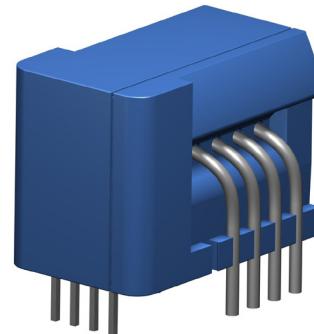


## Current transducer CKSR xx-NP

$I_{PN} = 6, 15, 25, 50 \text{ A}$

Ref: CKSR 6-NP, CKSR 15-NP, CKSR 25-NP, CKSR 50-NP

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



### Features

- Closed loop (compensated) multi-range current transducer
- Voltage output
- Single supply
- Compact design for PCB mounting.

### Advantages

- Very low temperature coefficient of offset
- Very good  $du/di$  immunity
- Higher creepage distance/clearance
- Reduced height
- Reference pin with two modes: Ref IN and Ref OUT
- Extended measuring range for unipolar measurement.

### Applications

- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Solar inverters.

### Standards

- EN 50178: 1997
- IEC 60950-1: 2006
- IEC 61010-1: 2010
- IEC 61326-1: 2012
- UL 508: 2010.

### Application Domains

- Industrial
- Automotive (list of additional tests available at [LEM\\_Auto\\_Tech\\_Support@lem.com](mailto:LEM_Auto_Tech_Support@lem.com)).

**Safety**

Caution

If the device is used in a way that is not specified by the manufacturer, the protection provided by the device may be compromised. Always inspect the electronics unit and connecting cable before using this product and do not use it if damaged. Mounting assembly shall guarantee the maximum primary conductor temperature, fulfill clearance and creepage distance, minimize electric and magnetic coupling, and unless otherwise specified can be mounted in any orientation.



Caution, risk of electrical shock

This transducer must be used in limited-energy secondary circuits SELV according to IEC 61010-1, in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating specifications.

Use caution during installation and use of this product; certain parts of the module can carry hazardous voltages and high currents (e.g. power supply, primary conductor).

Ignoring this warning can lead to injury and/or cause serious damage.

De-energize all circuits and hazardous live parts before installing the product.

All installations, maintenance, servicing operations and use must be carried out by trained and qualified personnel practicing applicable safety precautions.

This transducer is a build-in device, whose hazardous live parts must be inaccessible after installation.

This transducer must be mounted in a suitable end-enclosure.

Besides make sure to have a distance of minimum 30 mm between the primary terminals of the transducer and other neighboring components.

Main supply must be able to be disconnected.

Never connect or disconnect the external power supply while the primary circuit is connected to live parts.

Never connect the output to any equipment with a common mode voltage to earth greater than 30 V.

Always wear protective clothing and gloves if hazardous live parts are present in the installation where the measurement is carried out.

This transducer is a built-in device, not intended to be cleaned with any product. Nevertheless if the user must implement cleaning or washing process, validation of the cleaning program has to be done by himself.

When defining soldering process, please use no cleaning process only.



ESD susceptibility

The product is susceptible to be damaged from an ESD event and the personnel should be grounded when handling it.

Do not dispose of this product as unsorted municipal waste. Contact a qualified recycler for disposal.

Although LEM applies utmost care to facilitate compliance of end products with applicable regulations during LEM product design, use of this part may need additional measures on the application side for compliance with regulations regarding EMC and protection against electric shock. Therefore LEM cannot be held liable for any potential hazards, damages, injuries or loss of life resulting from the use of this product.



Underwriters Laboratory Inc. recognized component

## Absolute maximum ratings

CKSR xx-NP

Parameter	Symbol	Unit	Value
Maximum supply voltage	$U_{C\max}$	V	7
Maximum primary conductor temperature	$T_{B\max}$	°C	110
Maximum steady state primary current	$I_{P\max}$	A	$20 \times I_{P_N}$
Maximum ESD rating, Human Body Model (HBM)	$U_{ESD\max}$	kV	4

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

## UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 1

### Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT - Edition 11 - Revision Date 2011/08/01
- UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT - Edition 17 - Revision Date 2010/04/15

### Ratings

Parameter	Symbol	Unit	Value
Primary involved potential		V AC/DC	1000
Max surrounding air temperature	$T_A$	°C	105
Primary current	$I_P$	A	According to series primary currents
Secondary supply voltage	$U_C$	V DC	5
Output voltage	$U_{out}$	V	0 to 5

### Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

- 1 - These devices must be mounted in a suitable end-use enclosure.
- 4 - CKSR series intended to be mounted on the printed circuit wiring board of the end-use equipment (with a minimum CTI of 100).
- 5 - CKSR series shall be used in a pollution degree 2.
- 8 - Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).
- 11 - CKSR series: based on results of temperature tests, in the end-use application, a maximum of 100 °C cannot be exceeded at soldering joint between primary coil pin and soldering point (corrected to the appropriate evaluated max. surrounding air).

### Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

**Insulation coordination**

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_d$	kV	4.3	
Impulse withstand voltage 1.2/50 $\mu$ s	$U_{Ni}$	kV	8	
Partial discharge RMS test voltage ( $q_m < 10$ pC)	$U_t$	V	1000	
Clearance distance (pri. - sec.)	$d_{Cl}$	mm	8.2	Shortest distance through air
Creepage distance (pri. - sec.)	$d_{Cp}$	mm	8.2	Shortest path along device body
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	
Application example	-	-	300 V	Reinforced insulation, non uniform field according to IEC 61010-1 CAT III PD2
Application example	-	-	600 V	Reinforced insulation, non uniform field according to EN 50178 CAT III PD2
Application example	-	-	1000 V	Simple insulation, non uniform field according to EN 50178 CAT III PD2

**Environmental and mechanical characteristics**

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	$T_A$	°C	-40		105	
Ambient storage temperature	$T_{A\ st}$	°C	-55		105	
Mass	$m$	g		9		

At  $T_A = 25^\circ\text{C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1$  turn,  $R_L = 10\text{ k}\Omega$ , internal reference, unless otherwise noted (see Min, Max, typ. definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	$I_{P_N}$	A		6		Apply derating according to fig. 25
Primary current, measuring range	$I_{P_M}$	A	-20		20	
Number of primary turns	$N_p$	-		1, 2, 3, 4		
Supply voltage	$U_C$	V	4.75	5	5.25	
Current consumption	$I_C$	mA		$15 + \frac{I_p(\text{mA})}{N_s}$	$20 + \frac{I_p(\text{mA})}{N_s}$	$N_s = 1731$ turns
Reference voltage @ $I_p = 0\text{ A}$	$U_{\text{ref}}$	V	2.495	2.5	2.505	Internal reference
External reference voltage	$U_{\text{ref}}$	V	0		4	
Output voltage	$U_{\text{out}}$	V	0.375		4.625	
Output voltage @ $I_p = 0\text{ A}$	$U_{\text{out}}$	V		$U_{\text{ref}}$		
Electrical offset voltage	$U_{OE}$	mV	-5.3		5.3	100 % tested $U_{\text{out}} - U_{\text{ref}}$
Electrical offset current referred to primary	$I_{OE}$	mA	-51		51	100 % tested
Temperature coefficient of $U_{\text{ref}}$	$TCU_{\text{ref}}$	ppm/K		±5	±50	Internal reference
Temperature coefficient of $U_{\text{out}}$ @ $I_p = 0\text{ A}$	$TCU_{\text{out}}$	ppm/K		±6	±14	ppm/K of 2.5 V -40 °C ... 105 °C (at ±6 Sigma)
Nominal sensitivity	$S_N$	mV/A		104.2		$625\text{ mV}/I_{P_N}$
Sensitivity error	$\varepsilon_S$	%	-0.7		0.7	100 % tested
Temperature coefficient of $S$	$TCS$	ppm/K			±40	-40 °C ... 105 °C
Linearity error	$\varepsilon_L$	% of $I_{P_N}$	-0.1		0.1	
Magnetic offset current @ $I_p = 0$ and specified $R_M$ , after an overload of $10 \times I_{P_N}$	$I_{OM}$	A	-0.1		0.1	
Noise current spectral density 100 Hz ... 100 kHz referred to primary	$i_{no}$	$\mu\text{A}/\text{Hz}^{\frac{1}{2}}$		20		$R_L = 1\text{ k}\Omega$
Peak-peak output ripple at oscillator frequency $f = 450\text{ kHz}$ (typ.)	-	mV		40	160	$R_L = 1\text{ k}\Omega$
Delay time to 10 % to the final output value for $I_{P_N}$ step	$t_{D10}$	μs			0.3	$R_L = 1\text{ k}\Omega$ $di/dt = 18\text{ A}/\mu\text{s}$
Delay time to 90 % to the final output value for $I_{P_N}$ step	$t_{D90}$	μs			0.3	$R_L = 1\text{ k}\Omega$ $di/dt = 18\text{ A}/\mu\text{s}$
Frequency bandwidth (±1 dB)	$BW$	kHz	200			$R_L = 1\text{ k}\Omega$
Frequency bandwidth (±3 dB)	$BW$	kHz	300			$R_L = 1\text{ k}\Omega$
Total error	$\varepsilon_{\text{tot}}$	% of $I_{P_N}$			1.7	
Total error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon_{\text{tot}}$	% of $I_{P_N}$			2.2 (2.4)	
Error	$\varepsilon$	% of $I_{P_N}$			0.8	
Error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon$	% of $I_{P_N}$			1.4 (1.6)	

**Electrical data CKSR 15-NP**

At  $T_A = 25^\circ\text{C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1$  turn,  $R_L = 10\text{ k}\Omega$ , internal reference, unless otherwise noted (see Min, Max, typ. definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	$I_{PN}$	A		15		Apply derating according to fig. 26
Primary current, measuring range	$I_{PM}$	A	-51		51	
Number of primary turns	$N_p$	-		1, 2, 3, 4		
Supply voltage	$U_C$	V	4.75	5	5.25	
Current consumption	$I_C$	mA		$15 + \frac{I_p(\text{mA})}{N_s}$	$20 + \frac{I_p(\text{mA})}{N_s}$	$N_s = 1731$ turns
Reference voltage @ $I_p = 0\text{ A}$	$U_{ref}$	V	2.495	2.5	2.505	Internal reference
External reference voltage	$U_{ref}$	V	0		4	
Output voltage	$U_{out}$	V	0.375		4.625	
Output voltage @ $I_p = 0\text{ A}$	$U_{out}$	V		$U_{ref}$		
Electrical offset voltage	$U_{OE}$	mV	-2.21		2.21	100 % tested $U_{out} - U_{ref}$
Electrical offset current referred to primary	$I_{OE}$	mA	-53		53	100 % tested
Temperature coefficient of $U_{ref}$	$TCU_{ref}$	ppm/K		±5	±50	Internal reference
Temperature coefficient of $U_{out}$ @ $I_p = 0\text{ A}$	$TCU_{out}$	ppm/K		±2.3	±6	ppm/K of 2.5 V -40 °C ... 105 °C (at ±6 Sigma)
Nominal sensitivity	$S_N$	mV/A		41.67		625 mV/ $I_{PN}$
Sensitivity error	$\varepsilon_S$	%	-0.7		0.7	100 % tested
Temperature coefficient of $S$	$TCS$	ppm/K			±40	-40 °C ... 105 °C
Linearity error	$\varepsilon_L$	% of $I_{PN}$	-0.1		0.1	
Magnetic offset current @ $I_p = 0$ and specified $R_M$ , after an overload of $10 \times I_{PN}$	$I_{OM}$	A	-0.1		0.1	
Noise current spectral density 100 Hz ... 100 kHz referred to primary	$i_{no}$	$\mu\text{A}/\text{Hz}^{\frac{1}{2}}$		20		$R_L = 1\text{ k}\Omega$
Peak-peak output ripple at oscillator frequency $f = 450\text{ kHz}$ (typ.)	-	mV		15	60	$R_L = 1\text{ k}\Omega$
Delay time to 10 % to the final output value for $I_{PN}$ step	$t_{D10}$	μs			0.3	$R_L = 1\text{ k}\Omega$ $di/dt = 44\text{ A}/\mu\text{s}$
Delay time to 90 % to the final output value for $I_{PN}$ step	$t_{D90}$	μs			0.3	$R_L = 1\text{ k}\Omega$ $di/dt = 44\text{ A}/\mu\text{s}$
Frequency bandwidth (±1 dB)	$BW$	kHz	200			$R_L = 1\text{ k}\Omega$
Frequency bandwidth (±3 dB)	$BW$	kHz	300			$R_L = 1\text{ k}\Omega$
Total error	$\varepsilon_{tot}$	% of $I_{PN}$			1.2	
Total error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon_{tot}$	% of $I_{PN}$			1.5 (1.7)	
Error	$\varepsilon$	% of $I_{PN}$			0.8	
Error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon$	% of $I_{PN}$			1.2 (1.3)	

## Electrical data CKSR 25-NP

## CKSR xx-NP

At  $T_A = 25^\circ\text{C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1$  turn,  $R_L = 10\text{ k}\Omega$ , internal reference, unless otherwise noted (see Min, Max, typ. definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	$I_{PN}$	A		25		Apply derating according to fig. 27
Primary current, measuring range	$I_{PM}$	A	-85		85	
Number of primary turns	$N_p$	-		1, 2, 3, 4		
Supply voltage	$U_C$	V	4.75	5	5.25	
Current consumption	$I_C$	mA		$15 + \frac{I_p(\text{mA})}{N_s}$	$20 + \frac{I_p(\text{mA})}{N_s}$	$N_s = 1731$ turns
Reference voltage @ $I_p = 0\text{ A}$	$U_{ref}$	V	2.495	2.5	2.505	Internal reference
External reference voltage	$U_{ref}$	V	0		4	
Output voltage	$U_{out}$	V	0.375		4.625	
Output voltage @ $I_p = 0\text{ A}$	$U_{out}$	V		$U_{ref}$		
Electrical offset voltage	$U_{OE}$	mV	-1.35		1.35	100 % tested $U_{out} - U_{ref}$
Electrical offset current referred to primary	$I_{OE}$	mA	-54		54	100 % tested
Temperature coefficient of $U_{ref}$	$TCU_{ref}$	ppm/K		±5	±50	Internal reference
Temperature coefficient of $U_{out}$ @ $I_p = 0\text{ A}$	$TCU_{out}$	ppm/K		±1.4	±4	ppm/K of 2.5 V -40 °C ... 105 °C (at ±6 Sigma)
Nominal sensitivity	$S_N$	mV/A		25		625 mV/ $I_{PN}$
Sensitivity error	$\varepsilon_s$	%	-0.7		0.7	100 % tested
Temperature coefficient of $S$	$TCS$	ppm/K			±40	-40 °C ... 105 °C
Linearity error	$\varepsilon_L$	% of $I_{PN}$	-0.1		0.1	
Magnetic offset current @ $I_p = 0$ and specified $R_M$ , after an overload of $10 \times I_{PN}$	$I_{OM}$	A	-0.1		0.1	
Noise current spectral density 100 Hz ... 100 kHz referred to primary	$i_{no}$	µA/Hz <sup>1/2</sup>		20		$R_L = 1\text{ k}\Omega$
Peak-peak output ripple at oscillator frequency $f = 450\text{ kHz}$ (typ.)	-	mV		10	40	$R_L = 1\text{ k}\Omega$
Delay time to 10 % to the final output value for $I_{PN}$ step	$t_{D10}$	µs			0.3	$R_L = 1\text{ k}\Omega \text{ } di/dt = 68\text{ A/}\mu\text{s}$
Delay time to 90 % to the final output value for $I_{PN}$ step	$t_{D90}$	µs			0.3	$R_L = 1\text{ k}\Omega \text{ } di/dt = 68\text{ A/}\mu\text{s}$
Frequency bandwidth (±1 dB)	$BW$	kHz	200			$R_L = 1\text{ k}\Omega$
Frequency bandwidth (±3 dB)	$BW$	kHz	300			$R_L = 1\text{ k}\Omega$
Total error	$\varepsilon_{tot}$	% of $I_{PN}$			1	
Total error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon_{tot}$	% of $I_{PN}$			1.35 (1.45)	
Error	$\varepsilon$	% of $I_{PN}$			0.8	
Error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon$	% of $I_{PN}$			1.15 (1.25)	

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**Electrical data CKSR 50-NP**

At  $T_A = 25^\circ\text{C}$ ,  $U_C = +5\text{ V}$ ,  $N_p = 1$  turn,  $R_L = 10\text{ k}\Omega$ , internal reference, unless otherwise noted (see Min, Max, typ. definition paragraph in page 9).

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal RMS current	$I_{PN}$	A		50		Apply derating according to fig. 28
Primary current, measuring range	$I_{PM}$	A	-150		150	
Number of primary turns	$N_p$	-		1, 2, 3, 4		
Supply voltage	$U_C$	V	4.75	5	5.25	
Current consumption	$I_C$	mA		$15 + \frac{I_p(\text{mA})}{N_s}$	$20 + \frac{I_p(\text{mA})}{N_s}$	$N_s = 966$ turns
Reference voltage @ $I_p = 0\text{ A}$	$U_{ref}$	V	2.495	2.5	2.505	Internal reference
External reference voltage	$U_{ref}$	V	0		4	
Output voltage	$U_{out}$	V	0.375		4.625	
Output voltage @ $I_p = 0\text{ A}$	$U_{out}$	V		$U_{ref}$		
Electrical offset voltage	$U_{OE}$	mV	-0.725		0.725	100 % tested $U_{out} - U_{ref}$
Electrical offset current referred to primary	$I_{OE}$	mA	-58		58	100 % tested
Temperature coefficient of $U_{ref}$	$TCU_{ref}$	ppm/K		±5	±50	Internal reference
Temperature coefficient of $U_{out}$ @ $I_p = 0\text{ A}$	$TCU_{out}$	ppm/K		±0.7	±3	ppm/K of 2.5 V -40 °C ... 105 °C (at ±6 sigma)
Nominal sensitivity	$S_N$	mV/A		12.5		$625\text{ mV}/I_{PN}$
Sensitivity error	$\varepsilon_s$	%	-0.7		0.7	100 % tested
Temperature coefficient of $S$	$TCS$	ppm/K			±40	-40 °C ... 105 °C
Linearity error	$\varepsilon_L$	% of $I_{PN}$	-0.1		0.1	
Magnetic offset current ( $10 \times I_{PN}$ ) referred to primary	$I_{OM}$	A	-0.1		0.1	
Noise current spectral density 100 Hz ... 100 kHz referred to primary	$i_{no}$	$\mu\text{A}/\text{Hz}^{\frac{1}{2}}$		20		$R_L = 1\text{ k}\Omega$
Peak-peak output ripple at oscillator frequency = 450 kHz (Typ.)	-	mV		5	20	$R_L = 1\text{ k}\Omega$
Delay time to 10 % to the final output value for $I_{PN}$ step	$t_{D10}$	μs			0.3	$R_L = 1\text{ k}\Omega$ $di/dt = 100\text{ A}/\mu\text{s}$
Delay time to 90 % to the final output value for $I_{PN}$ step	$t_{D90}$	μs			0.3	$R_L = 1\text{ k}\Omega$ $di/dt = 100\text{ A}/\mu\text{s}$
Frequency bandwidth (±1 dB)	$BW$	kHz	200			$R_L = 1\text{ k}\Omega$
Frequency bandwidth (±3 dB)	$BW$	kHz	300			$R_L = 1\text{ k}\Omega$
Total error	$\varepsilon_{tot}$	% of $I_{PN}$			0.9	
Total error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon_{tot}$	% of $I_{PN}$			1.2 (1.3)	
Error	$\varepsilon$	% of $I_{PN}$			0.8	
Error @ $T_A = 85^\circ\text{C}$ (105 °C)	$\varepsilon$	% of $I_{PN}$			1.1 (1.3)	

**Definition of typical, minimum and maximum values**

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between  $-3\sigma$  and  $+3\sigma$ . If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between  $-\sigma$  and  $+\sigma$  for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

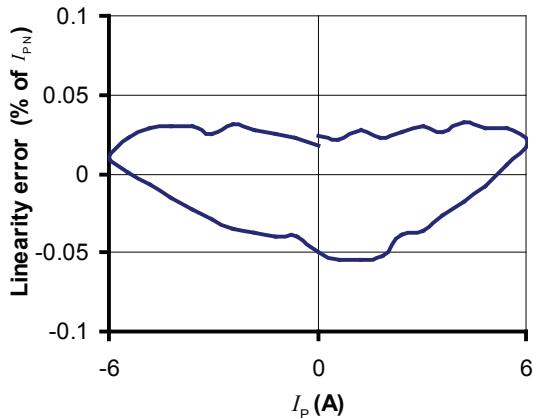
**Typical performance characteristics CKSR 6-NP**


Figure 1: Linearity error

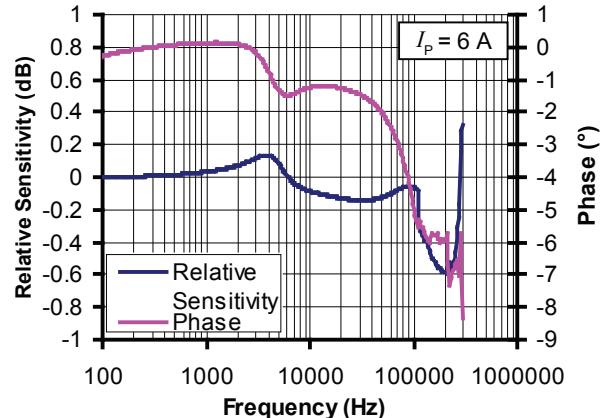


Figure 2: Frequency response

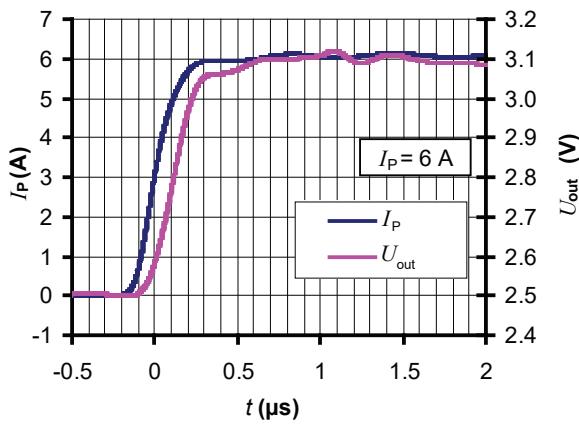


Figure 3: Step response

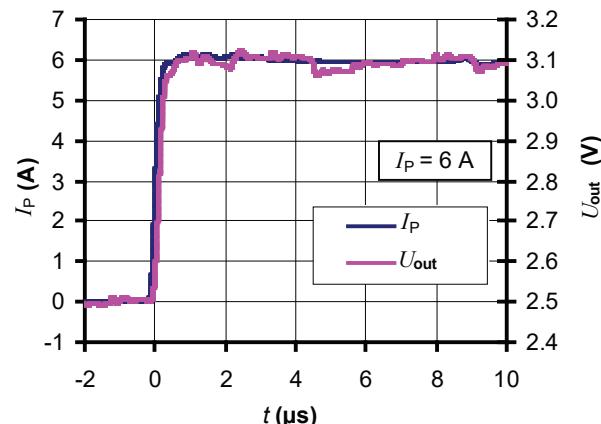


Figure 4: Step response

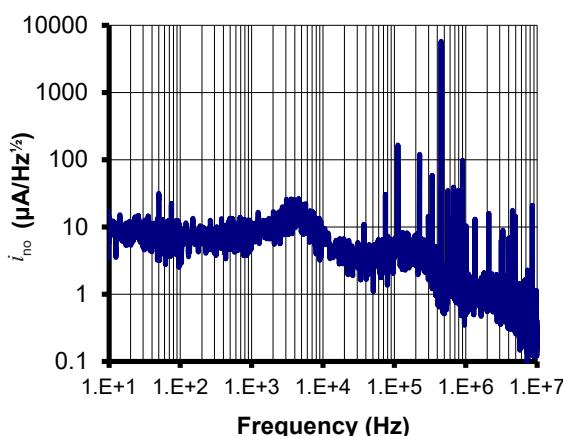


Figure 5: Noise current spectral density referred to primary

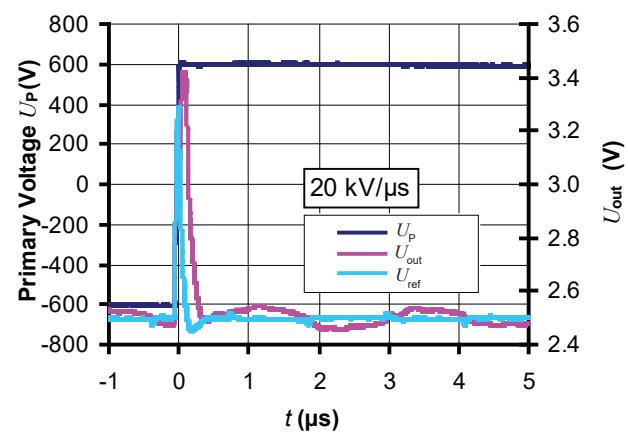


Figure 6:  $dv/dt$

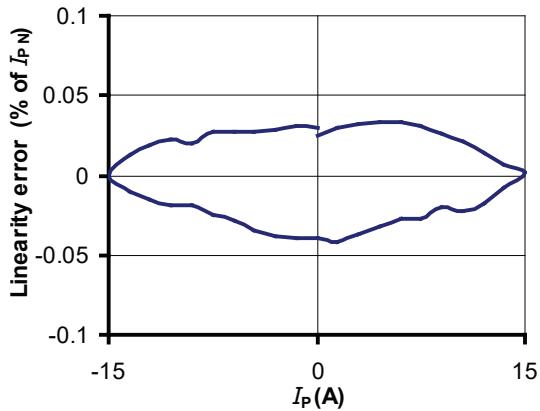
**Typical performance characteristics CKSR 15-NP**


Figure 7: Linearity error

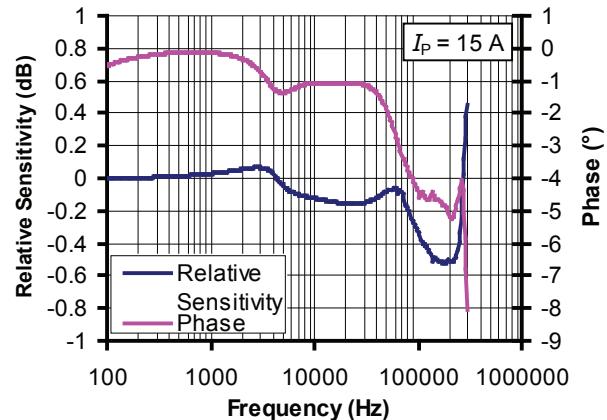


Figure 8: Frequency response

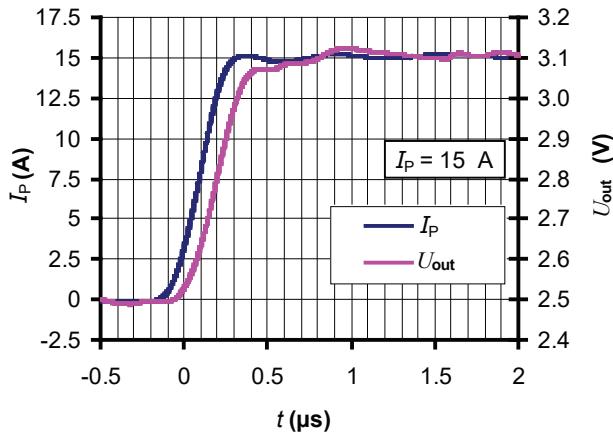


Figure 9: Step response

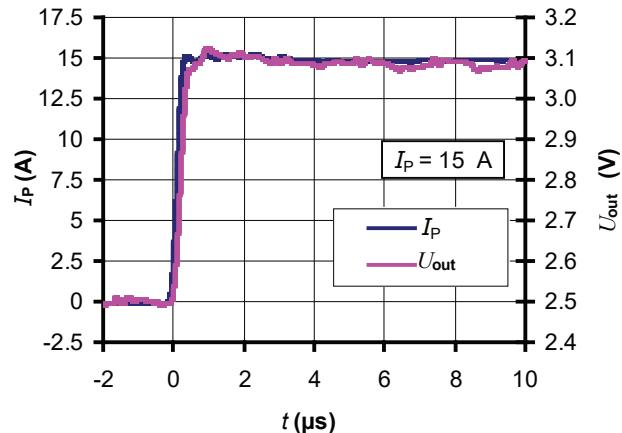


Figure 10: Step response

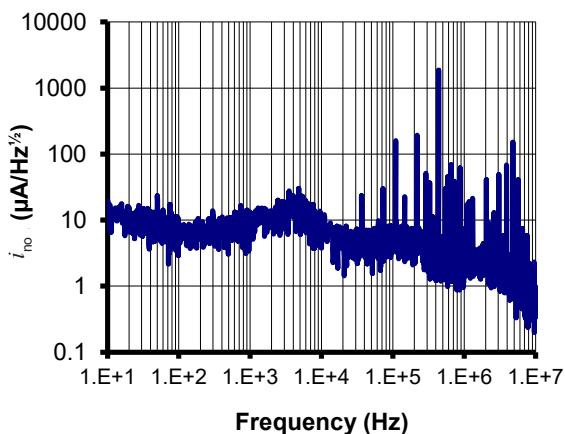


Figure 11: Noise current spectral density referred to primary

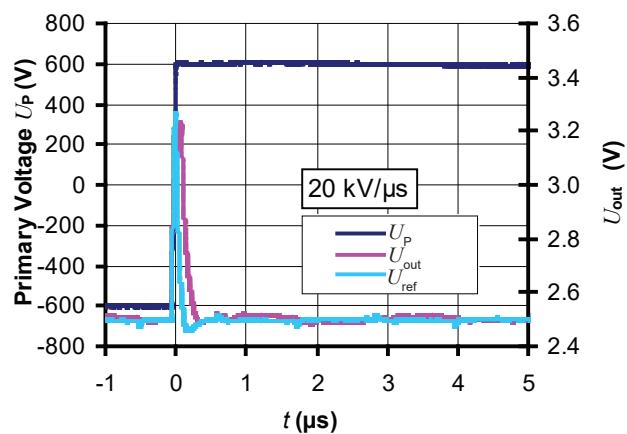


Figure 12:  $du/dt$

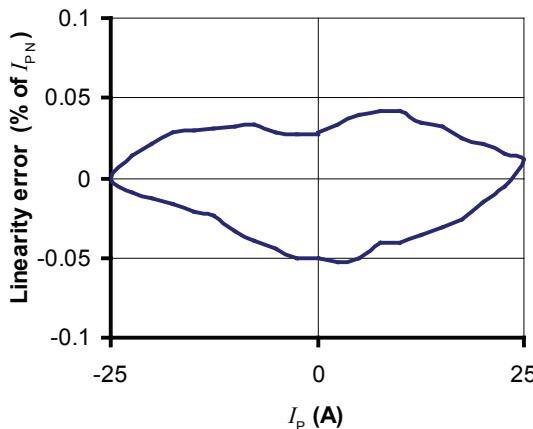
**Typical performance characteristics CKSR 25-NP**


Figure 13: Linearity error

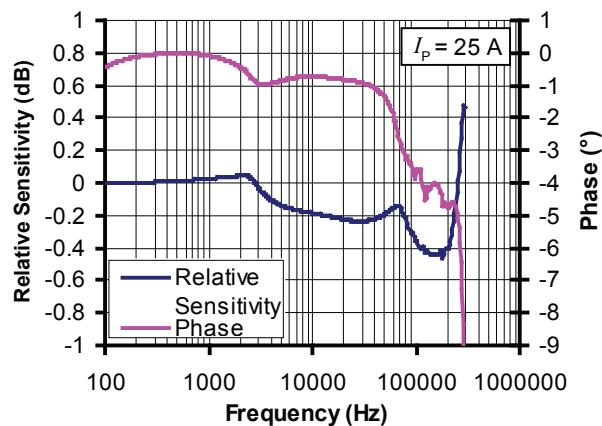


Figure 14: Frequency response

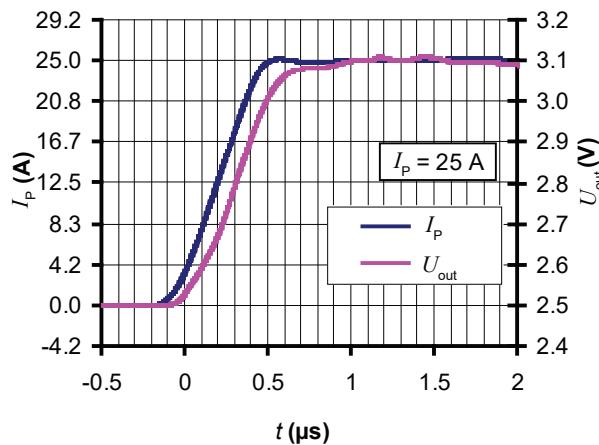


Figure 15: Step response

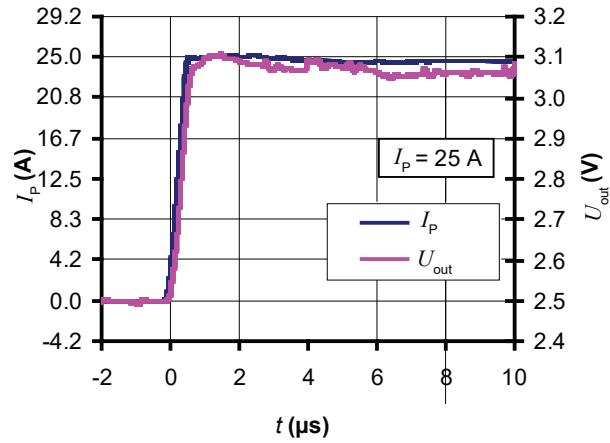


Figure 16: Step response

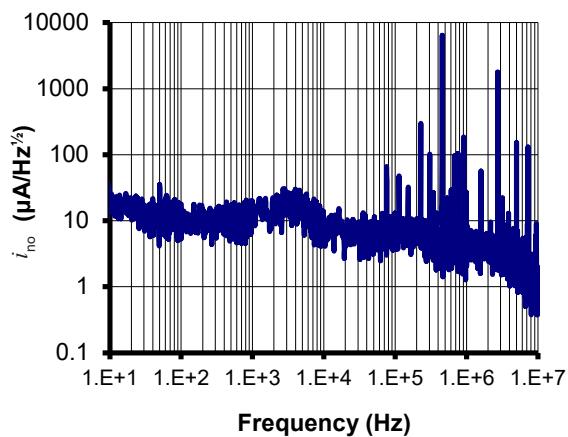


Figure 17: Noise current spectral density referred to primary

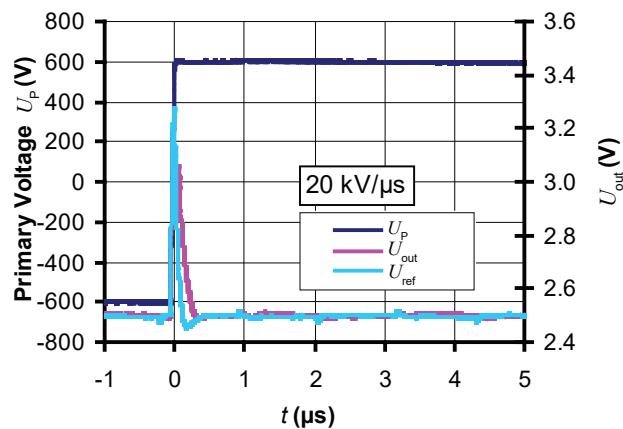
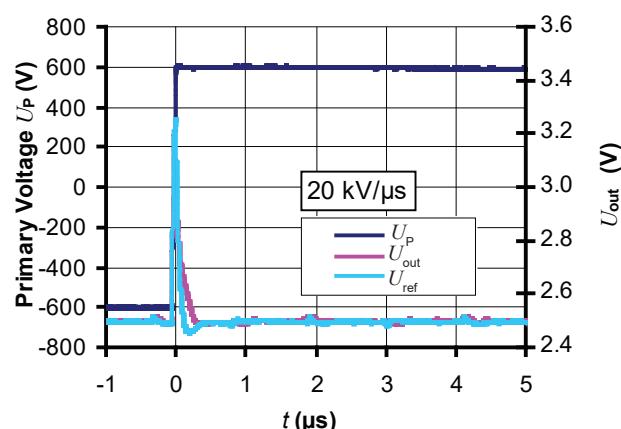
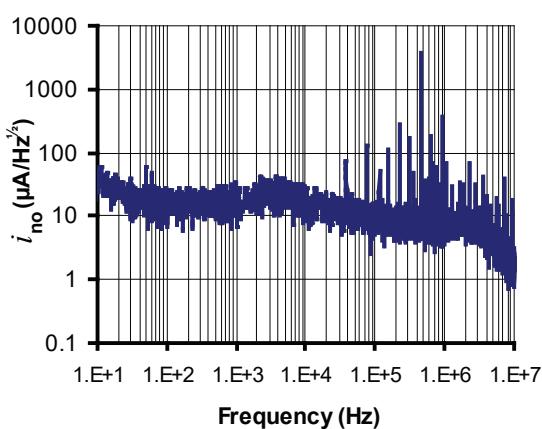
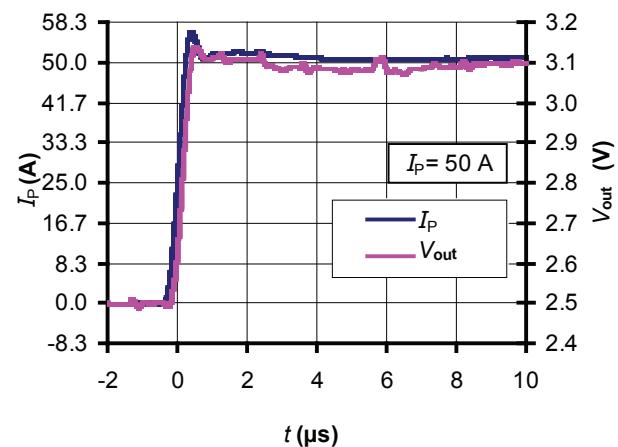
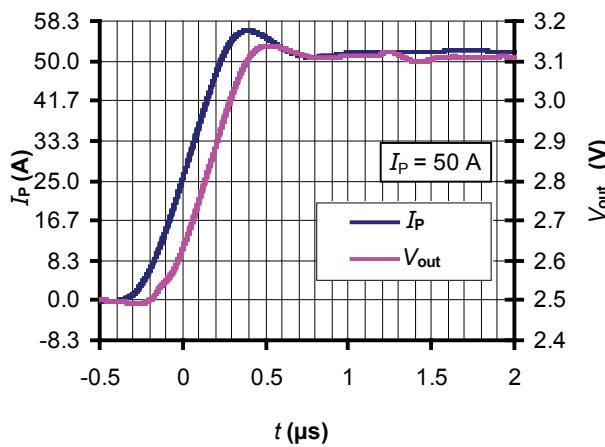
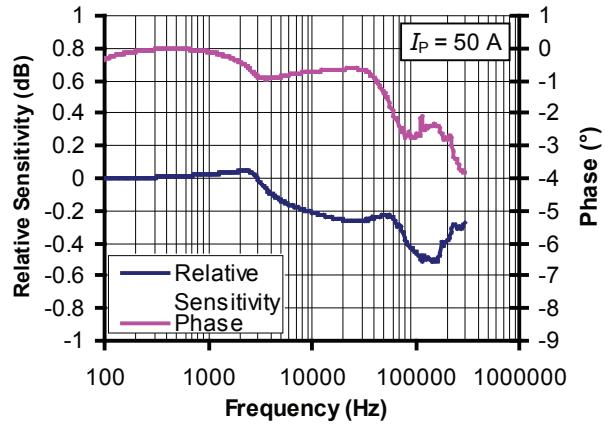
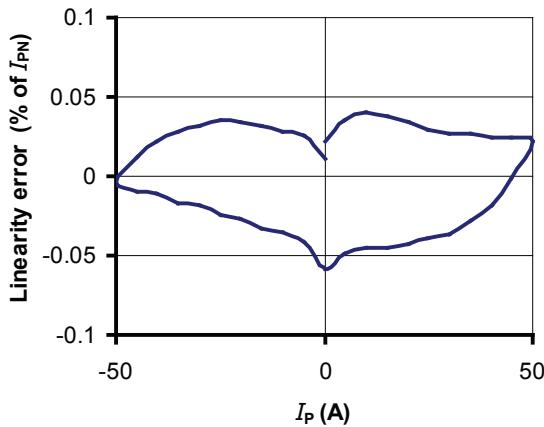


Figure 18:  $dU/dt$

**Typical performance characteristics CKSR 50-NP**


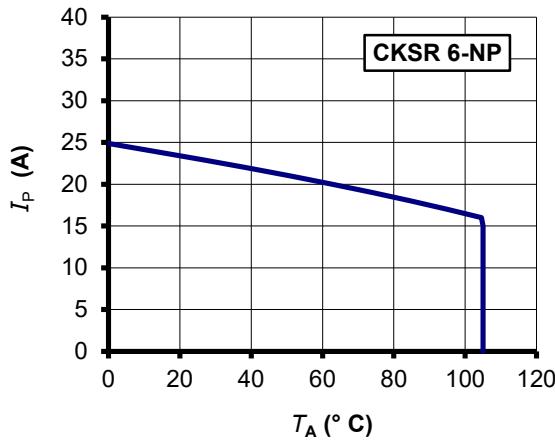
**Maximum continuous DC primary current**


Figure 25:  $I_P$  vs  $T_A$  for CKSR 6-NP

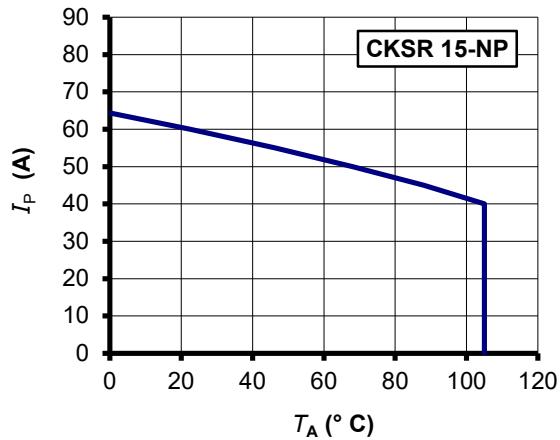


Figure 26:  $I_P$  vs  $T_A$  for CKSR 15-NP

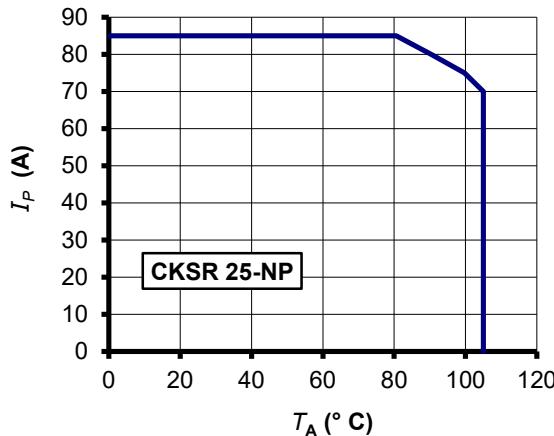


Figure 27:  $I_P$  vs  $T_A$  for CKSR 25-NP

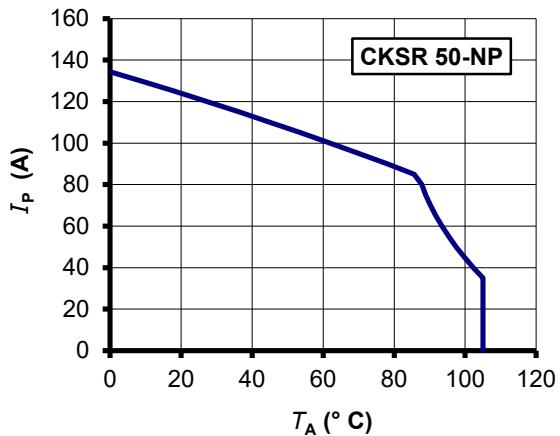


Figure 28:  $I_P$  vs  $T_A$  for CKSR 50-NP

The maximum continuous DC primary current plot shows the boundary of the area for which all the following conditions are true:

- $I_P < I_{P\text{M}}$
- Junction temperature  $T_J < 125$  °C
- Primary conductor temperature < 110 °C
- Resistor power dissipation < 0.5 × rated power

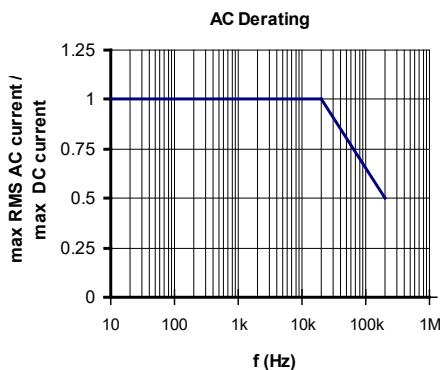
**Frequency derating**


Figure 29: Maximum RMS AC primary current / maximum DC primary current vs frequency

## Performance parameters definition

### Ampere-turns and amperes

The transducer is sensitive to the primary current linkage  $\Theta_p$  (also called ampere-turns).

$$\Theta_p = N_p I_p \text{ (At)}$$

Where  $N_p$  the number of primary turn (depending on the connection of the primary jumpers)

Caution: As most applications will use the transducer with only one single primary turn ( $N_p = 1$ ), much of this datasheet is written in terms of primary current instead of current linkages. However, the ampere-turns (At) unit is used to emphasize that current linkages are intended and applicable.

### Transducer simplified model

The static model of the transducer at temperature  $T_A$  is:

$$U_{out} = S \Theta_p + \varepsilon$$

In which  $\varepsilon =$

$$U_{OE} + U_{OT}(T_A) + \varepsilon_s \cdot \Theta_p \cdot S + \varepsilon_l(\Theta_{p_{max}}) \cdot \Theta_{p_{max}} \cdot S + TCS \cdot (T_A - 25) \cdot \Theta_p \cdot S$$

With:	$\Theta_p = N_p I_p$	:the input ampere-turns (At) Please read above warning.
	$\Theta_{p_{max}}$	:the maxi input ampere-turns that have been applied to the transducer (At)
	$U_{out}$	:the secondary voltage (V)
	$T_A$	:the ambient temperature (°C)
	$U_{OE}$	:the electrical offset voltage (V)
	$U_{OT}(T_A)$	:the temperature variation of $U_O$ at temperature $T_A$ (V)
	$S$	:the sensitivity of the transducer (V/At)
	$\varepsilon_s$	:the sensitivity error
	$\varepsilon_l(\Theta_{p_{max}})$	:the linearity error for $\Theta_{p_{max}}$

This model is valid for primary ampere-turns  $\Theta_p$  between  $-\Theta_{p_{max}}$  and  $+\Theta_{p_{max}}$  only.

### Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to  $I_p$ , then to  $-I_p$  and back to 0 (equally spaced  $I_p/10$  steps).

The sensitivity  $S$  is defined as the slope of the linear regression line for a cycle between  $\pm I_{p_N}$ .

The linearity error  $\varepsilon_l$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of  $I_{p_N}$ .

### Magnetic offset

The magnetic offset current  $I_{OM}$  is the consequence of a current on the primary side ("memory effect" of the transducer's ferromagnetic parts). It is included in the linearity figure but can be measured individually.

It is measured using the following primary current cycle.

$I_{OM}$  depends on the current value  $I_{p1}$  ( $I_{p1} > I_{p_N}$ ).

$$I_{OM} = \frac{U_{out}(t_1) - U_{out}(t_2)}{2} \cdot \frac{1}{S_N}$$

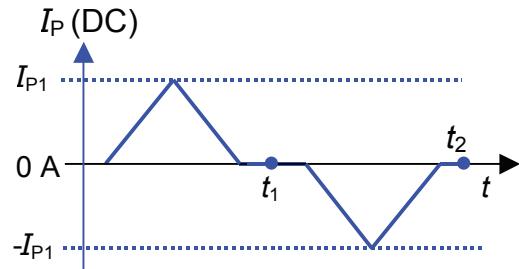


Figure 30: Current cycle used to measure magnetic and electrical offset (transducer supplied)

### Electrical offset

The electrical offset voltage  $U_{OE}$  can either be measured when the ferro-magnetic parts of the transducer are:

- completely demagnetized, which is difficult to realize,
- or in a known magnetization state, like in the current cycle shown in figure 30.

Using the current cycle shown in figure 30, the electrical offset is:

$$U_{OE} = \frac{U_{out}(t_1) + U_{out}(t_2)}{2}$$

The temperature variation  $U_{OT}$  of the electrical offset voltage  $U_{OE}$  is the variation of the electrical offset from 25 °C to the considered temperature:

$$U_{OT}(T) = U_{OE}(T) - U_{OE}(25 \text{ } ^\circ\text{C})$$

Note: the transducer has to be demagnetized prior to the application of the current cycle (for example with a demagnetization tunnel).

### Total error

The total error at 25 °C  $\varepsilon_{tot}$  is the error in the  $-I_{PN} \dots +I_{PN}$  range, relative to the rated value  $I_{PN}$ .

It includes:

- the electrical offset  $U_{OE}$
- the sensitivity error  $\varepsilon_s$
- the linearity error  $\varepsilon_L$  (to  $I_{PN}$ )

The magnetic offset is part of the total error. It is taken into account in the linearity error figure provided the transducer has not been magnetized by a current higher than  $I_{PN}$ .

### Response and reaction times

The delay time  $t_{D90}$  @ 90 % and the delay time  $t_{D10}$  @ 10 % are shown in figure 31.

Both depend on the primary current  $di/dt$ . They are measured at nominal ampere-turns.

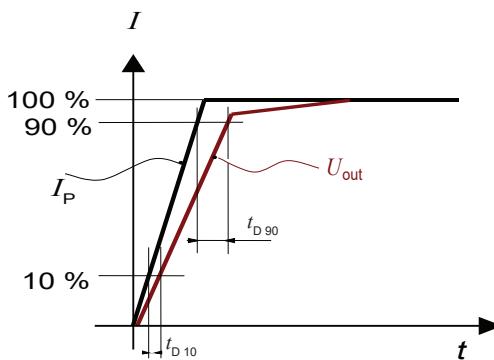


Figure 31:  $t_{D90}$  ( delay time @ 90 %) and  $t_{D10}$  ( delay time @ 10 %)

### Filtering and decoupling

#### Supply voltage $U_c$

The fluxgate oscillator draws current pulses of up to 30 mA at a rate of ca. 900 kHz. Significant 900 kHz voltage ripple on  $U_c$  can indicate a power supply with high impedance. At these frequencies the power supply rejection ratio is low, and the ripple may appear on the transducer output  $U_{out}$  and reference  $U_{ref}$ . The transducer has internal decoupling capacitors, but in the case of a power supply with high impedance, it is advised to provide local decoupling (100 nF or more, located close to the transducer)

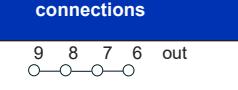
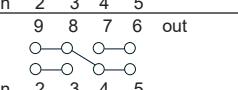
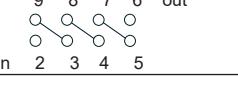
#### Output $U_{out}$

The output  $U_{out}$  has a very low output impedance of typically 2 Ohms; it can drive 100 pF directly. Adding series  $R_f = 100$  Ohms allows much larger capacitive loads. Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on  $U_{out}$  is 1 kOhm.

#### Total Primary Resistance

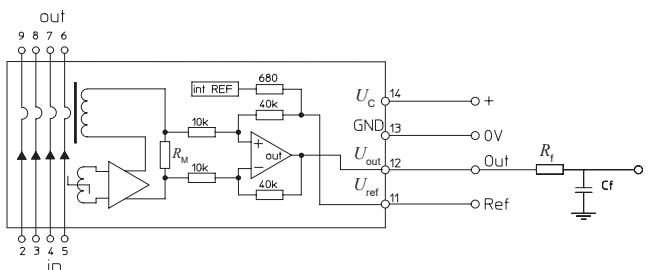
The primary resistance is 0.72 mΩ per conductor.

In the following table, examples of primary resistance according to the number of primary turns.

Number of primary turns	Primary resistance $R_p$ [mΩ]	Recommended connections
1	0.18	
2	0.72	
4	2.88	

#### Reference $U_{ref}$

Ripple present on the reference output can be filtered with a low value of capacitance because of the internal 680 Ohm series resistance. The maximum filter capacitance value is 1 μF.



### External reference voltage

If the Ref pin of the transducer is not used it could be either left unconnected or filtered according to the previous paragraph "Reference  $U_{ref}$ ".

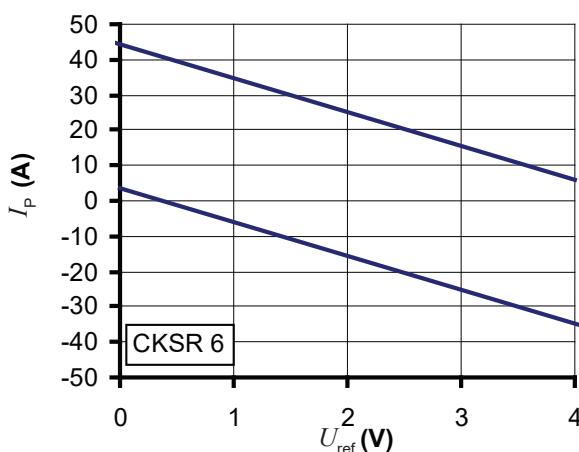
The Ref pin has two modes Ref IN and Ref OUT:

- In the Ref OUT mode the 2.5 V internal precision reference is used by the transducer as the reference point for bipolar measurements; this internal reference is connected to the Ref pin of the transducer through a 680 Ohms resistor. It tolerates sink or source currents up to  $\pm 5$  mA, but the 680 Ohms resistor prevents this current to exceed these limits.
- In the Ref IN mode, an external reference voltage is connected to the Ref pin; this voltage is specified in the range 0 to 4 V and is directly used by the transducer as the reference point for measurements. The external reference voltage  $U_{ref}$  must be able:

- either to source a typical current of  $\frac{U_{ref} - 2.5}{680}$ , the maximum value will be 2.2 mA typ. when  $U_{ref} = 4$  V.

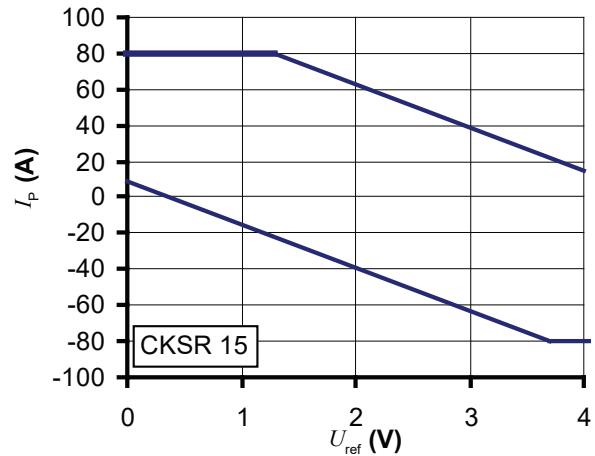
- or to sink a typical current of  $\frac{2.5 - U_{ref}}{680}$ , the maximum value will be 3.68 mA typ. when  $U_{ref} = 0$  V.

The following graphs show how the measuring range of each transducer version depends on the external reference voltage value  $U_{ref}$ .



$$\text{Upper limit: } I_P = -9.6 * U_{ref} + 44.4 \quad (U_{ref} = 0 \dots 4 \text{ V})$$

$$\text{Lower limit: } I_P = -9.6 * U_{ref} + 3.6 \quad (U_{ref} = 0 \dots 4 \text{ V})$$



$$\text{Upper limit: } I_P = -24 * U_{ref} + 111 \quad (U_{ref} = 1.29 \dots 4 \text{ V})$$

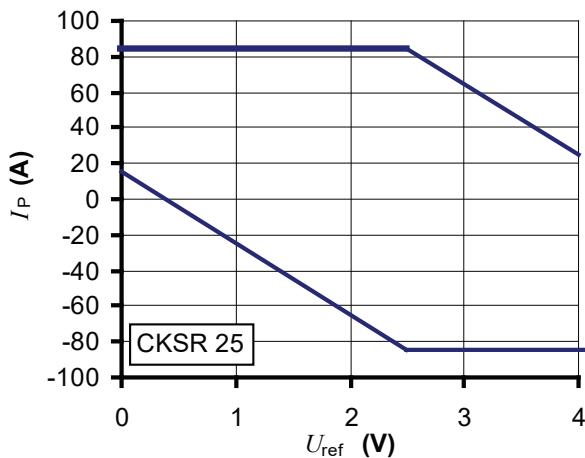
$$\text{Upper limit: } I_P = 80 \quad (U_{ref} = 0 \dots 1.29 \text{ V})$$

$$\text{Lower limit: } I_P = -24 * U_{ref} + 9 \quad (U_{ref} = 0 \dots 3.7 \text{ V})$$

$$\text{Lower limit: } I_P = -80 \quad (U_{ref} = 3.7 \dots 4 \text{ V})$$

## External reference voltage (continued)

CKSR xx-NP



Upper limit:  $I_P = -40 * U_{ref} + 185$  ( $U_{ref} = 2.5 \dots 4$  V)

Upper limit:  $I_P = 85$  ( $U_{ref} = 0 \dots 2.5$  V)

Lower limit:  $I_P = -40 * U_{ref} + 15$  ( $U_{ref} = 0 \dots 2.5$  V)

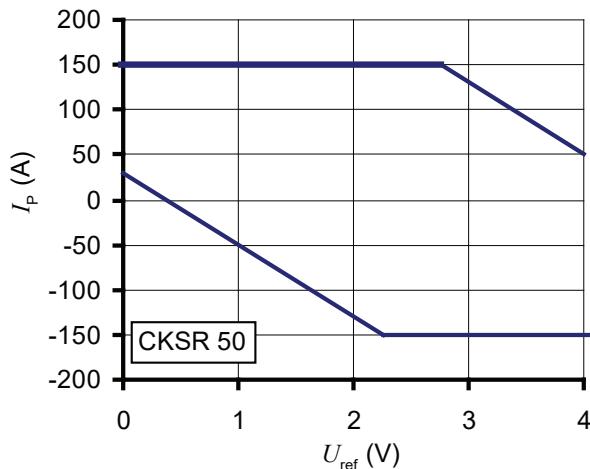
Lower limit:  $I_P = -85$  ( $U_{ref} = 2.5 \dots 4$  V)

Example with  $U_{ref} = 1.65$  V:

- The 6 A version has a measuring range from -12.24 A to +28.5 A
- The 15 A version has a measuring range from -30.6 A to +71.4 A
- The 25 A version has a measuring range from -51 A to +85 A
- The 50 A version has a measuring range from -102 A to +150 A

Example with  $U_{ref} = 0$  V:

- The 6 A version has a measuring range from +3.6 A to +44.4 A
- The 15 A version has a measuring range from +9 A to +80 A
- The 25 A version has a measuring range from +15 A to +85 A
- The 50 A version has a measuring range from +30 A to +150 A



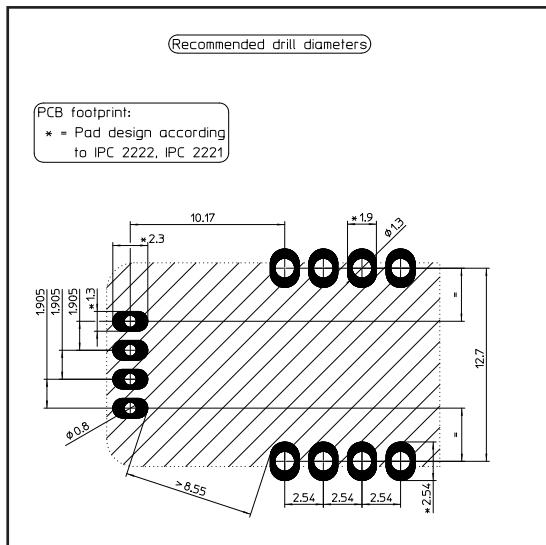
Upper limit:  $I_P = -80 * U_{ref} + 370$  ( $U_{ref} = 2.75 \dots 4$  V)

Upper limit:  $I_P = 150$  ( $U_{ref} = 0 \dots 2.75$  V)

Lower limit:  $I_P = -80 * U_{ref} + 30$  ( $U_{ref} = 0 \dots 2.25$  V)

Lower limit:  $I_P = -150$  ( $U_{ref} = 2.25 \dots 4$  V)

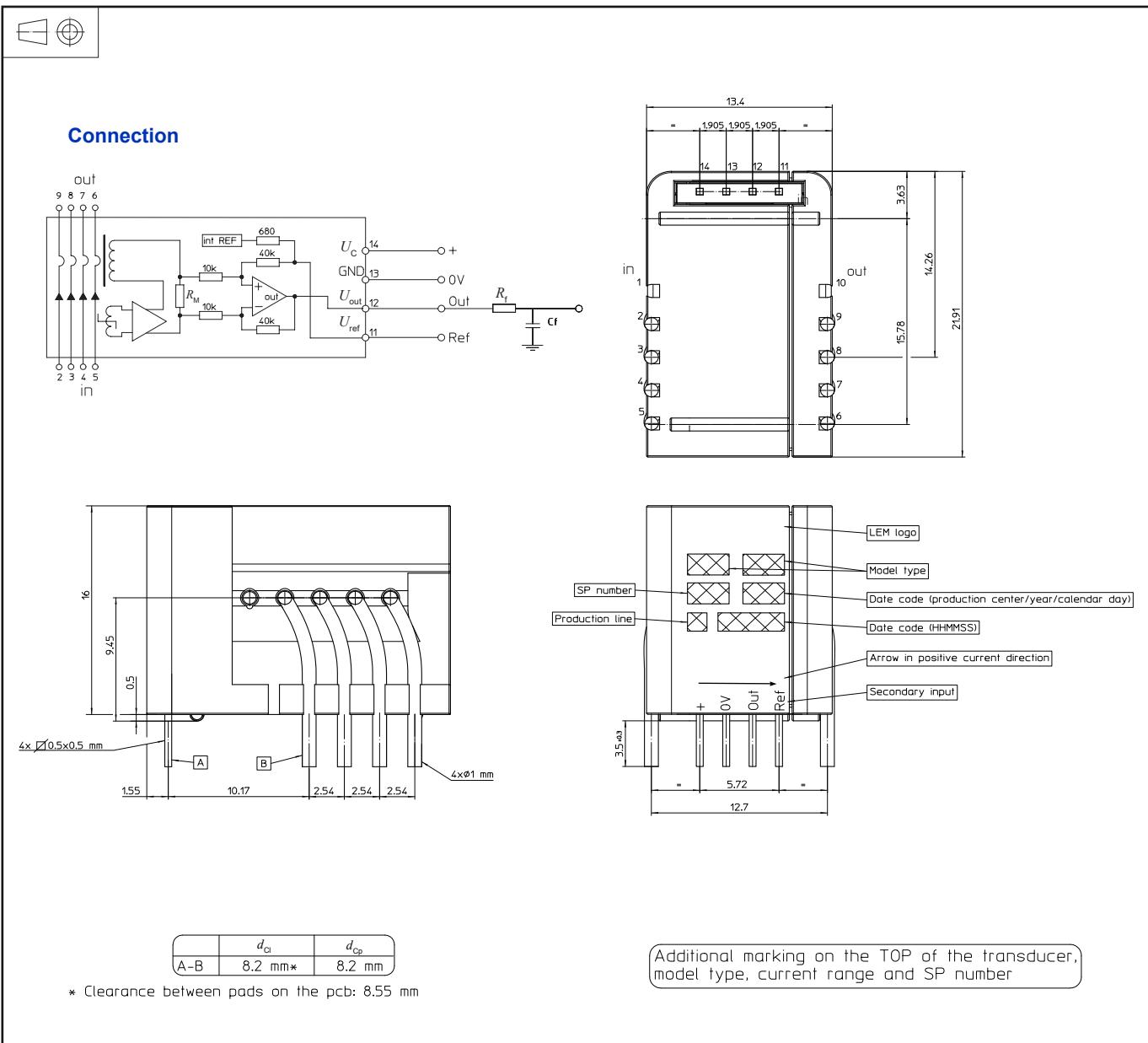
## PCB footprint



## Assembly on PCB

- Recommended PCB hole diameter 1.3 mm for primary pin  
0.8 mm for secondary pin
- Maximum PCB thickness 2.4 mm  
maximum 260 °C for 10 s

No clean process only.



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