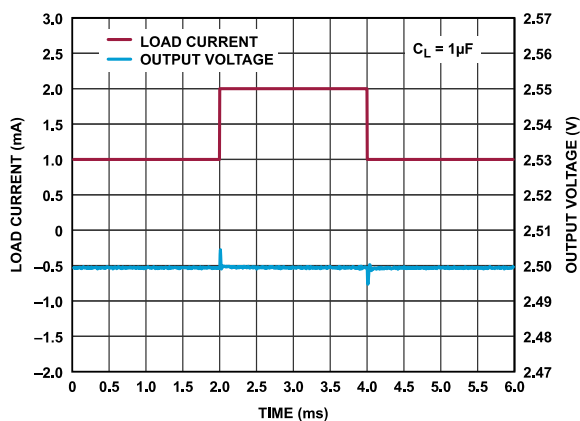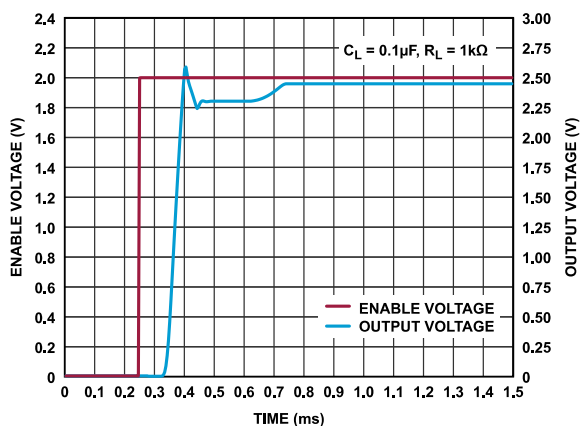


Figure 23. Startup Response (Input)



Figure 26. Startup Response (Enable)

## TYPICAL PERFORMANCE CHARACTERISTICS
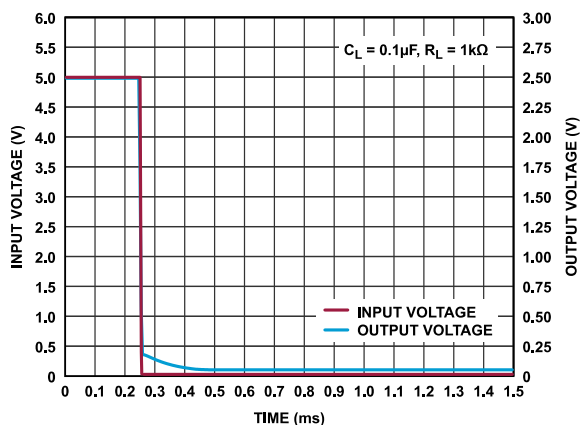


*Figure 27. Shutdown Response (Input)*
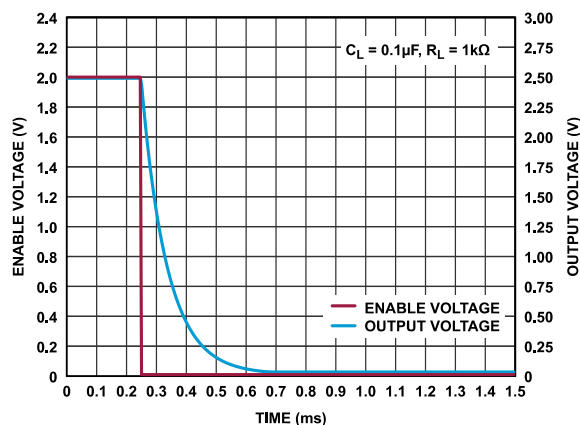


*Figure 30. Shutdown Response (Enable)*
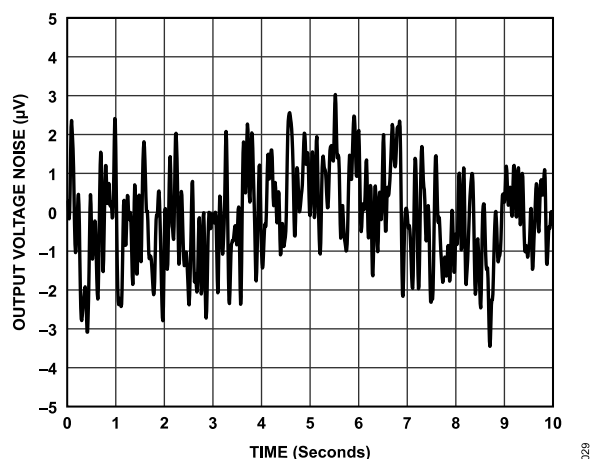


*Figure 28. Voltage Noise (0.1 Hz to 10 Hz)*
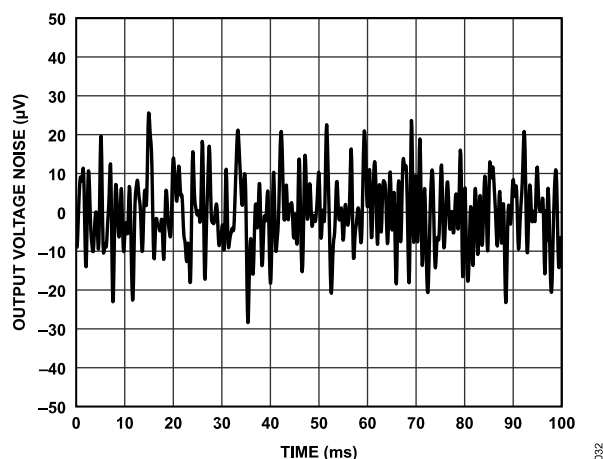


*Figure 31. Voltage Noise (10 Hz to 1 kHz)*
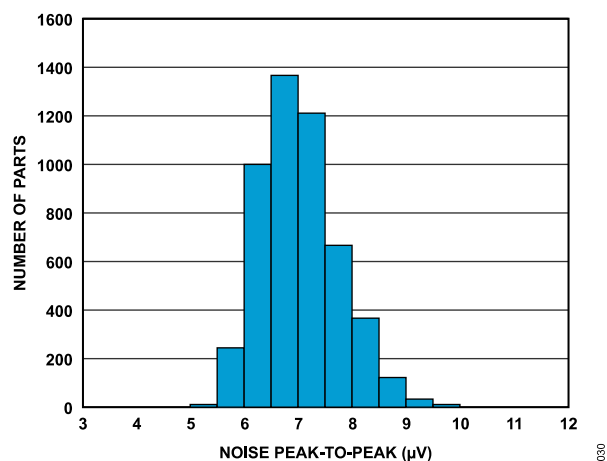


*Figure 29. Voltage Noise (0.1 Hz to 10 Hz) Histogram*
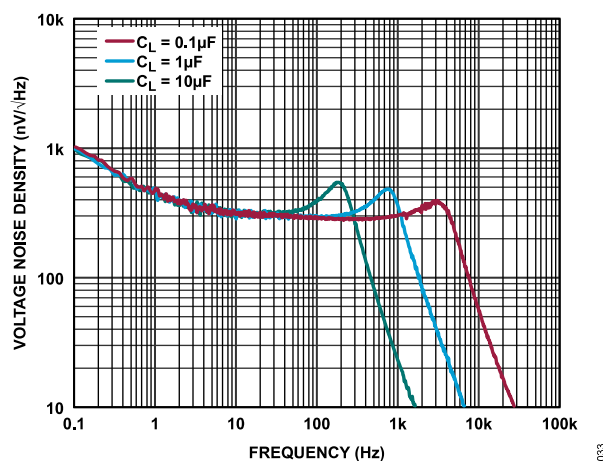


*Figure 32. Spectral Noise Density*

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 33. Output Impedance vs. Frequency



Figure 36. Ripple Rejection Ratio vs. Frequency



Figure 34. Long-Term Drift



Figure 37. Hysteresis



Figure 35. Solder Heat Reflow Shift Histogram



Figure 38. Hysteresis Histogram

## TERMINOLOGY

### Dropout Voltage

Dropout voltage ($V_{DO}$), sometimes referred to as supply voltage headroom or supply output voltage differential, is defined as the minimum voltage differential between the input and output such that the output voltage is maintained to within 0.1% accuracy.
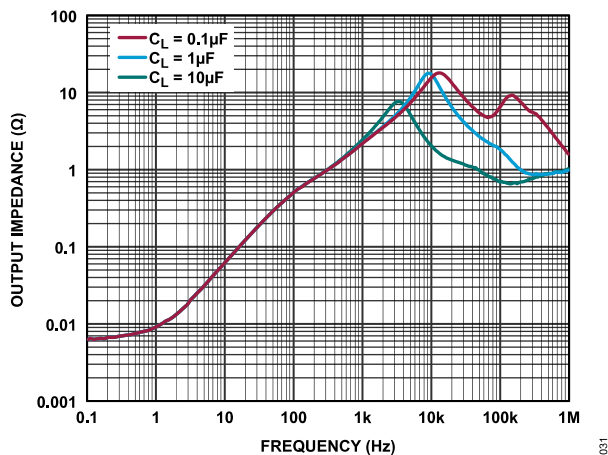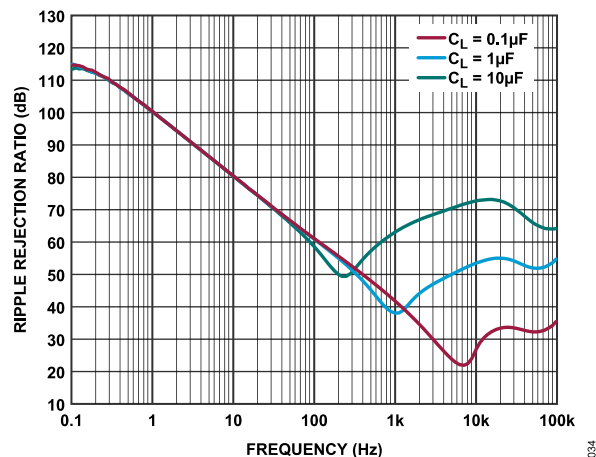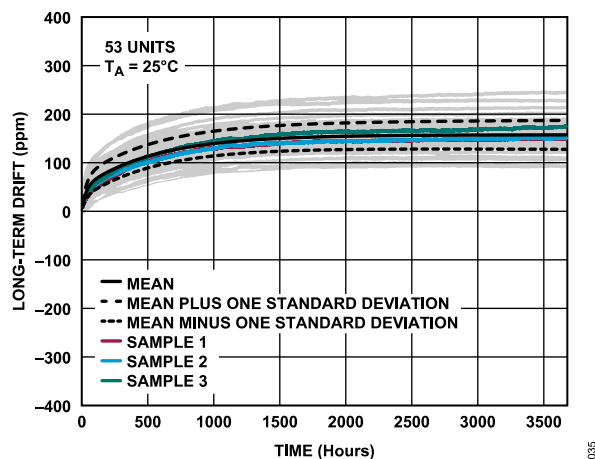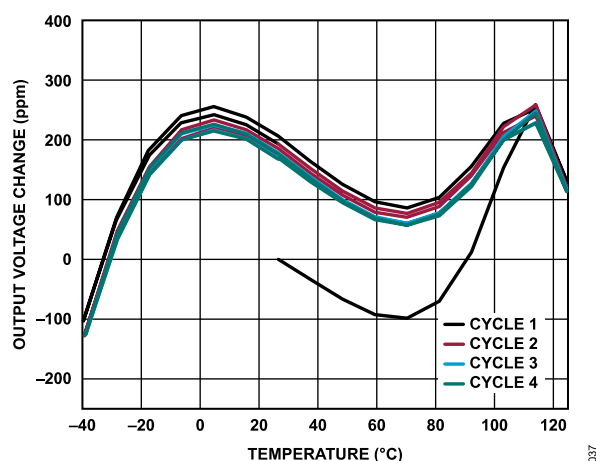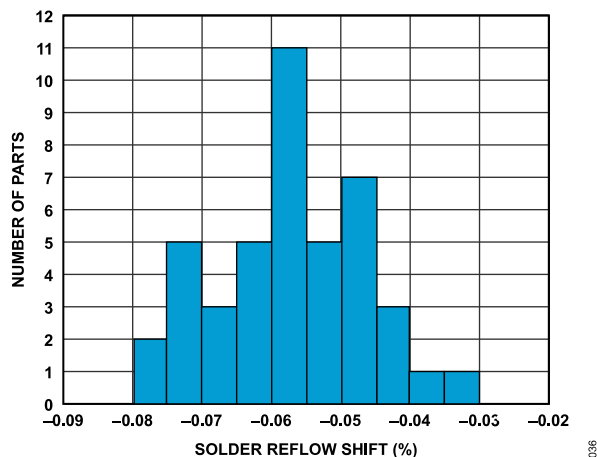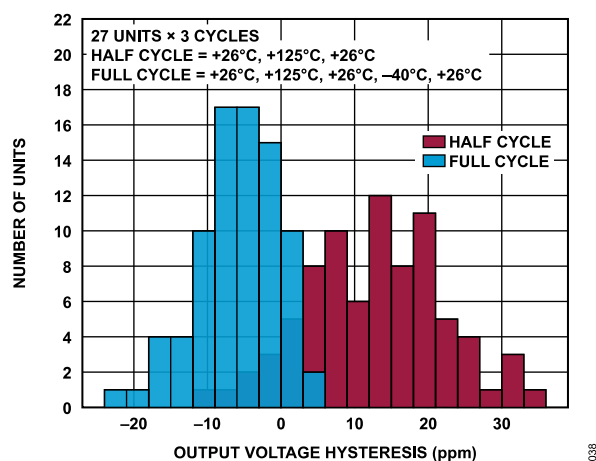
$$V_{DO} = (V_{IN} - V_{OUT})_{MIN}|I_L = Constant$$

Because $V_{DO}$ depends on the current passing through the device, it is always specified for a given load current. In series mode devices, the dropout voltage typically increases proportionally to the load current (see Figure 6).

### Line Regulation

Line regulation refers to the change in output voltage in response to a given change in input voltage and is expressed in percent per volt, ppm per volt, or µV per volt change in input voltage.

### Load Regulation

Load regulation refers to the change in output voltage in response to a given change in load current and is expressed in µV per mA, ppm per mA, or ohms of dc output resistance.

### Solder Heat Resistance Shift

Solder heat resistance shift refers to the permanent shift in output voltage that is induced by exposure to reflow soldering and is expressed as a percentage of the output voltage. This shift is caused by changes in the stress exhibited on the die by the package materials when these materials are exposed to high temperatures. This effect is more pronounced in lead-free soldering processes due to higher reflow temperatures. Solder heat resistance is calculated after three solder reflow cycles to simulate the worst case conditions when assembling a two-sided PCB with surface-mount components with one additional rework cycle. The reflow cycles use the JEDEC standard reflow temperature profile.

### Temperature Coefficient

The temperature coefficient ($TCV_{OUT}$) relates the change in the output voltage to the change in the ambient temperature of the device, as normalized by the output voltage at 25°C. The $TCV_{OUT}$ for the ADR3625 is fully tested over three temperatures: –40°C, +25°C, and +125°C.

### Box Method

The box method is represented by the following equation:

$$TCV_{OUT} = \left| \frac{max(V_{OUT}(T1, T2, T3)) - min(V_{OUT}(T1, T2, T3))}{V_{OUT}(T2) \times (T3 - T1)} \right| \times 10^6$$

where:
$TCV_{OUT}$ is expressed in ppm/°C.
$V_{OUT}(Tx)$ is the output voltage at temperature Tx.
$T1_1 = –40°C$.

$T2_2 = +25°C$.
$T3_3 = +125°C$.

This box method ensures that $TCV_{OUT}$ accurately portrays the maximum difference between any of the three temperatures at which the output voltage of the device is measured.

### Thermal Hysteresis

Thermal hysteresis ($\Delta V_{OUT\_HYS}$) represents the change in the output voltage after the device is exposed to a specified temperature cycle. $\Delta V_{OUT\_HYS}$ is expressed as a difference in ppm from the nominal output.

$$\Delta V_{OUT\_HYS} = \frac{V_{OUT1\_25°C} - V_{OUT2\_25°C}}{V_{OUT1\_25°C}} \times 10^6 (ppm)$$

where:
$V_{OUT1\_25°C}$ is the output voltage at 25°C.
$V_{OUT2\_25°C}$ is the output voltage after temperature cycling.

### Long-Term Drift

Long-term drift ($\Delta V_{OUT\_LTD}$) refers to the shift in the output voltage vs. time. This is expressed as a difference in ppm from the nominal output.

$$\Delta V_{OUT\_LTD} = \left| \frac{V_{OUT}(t_1) - V_{OUT}(t_0)}{V_{OUT}(t_0)} \right| \times 10^6 (ppm)$$

where:
$V_{OUT}(t_0)$ is the $V_{OUT}$ at the starting time of the measurement.
$V_{OUT}(t_1)$ is the $V_{OUT}$ at the end time of the measurement.

## THEORY OF OPERATION

The ADR3625 incorporates a proprietary low noise design and advanced curvature correction technology. Combined with micropower design techniques the ADR3625 has unmatched performance.

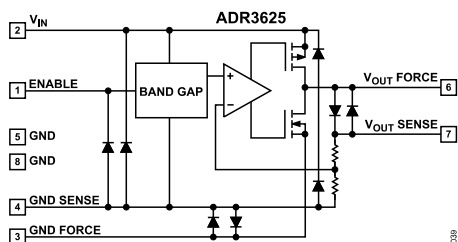The circuit shown in Figure 39 shows the ADR3625 simplified schematic.



Figure 39. ADR3625 Simplified Schematic

## POWER DISSIPATION

While the ADR3625 is a micropower voltage reference, it is capable of sourcing 50 mA and sinking current up to 10 mA of load current at room temperature across the rated input voltage range. However, when used in applications subject to high ambient temperatures, the input voltage and load current must be monitored carefully to ensure that the device does not exceed its maximum allowable power dissipation. To calculate the maximum allowable power dissipation of the device, use the following equation:

$$P_D = \frac{T_J - T_A}{\theta_{JA}}$$

where:
$P_D$ is the device power dissipation.
$T_J$ is the device junction temperature.
$T_A$ is the ambient temperature.

The ADR3625 has a thermal resistance of 132.5°C/W for the 8-lead MSOP. A curve that illustrates allowed power dissipation vs. temperature for the MSOP is shown in Figure 40. The power dissipation of the ADR3625 as a function of the input voltage is shown in Figure 41. The top curve shows power dissipation with a 50 mA load, and the bottom curve shows power dissipation with no load. When operated within its specified limits of $V_{IN}$ = 16 V and sourcing 50 mA, the ADR3625 consumes about 800 mW at room temperature. The power derating curve in Figure 40 shows that the ADR3625 can only safely dissipate 120 mW at 125°C, which is less than its maximum power output. Care must be taken when designing the circuit so that the maximum junction temperature is not exceeded. For best performance, keep the junction temperature less than 150°C.

The ADR3625 includes output current-limit circuitry, as well as thermal limit circuitry, to protect the reference from damage in the event of excessive power dissipation. The ADR3625 is protected from damage by a thermal shutdown circuit. However, changes in performance can occur as a result of operating at above the maximum rating.
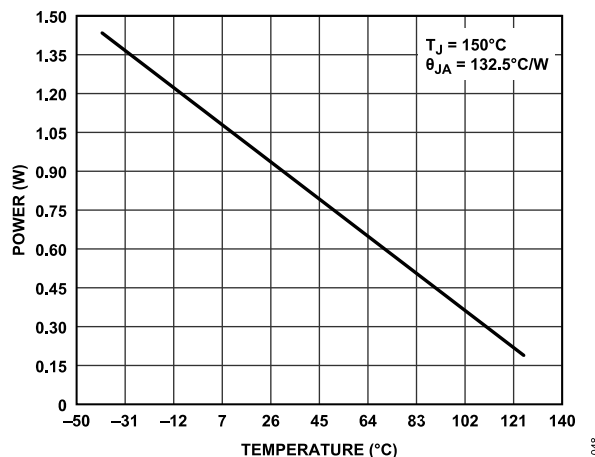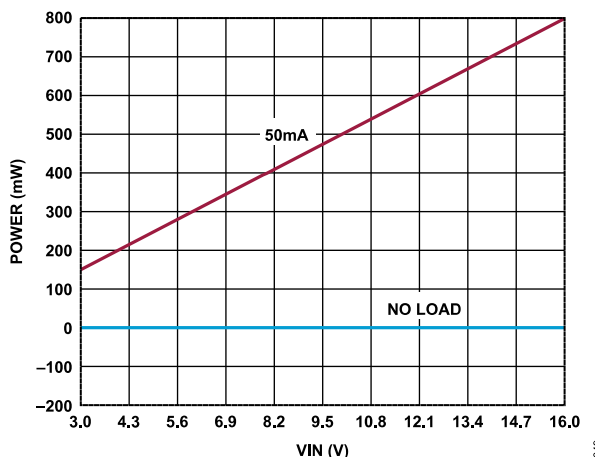


Figure 40. Maximum Allowed Power Dissipation



Figure 41. Typical Power Dissipation

The safe operating area is the voltage, current, and temperature conditions where the device can operate reliably (see Figure 42). The safe operating area takes into account the ambient temperature and power dissipated in the 8-lead MSOP.
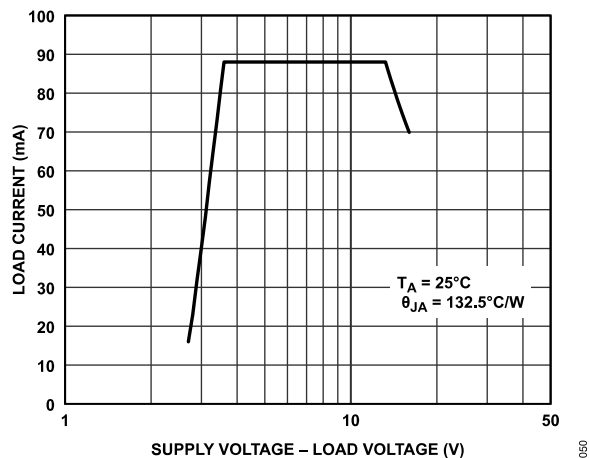


Figure 42. Safe Operating Area

## THEORY OF OPERATION

### INTERNAL PROTECTION

The ADR3625 has two internal protection circuits for monitoring the output current and internal junction temperature.

The ADR3625 has a current-limit circuit that limits the output source current in the event of a short circuit from the $V_{OUT}$ FORCE pin to ground. The limit is set to 90 mA (typical) and does not vary much over temperature or input voltage.

An overtemperature shutdown circuit disables the output source current when the internal junction temperature reaches 178°C. There is 3°C of hysteresis. Once the junction temperature reduces beyond the hysteresis, the output drive circuit reenables. Degradation can occur or reliability can be affected when the junction temperature of the device exceeds 150°C.

### LONG-TERM DRIFT

The stability of a precision signal path over its lifetime, or between calibration procedures, is dependent on the long-term stability of the analog components in its path, such as op amps, references, and data converters. To help system designers predict the long-term drift of the circuits that use the ADR3625, Analog Devices measured the output voltage of multiple units for more than 4500 hours (more than 6 months) using a high precision measurement system, including an ultrastable oil bath. To replicate the real-world system performance, the devices under test (DUTs) were soldered onto an FR4 PCB using a standard reflow profile (as defined in the JEDEC J-STD-020D standard), rather than testing them in sockets. This manner of testing is important because expansion and contraction of the PCB can apply stress to the IC package and contribute to shifts in the offset voltage.

Note that early life drift (0 hours to 250 hours) accounts for 50% of the total drift observed over 4500 hours, as shown in Figure 43. The first 1000 hours account for the 80% of the total drift, and the remaining 3500 hours account for the remaining 20% of the drift. Thus, the early life drift is the dominant contributor, whereas the drift after 1000 hours is significantly lower.
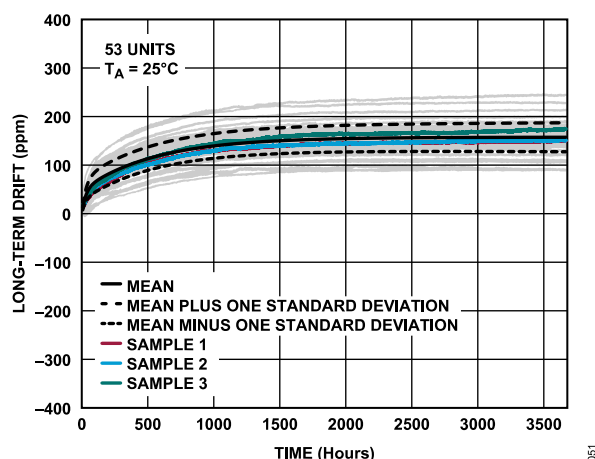


*Figure 43. Long-Term Drift*

### THERMAL HYSTERESIS

In addition to stability over time, as described in the Long-Term Drift section, it is useful to know the thermal hysteresis, that is, the stability vs. cycling of temperature. Thermal hysteresis is an important parameter because it tells the system designer how closely the signal returns to its starting amplitude after the ambient temperature changes and the subsequent return to room temperature. Figure 44 shows the change in output voltage as the temperature cycles four times from room temperature to +125°C to −40°C and back to room temperature.

Other than the first full cycle, the output hysteresis is typically −7 ppm. The histogram in Figure 45 shows that the hysteresis is larger when the device cycles through only a half cycle, from room temperature to 125°C and back to room temperature, typically 15 ppm.
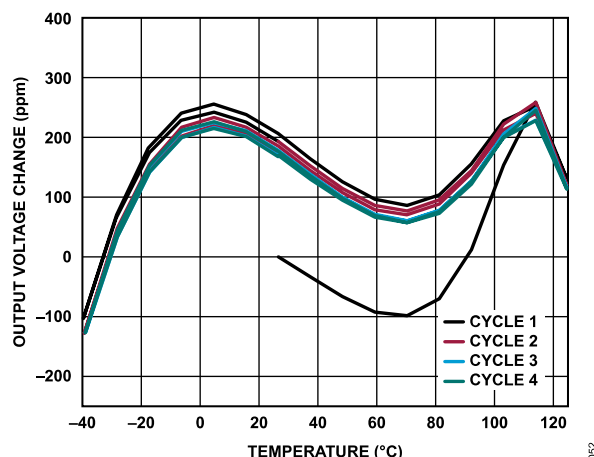


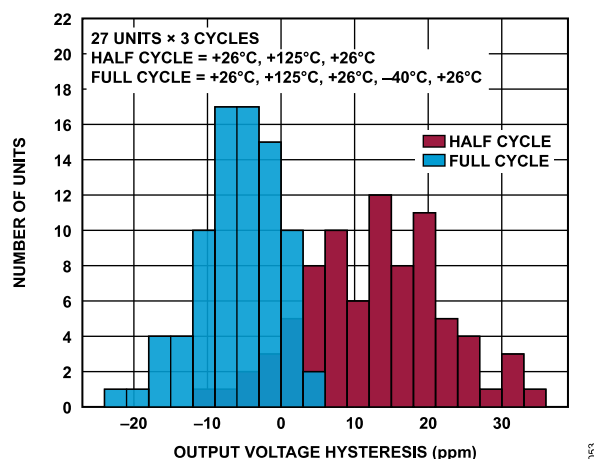*Figure 44. Change in Output Voltage over Four Full Temperature Cycle*



*Figure 45. Output Voltage Hysteresis Histogram (−40°C to +125°C)*

## THEORY OF OPERATION

### POWER CYCLE HYSTERESIS

By power cycling large numbers of samples, the power cycle hysteresis can be determined. To keep this measurement independent of other variables and environmental effects, the power cycle testing was performed using a high precision measurement system, including an ultrastable oil bath.

Figure 46 shows the power cycle hysteresis. The units were powered down for approximately four hours and then powered up. The ADR3625 does not have any power cycle hysteresis even after a long power-down period, making these devices suitable for equipment that must maintain its calibration accuracy between power cycles.
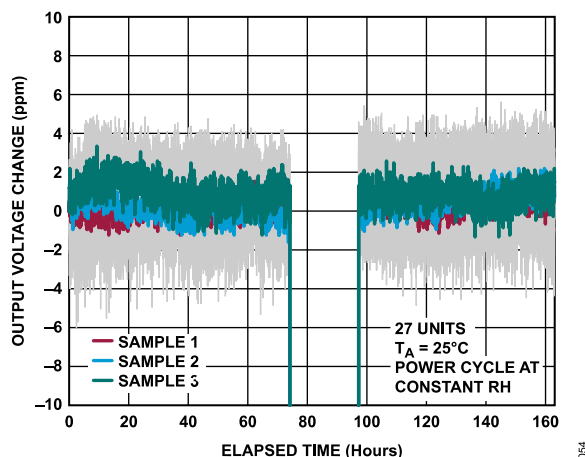


Figure 46. Power Cycle Hysteresis

### HUMIDITY SENSITIVITY

The ADR3625 is packaged in an MSOP. However, moisture absorption from the air into the package changes the internal mechanical stresses on the die, causing shifts in the output voltage. Figure 47 shows the effects of a step change in relative humidity on the output voltage over time. The humidity chamber is maintained at an ambient temperature of +25°C, while the relative humidity undergoes a step change from 30% to 70%. The relative humidity is maintained at 70% for the duration of the testing. Note that the output voltage shifts quickly compared to the overall settling time, following the step change in relative humidity.
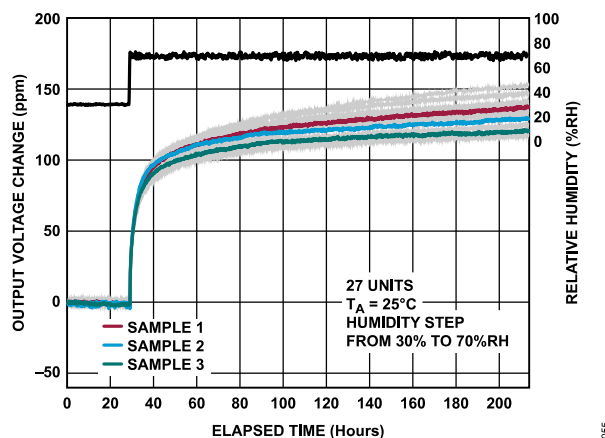


Figure 47. Change in Output Voltage vs. Time After Humidity Step (30% to 70% Relative Humidity (RH))

## APPLICATIONS INFORMATION

### BASIC VOLTAGE REFERENCE CONNECTION

The basic configuration for the ADR3625 reference is shown in Figure 48. For detailed information on connecting the bypass capacitors, see the Input and Output Capacitors section.
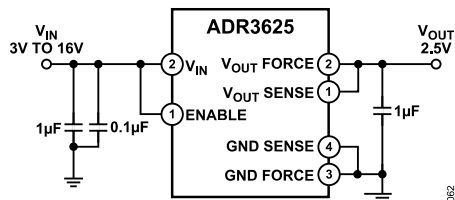


*Figure 48. Basic Reference Connection*

### INPUT AND OUTPUT CAPACITORS

#### Input Capacitors

A 1 µF to 10 µF electrolytic or ceramic capacitor can be connected to the input to improve transient response in applications where the supply voltage can fluctuate. It is recommended to connect an additional 0.1 µF ceramic capacitor in parallel to reduce supply noise.

#### Output Capacitors

A $C_{OUT}$ is required for stability and to filter out low level voltage noise. The minimum value of $C_{OUT}$ is 0.1 µF and can go as high as 10 µF for stability.

An additional 1 µF to 10 µF electrolytic or ceramic capacitor can be added in parallel to improve transient performance in response to sudden changes in load current.

The larger the output capacitor, the lower the bandwidth of the output is, thus lowering the noise. However, increasing the output capacitor increases the settling time and decreases the response rate.

The ADR3625 is stable with a variety of capacitor types, including ceramic, electrolytic (including polymer), tantalum, and film. Small surface-mount capacitors have low effective series resistance (ESR) and take up little board space. Place and connect the output capacitor as close as possible to the $V_{OUT}$ FORCE pin. Use low ESR capacitors.

### START-UP TIME

The start-up time is determined by the output capacitance and output load current. Figure 49 shows an example of the start-up response when stepping the supply voltage and Figure 50 shows an example of the start-up response when stepping the enable voltage.
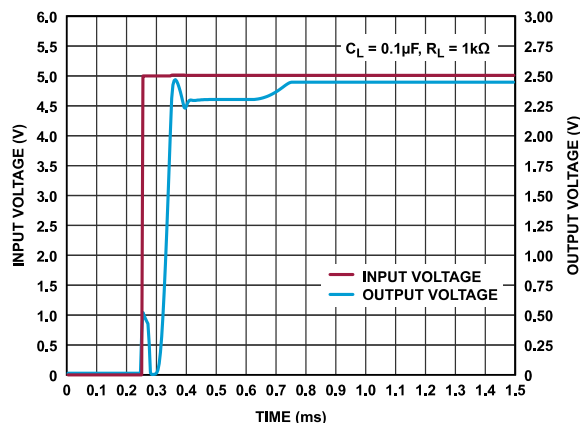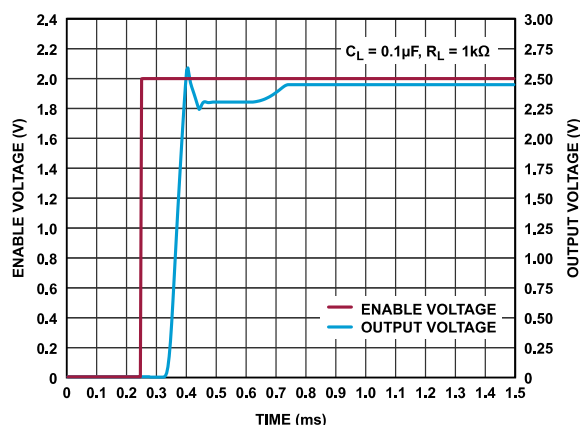


*Figure 49. Star-Up Response (Input)*



*Figure 50. Start-Up Response (Enable)*

## APPLICATIONS INFORMATION

### SETTLING TIME

The ADR3625 can take up to 16 V supply, source 50 mA, and sink 10 mA. The output settling time is dependent upon the output capacitance and load current. Figure 51 through Figure 54 show the transient response of the device at different conditions.
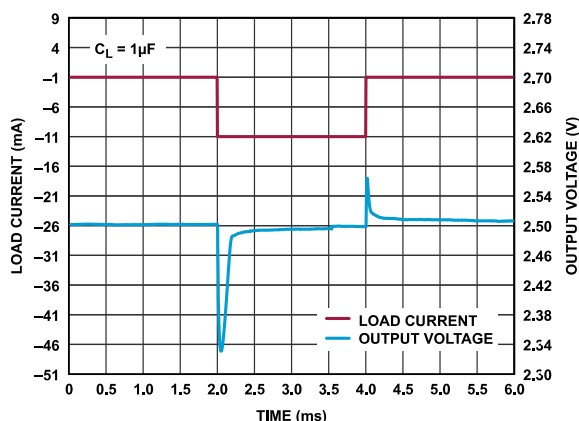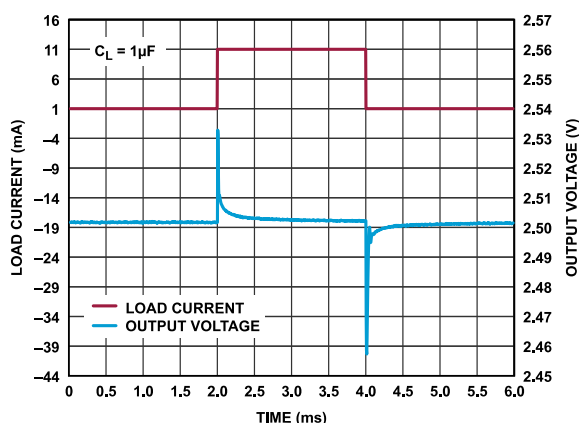


*Figure 51. 10 mA Sourcing Response*
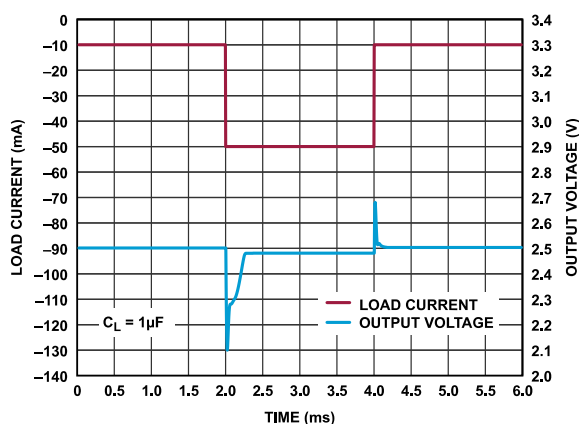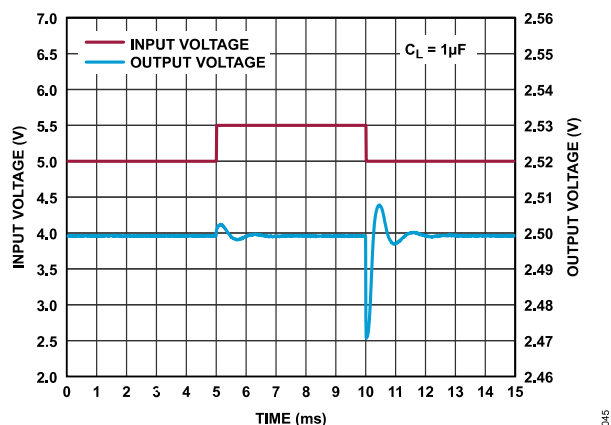


*Figure 52. 10 mA Sinking Response*



*Figure 53. 50 mA Sourcing Response*



*Figure 54. Output Response with a 500 mV Step on $V_{IN}$*

### ENABLE PIN

The ENABLE pin is compatible with 1.8 V thresholds and has an internal active pull-up. When powered down, the supply current is only 1.5 µA typical.

There is no diode connected between the ENABLE pin and $V_{IN}$. The ENABLE pin can be driven high when $V_{IN}$ is low without drawing current or powering the device through the ENABLE pin as can happen with other references.

### PCB LAYOUT

The mechanical stress of soldering a surface-mount voltage refer-ence to a PCB can cause the output voltage to shift and the temperature coefficient to change. These two changes are not correlated. For example, the voltage may shift but the temperature coefficient may not.

To reduce the effects of the stress-related shifts, mount the refer-ence near the short edge of the PCB or in a corner. In addition, slots can be cut into the PCB on two sides of the device. For more information, see Application Note AN82.

Connect the output capacitor close to the $V_{OUT}$ FORCE pin. For good load regulation, connect the $V_{OUT}$ SENSE pin directly at the load, as shown in Figure 55.

## APPLICATIONS INFORMATION
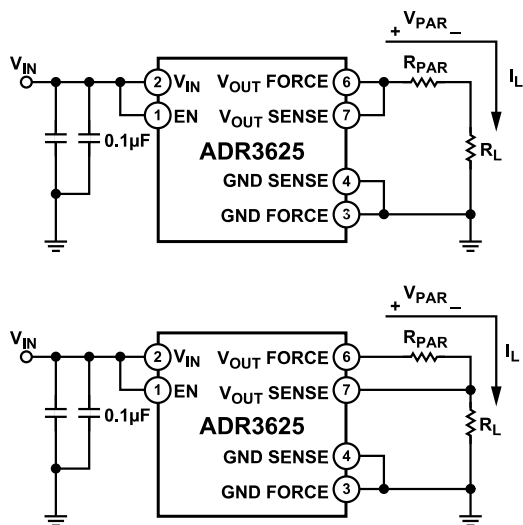


*Figure 55. Output Force and Sense*

Avoid adding parasitic resistance between the load and the $V_{OUT}$ SENSE pin. Minimize the metal parasitic in the $V_{OUT}$ FORCE line to the load to maintain a low dropout voltage.

The GND_FORCE line carries the load sinking current. Connect the GND_SENSE line directly to the bottom of the load as shown in Figure 56.
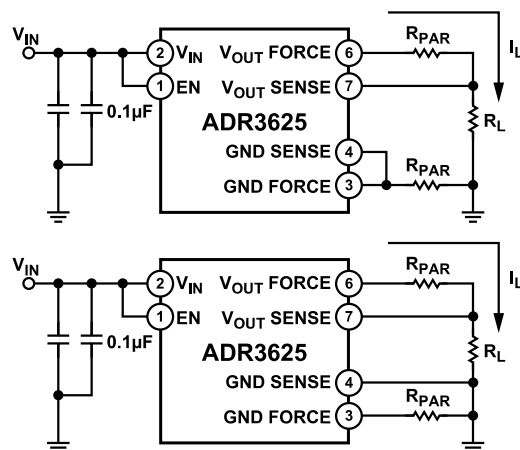


*Figure 56. Ground Force and Sense*

## SAMPLE APPLICATIONS

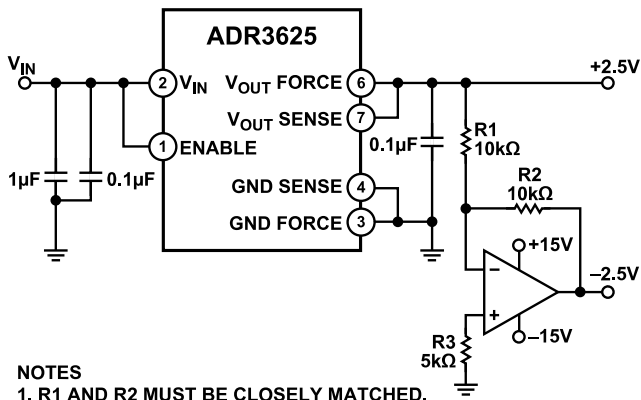The ADR3625 can be used in various applications, some of which are shown as follows.


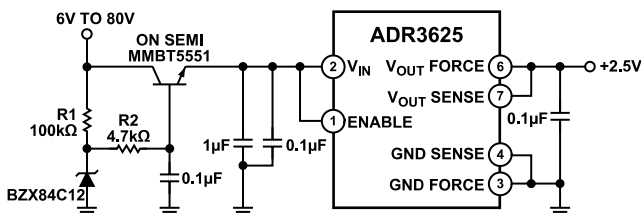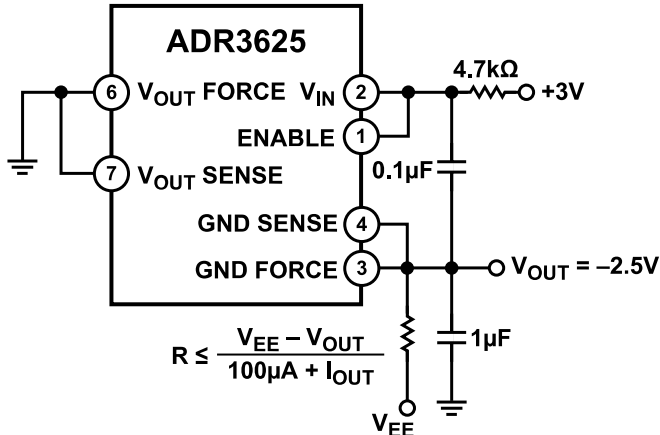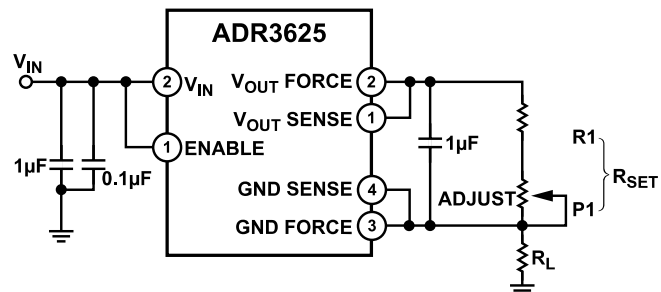
*Figure 57. Bipolar Output Reference*



$$V_{IN} \geq I_{OUT} \times R_L \text{ (MAX)} + V_{IN} \text{ (MIN)}$$

$$I_{OUT} = \frac{V_{OUT}}{R_{SET}} + I_Q$$

$$\frac{V_{OUT}}{R_{SET}} \gg I_Q$$

FOR EXAMPLE: $V_{OUT}$ = 5V
$I_{OUT}$ = 5mA
R1 = 953Ω
P1 = 100Ω, 10-TURN

NOTE: $R_{SET}$ IS THE SETTING RESISTOR

*Figure 60. Constant Current*



*Figure 58. Extended Supply Range*



$$R \leq \frac{V_{EE} - V_{OUT}}{100\mu A + I_{OUT}}$$

NOTE: $V_{EE}$ IS THE VOLTAGE SUPPLY, AND $I_{OUT}$ IS THE OUTPUT CURRENT

*Figure 59. Negative Voltage Output*

## OUTLINE DIMENSIONS
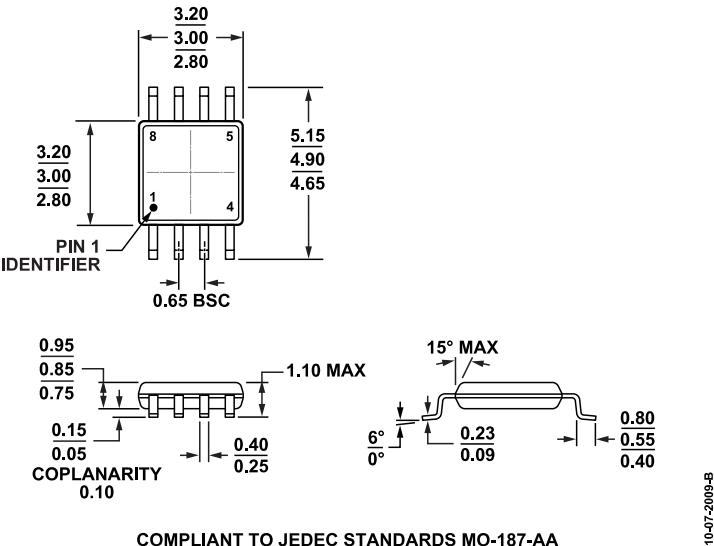


*Figure 61. 8-Lead Mini Small Outline Package [MSOP]*
*(RM-8)*
*Dimensions shown in millimeters*

COMPLIANT TO JEDEC STANDARDS MO-187-AA

Updated: October 15, 2021

## ORDERING GUIDE

| Model[1] | Temperature Range | Package Description | Packing Quantity | Package Option | Marking Code |
|---|---|---|---|---|---|
| ADR3625ARMZ | -40°C to +125°C | 8-Lead MSOP | Tube, 50 | RM-8 | FJ |
| ADR3625ARMZ-R7 | -40°C to +125°C | 8-Lead MSOP | Reel, 1000 | RM-8 | FJ |
| ADR3625BRMZ | -40°C to +125°C | 8-Lead MSOP | Tube, 50 | RM-8 | FK |
| ADR3625BRMZ-R7 | -40°C to +125°C | 8-Lead MSOP | Reel, 1000 | RM-8 | FK |

[1] Z = RoHS Compliant Part.

## EVALUATION BOARDS

*Table 7.*

| Model[1] | Description |
|---|---|
| EVAL-ADR3625EBZ | ADR3625 Evaluation Board |

[1] Z = RoHS-Compliant Part.

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