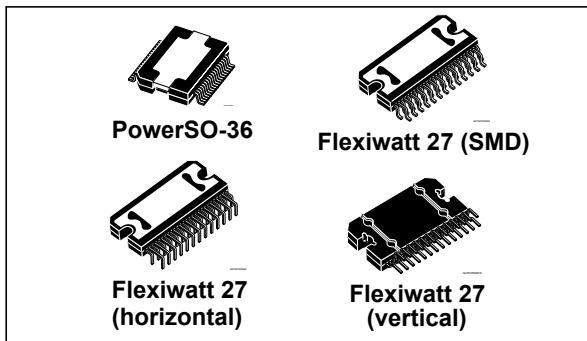


High efficiency digital input automotive quad power amplifier with built-in diagnostics features, 'start stop' compatible

Datasheet - production data



Features

- AEC-Q100 qualified
- 24-bit digital processing
- 115 dB dynamic range (A-weighted)
- SB-I (SB - improved) high efficiency operation the highest 'non - class D' efficiency
- Parallel mode function availability
- High output power capability:
 - 4 x 27 W 4 Ω @ 14.4 V, 1 kHz, THD = 10%
 - 4 x 47 W 2 Ω @ 14.4 V, 1 kHz, THD = 10%
- Flexible mode control:
 - Full I²C bus driving 1.8V/3.3V) with four addresses selectable (only for PowerSO36 package option)
 - Independent front/rear play/ mute
 - Selectable digital gains for very-low noise line-out function
 - Digital diagnostic with DC and AC load detections
- Start-stop compatibility (operation down to 6V)
- Sample rates: 44.1 kHz, 48 kHz, 96 kHz, 192 kHz
- Flexible serial data port (1.8 V / 3.3 V):
 - I²S standard, TDM 4Ch, TDM 8Ch, TDM 16ch (8+8ch)
- Offset detector
- Independent front/rear clipping detector



- Programmable diagnostic pin
- CMOS compatible enable pin
- Thermal protection
- Pop free in mute to play transitions and viceversa

Description

The TDA7803A is a single chip quad bridge amplifier in advanced BCD technology integrating: a full D/A converter, digital input for direct connection to I²S (or TDM) and powerful MOSFET output stages.

The integrated D/A converter allows the performance to reach an outstanding 115 dB S/N ratio with more than 110 dB of dynamic range.

Moreover the TDA7803A integrates an innovative high efficiency concept, optimized also for uncorrelated music signals. The device is designed to be compatible to battery modulation for class-G systems.

Thanks to this concept, the dissipated "output power" under average listening conditions can be reduced up to 50% when compared to the conventional class AB solutions.

The TDA7803A integrates also a programmable PLL that is able to lock at the input frequencies of 64*Fs for all the input configurations.

The device is equipped with a full diagnostics array that communicates the status of each speaker through the I²C bus. The same I²C bus allows to control several configurations of the device.

The TDA7803A is able to play music down to 6 V supply voltage - so it is compatible with the so called 'start stop' battery profile recently adopted by several car makers (thus reducing the fuel consumption and the impact over the environment).

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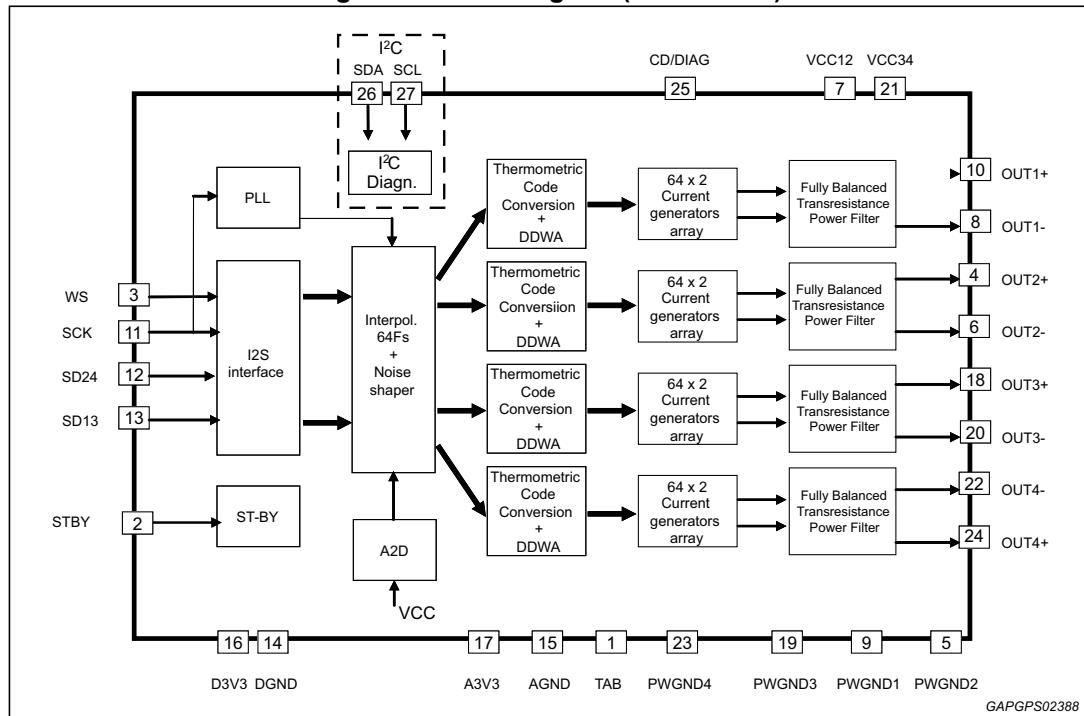
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1 Block diagram and pins description

1.1 Block diagram

Figure 1. Block diagram (Flexiwatt27)



1.2 Pins description

Figure 2. Pins connection diagrams

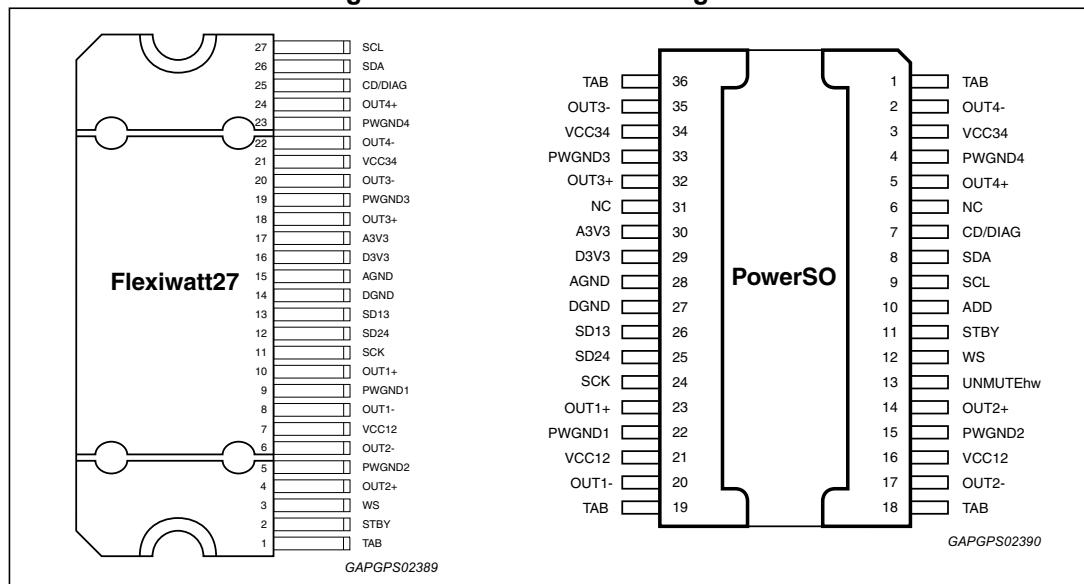


Table 1. Flexiwatt27 pins description

N°	Pin	Function	
1	TAB	TAB connection	Ground
2	STBY	STBY pin	Input
3	WS	Word select (I ² S bus)	Logic Input
4	OUT2+	Channel 2 (Left Rear) positive output	Power Output
5	PWGND2	Power ground channels 2	Power Ground
6	OUT2-	Channels 2 (Left Rear) negative output	Power Output
7	VCC12	Channel 1 and 2 positive supply	Battery
8	OUT1-	Channel 1 (Left Front) negative output	Power Output
9	PWGND1	Power ground channel 1	Power Ground
10	OUT1+	Channel 1 (Left Front) positive output	Power Output
11	SCK	Serial clock (I ² S bus)	Logic Input
12	SD24	Serial data channels 2 and 4 (I ² S bus)	Logic Input
13	SD13	Serial data channels 1 and 3 (I ² S bus)	Logic Input
14	DGND	Digital ground	Signal Ground
15	AGND	Analog ground	Signal Ground
16	D3V3	Digital 3.3V supply filter	Digital Regulator
17	A3V3	Analog 3.3V supply filter	Analog Regulator
18	OUT3+	Channels 3 (right front) positive output	Power Output
19	PWGND3	Power ground channel 3	Power Ground
20	OUT3-	Channels 3 (right front) negative output	Power Output
21	VCC34	Channels 3 and 4 positive supply	Battery
22	OUT4-	Channels 4 (right rear) negative output	Power Output
23	PWGND4	Power ground channel 4	Power Ground
24	OUT4+	Channels 4 (right rear) positive output	Power Output
25	CD/DIAG	Clip detector and diagnostic output	Open Drain Output
26	SDA	I ² C data	Signal Input
27	SCL	I ² C clock	Signal Input

Table 2. PowerSO36 pins description

N°	Pin	Function	
1	TAB	Device slug connection	Ground
2	OUT4-	Channels 4 (right rear) negative output	Power Output
3	VCC34	Channels 3 and 4 positive supply	Battery
4	PWGND4	Power ground channel 4	Power Ground
5	OUT4+	Channels 4 (right rear) positive output	Power Output
6	NC	Not connected	-
7	CD/DIAG	Clip detector and diagnostic output	Open Drain Output
8	SDA	I ² C data	Signal Input
9	SCL	I ² C clock	Signal Input
10	ADD	I ² C Address	Logic Input
11	STBY	STBY pin	Input
12	WS	Word select (I ² S bus)	Logic Input
13	UNMUTEhw	Unmute Hardware	Logic Input
14	OUT2+	Channel 2 (Left Rear) positive output	Power Output
15	PWGND2	Power ground channels 2	Power Ground
16	VCC12	Channel 1 and 2 positive supply	Battery
17	OUT2-	Channels 2 (Left Rear) negative output	Power Output
18	TAB	Device slug connection	Ground
19	TAB	Device slug connection	Ground
20	OUT1-	Channel 1 (Left Front) negative output	Power Output
21	VCC12	Channel 1 and 2 positive supply	Battery
22	PWGND1	Power ground channel 1	Power Ground
23	OUT1+	Channel 1 (Left Front) positive output	Power Output
24	SCK	Serial clock (I ² S bus)	Logic Input
25	SD24	Serial data channels 2 and 4 (I ² S bus)	Logic Input
26	SD13	Serial data channels 1 and 3 (I ² S bus)	Logic Input
27	DGND	Digital ground	Signal Ground
28	AGND	Analog ground	Signal Ground
29	D3V3	Digital 3.3V supply filter	Digital Regulator
30	A3V3	Analog 3.3V supply filter	Analog Regulator
31	NC	Not connected	-
32	OUT3+	Channels 3 (right front) positive output	Power Output
33	PWGND3	Power ground channel 3	Power Ground
34	VCC34	Channels 3 and 4 positive supply	Battery
35	OUT3-	Channels 3 (right front) negative output	Power Output
36	TAB	Device slug connection	Ground

2 Application diagrams

Figure 3. I²C bus mode application diagram (Flexiwatt)

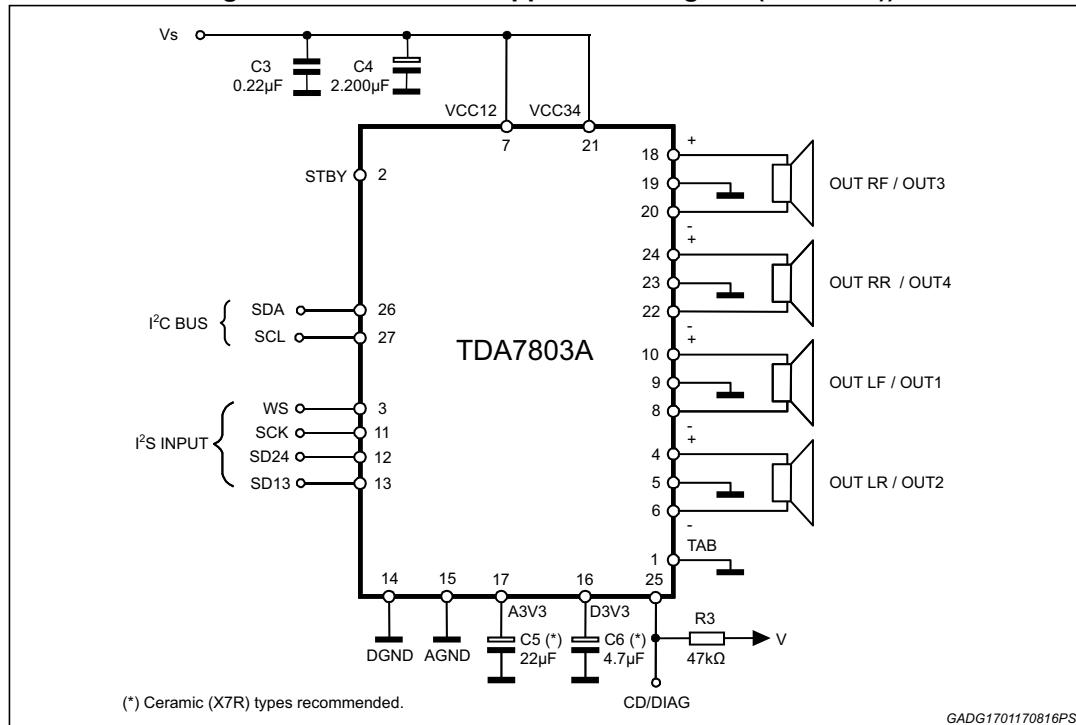
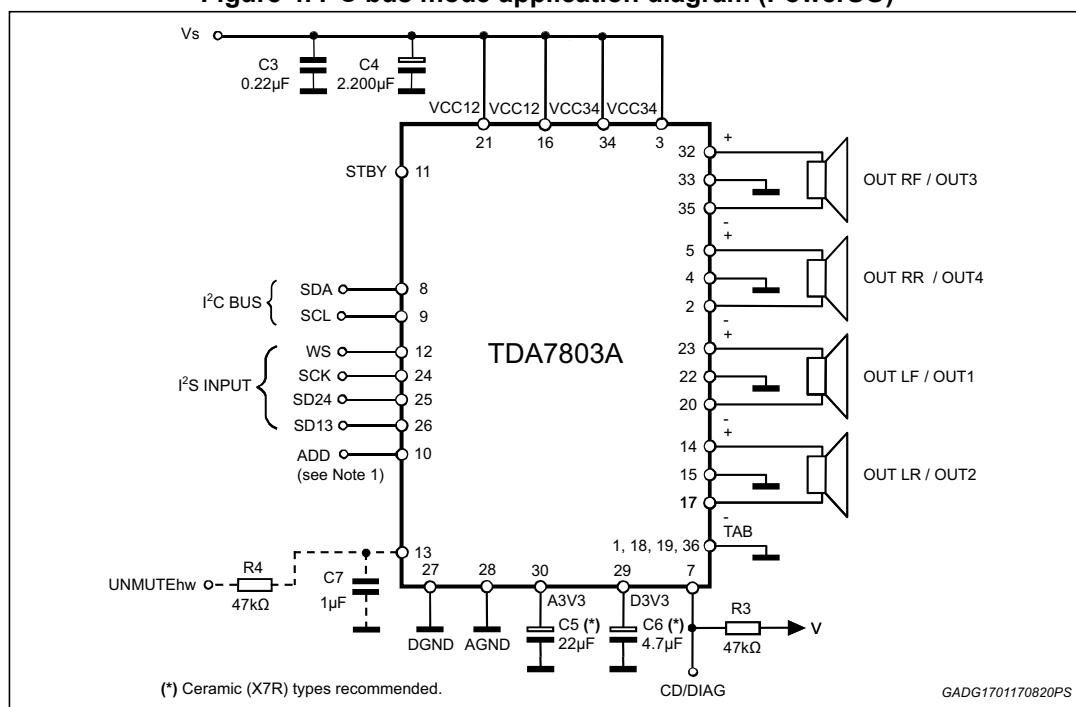


Figure 4. I²C bus mode application diagram (PowerSO)



1. Refer to [Section 9: I²C bus interface](#) for connection suggestions.

3 Electrical specification

3.1 Absolute maximum ratings

Table 3. Absolute maximum ratings

Symbol	Parameter	Value	Unit
V_S	DC supply voltage	-0.3 to 28	V
V_{peak}	Transient supply voltage for $t = 100$ ms	-0.3 to 50	V
V_{i2c}	I^2C bus pins voltage	-0.3 to 4.6	V
V_{i2s}	I^2S bus pins voltage	-0.3 to 4.6	V
V_{unmute}	Unmute hardware voltage (PSO36 only)	-0.3 to 4.6	V
V_{cd}	CD/Diag pin voltage	-0.3 to 20	V
V_{stby}	STBY pin voltage	-0.3 to 4.6	V
I_O	Output peak current (repetitive $f > 10$ Hz)	internally limited ⁽¹⁾	A
P_{tot}	Power dissipation $T_{case} = 70$ °C	85	W
T_{stg}, T_j	Storage and junction temperature	-55 to 150	°C
T_{amb}	Operative temperature range ⁽²⁾	-40 to 105	°C
C_{max}	Maximum capacitor vs. ground connected to the output	4.7	nF
ESD_{HBM}	ESD protection HBM ⁽³⁾	2000	V
ESD_{CDM}	ESD protection CDM ⁽³⁾	500	V

1. Internally limited by overcurrent protection.
2. A suitable heatsink/dissipation system should be used to keep T_j inside the specified limits.
3. Conforming to Q100 ESD standard.

3.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Value	Unit
$R_{th\ j-case}$	Thermal resistance junction-to-case (max.)	1	°C/W

3.3 Electrical characteristics

Referred to the test setup $V_S = 14.4$ V; $R_L = 4$ Ω ; $f = 1$ kHz; tested at $T_{amb} = 25$ °C; functionality guaranteed for $T_j = -40$ °C to 150 °C; SB-I mode; unless otherwise specified.

Table 5. Electrical characteristics

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
General						
V_S	Supply voltage range	$R_L = 4$ Ω	6	-	18.5	V
		$R_L = 2$ Ω , std_bridge	6	-	16	V
		$R_L = 2$ Ω , SBI	6	-	16	V
I_{SB}	Standby current	-	-	1	4	μ A
I_q	Total quiescent current in amplifier mode	Mute condition	-	170	210	mA
I_{qECO}	Total quiescent current in ECO mode	ECO mode	-	35	40	mA
A_M	Mute attenuation	-	80	-	-	dB
V_{OS}	Offset voltage	Mute and play	-25	-	+25	mV
V_{lowM}	V_{CC} low supply mute threshold (Min I ² C setting - default)	Attenuation <0.5 dB, digital mute disabled	-	-	5.6	V
		Attenuation \geq 60 dB, digital mute disabled	5	-	-	V
$V_{POWONRESET}$	Supply voltage of power-on reset	-	-	3.5	-	V
V_{highM}	High supply mute threshold	Attenuation = -6 dB	19	-	21	V
Audio performances						
P_O	Output power	$R_L = 4$ Ω ; max power ⁽¹⁾	40	43	-	W
		THD = 10 %	25	27	-	W
		THD = 1 %	20	22	-	W
		$R_L = 2$ Ω ; THD 10%	44	47	-	W
		$R_L = 2$ Ω ; THD 1%	34	37	-	W
		$R_L = 2$ Ω ; max power ⁽¹⁾	69	72	-	W
THD_{SB}	Total harmonic distortion (Standard bridge)	$P_O = 4$ W, $f=1$ kHz, G_{V1}	-	0.015	0.04	%
		$P_O = 4$ W, $f=10$ kHz, G_{V1}	-	0.15	0.5	%
		$R_L = 100$ Ω input=-10 dBFS, $f = 1$ kHz, $G_{V1,2,3,4}$	-	0.01	0.02	%
THD	Total harmonic distortion (SBI mode)	$P_O = 2$ W, $f = 1$ kHz, G_{V1}	-	0.015	0.04	%
		$P_O = 6$ W, $f = 1$ kHz, G_{V1}	-	0.02	0.06	%

Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
$C_T^{(2)}$	Cross talk	$f = 1 \text{ kHz}$	-	100	-	dB
		$f = 10 \text{ kHz}$	-	80	-	dB
G_{V1}	Voltage gain 1	@ Amplitude = -18 dBFs	2.3	2.5	-	Vp
G_{V2}	Voltage gain 2		1.25	1.35	-	Vp
G_{V3}	Voltage gain 3		0.9	1	-	Vp
G_{V4}	Voltage gain 4		0.4	0.55	-	Vp
$DR^{(2)}$	Dynamic range	A-wtd values, G_{V1} gain	-	115	-	dB
E_{out1}	Output noise voltage	A-wtd values	-	27	40	μV
	$G_V = G_{V1}$		-	18	-	
E_{out2}	Output noise voltage	ITU-R 468	-	70	96	μV
	$G_V = G_{V1}$		-	45	-	
$SNR^{(2)}$	Signal to noise ratio	A-wtd values, G_{V1} gain	-	115	-	dB
ΔG_V	Channel Gain Mismatch	-	-0.5	-	0.5	dB
SSR	Supply slew rate	-	-	1	-	$\text{V}/\mu\text{s}$
PSRR	Power supply rejection ratio	$f = 1 \text{ kHz};$ $V_r = 1 \text{ Vpk};$	60	70	-	dB
$ \Delta V_{OITUL} $	ITU Pop filter output voltage (standard bridge mode)	Eco mode to mute transition and vice versa	-	-	4	mV
		Mute to Play and Play to Mute transition ⁽³⁾	-	0	-	mV
Clipping detector						
CD_{LK}	Clip det high leakage current	CD off, $V = 3.3 \text{ V}$	-	0	1	μA
CD_{SAT}	Clip det sat. voltage	CD on; $I_{CD} = 1 \text{ mA}$	-	50	-	mV
$CD1_{THD}$	Clip det THD threshold 1	-	-	2	3	%
$CD2_{THD}$	Clip det THD threshold 2	-	4	6	8	%
$CD3_{THD}$	Clip det THD threshold 3	-	9	12	14	%
Turn on diagnostics for parallel mode configuration						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	-	-	-	1	V
P_{vs}	Short to V_s det. (above this limit, the output is considered in short circuit to V_s)	-	$V_s - 1$	-	-	V

Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
Pnop	Normal operation thresholds. (within these limits, the output is considered without faults).	-	2	-	$V_s - 2$	V
Lsc	Shorted load det.	-	-	-	0.7	Ω
Lop	Normal load det.	-	1.3	-	30	Ω
Lnop	Open load det.	-	70	-	-	Ω
Turn-on diagnostic for parallel mode configuration						
Lsc	Shorted load det.	-	-	-	0.35	Ω
Lop	Normal load det.	-	0.65	-	15	Ω
Lnop	Open load det.	-	35	-	-	Ω
Rss	Soft Short Diagnostic threshold (below this value, soft short resistance is recognized)	-	500	-	-	Ω
Turn-on diagnostic for line driver mode configuration						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	-	-	-	1	V
Pvs	Short to V_s det. (above this limit, the output is considered in short circuit to V_s)	-	$V_s - 1$	-	-	V
Pnop	Normal operation thresholds. (within these limits, the output is considered without faults).	-	2	-	$V_s - 2$	V
Lsc	Shorted load det.	-	-	-	20	Ω
Lop	Normal load det.	-	60	-	1400	Ω
Lnop	Open load det.	-	2600	-	-	Ω
Rss	Soft Short Diagnostic threshold (below this value, soft short resistance is recognized)	-	5.8 ⁽⁴⁾	-	-	$k\Omega$
AC-diagnostic						
I _{ACTRESH}	AC diagnostic current threshold	IB4 – D4= '0'	250	375	500	mA
		IB4 – D4= '1'	125	187	250	mA

Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
Permanent diagnostics						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	Power amplifier in Mute or Play, one or more short circuits protection activated	-	-	1	V
Pvs	Short to V_s det. (above this limit, the Output is considered in short circuit to V_s)	-	$V_s - 1$	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults)	-	2	-	$V_s - 2$	V
L_{SC}	Shorted load det.	Parallel mode	-	-	0.35	Ω
		Speaker mode	-	-	0.7	
		Line driver mode	-	-	20	
L_{OP}	Normal load det.	Parallel mode	0.65	-	-	Ω
		Speaker mode	1.3	-	-	
		Line driver mode	60	-	-	
T_{ph}	Thermal protection junction temperature	Attenuation ≥ 60 dB	-	165	-	°C
T_{pl}		Attenuation < 0.5 dB	-	155	-	°C
T_{w1}	Thermal warning junction temperature ⁽⁵⁾	-	-	T_{pl-5}	-	°C
T_{w2}		-	-	T_{pl-10}	-	°C
T_{w3}		-	-	T_{pl-20}	-	°C
T_{w4}		-	-	T_{pl-30}	-	°C
I²C bus interface						
f_{SCL}	Clock frequency	-	-	-	400	kHz
V_{IL}	Input low voltage	-	-	-	0.8	V
V_{IH}	Input high voltage	-	1.3	-	-	V
V_{OLmax}	Maximum I ² C data pin low voltage when current I_{sink} is sunked	$I_{sink} = 2$ mA	-	-	0.27	V
		$I_{sink} = 8$ mA	-	-	0.7	V
I_{limax}	Maximum input leakage current	$V = 3.6$ V	-	-	1	µA
STBY pin						
V_{ILSTBY}	Input low voltage	-	-	-	1.2	V
V_{IHSTBY}	Input high voltage	-	2.4	-	-	V

Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
I_{ILSTBY}	Logic '0' output current	$V_{IN} = 0.45$ V	-	-	1	μ A
I_{IHSTBY}	Logic '1' input current	$V_{IN} = 2.3$ V ($IB0\ D4=0$)	-	-	1	μ A
I²S pins						
V_{IL-I2S}	Input low voltage	-	-	-	0.8	V
V_{IH-I2S}	Input high voltage	-	1.3	-	-	V
I_{IH}	Input high current	@ $V_I = 3.3$ V	-	-	1	μ A
I_{IL}	Input low current	@ $V_I = 0$ V	-	-	1	μ A
Unmute hardware (pin 13)						
V_{HW_UNMUTE}	Hardware unmute threshold (PSO36 only)	Attenuation ≥ 60 dB	-	-	1.2	V
		Attenuation < 0.5 dB	2.6	-	-	V
I_{UNMUTE}	Input high current	@ $V_I = 3.3$ V	-	-	1	μ A
	Input low current	@ $V_I = 0$ V	-	-	1	μ A

1. Square-wave input / saturated output.
2. Evaluated at bench during product validation.
3. Guaranteed by design (intrinsically immune from any pop at mute to play and play to mute transitions)
4. The values are the ones that guarantee the correct working of the diagnostic. Since the value is strongly dependent on the loudspeaker, we decided to target the values for the limits of open load and short load diagnostic.
5. Thermal warning junction temperature values could be changed via I²C bits IB5-d6,d7.

3.4 Electrical characteristics typical curves

Figure 5. Quiescent current vs. supply voltage

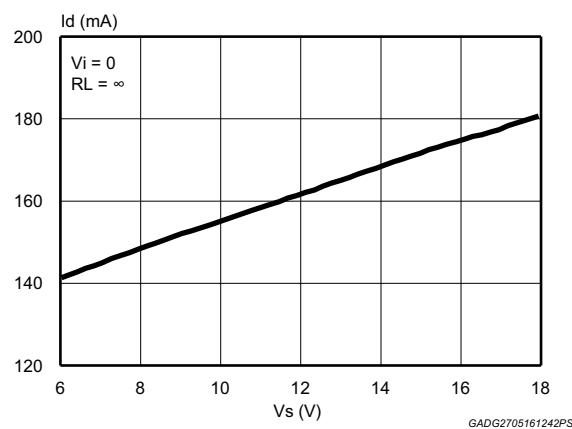


Figure 6. Output power vs. supply voltage (4 Ω)

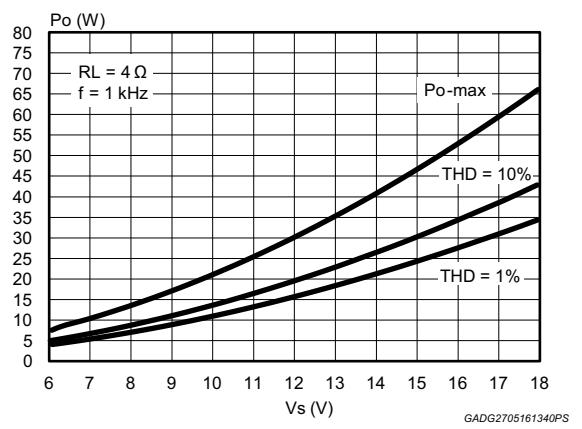


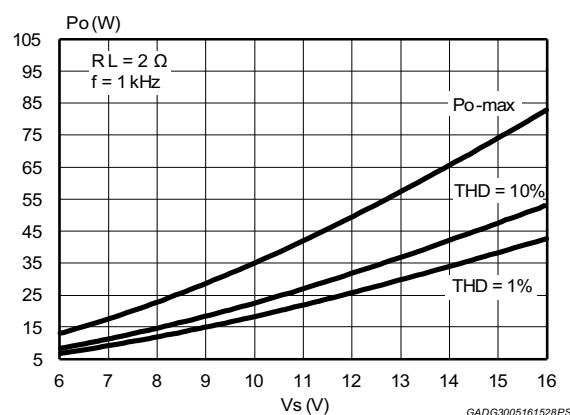
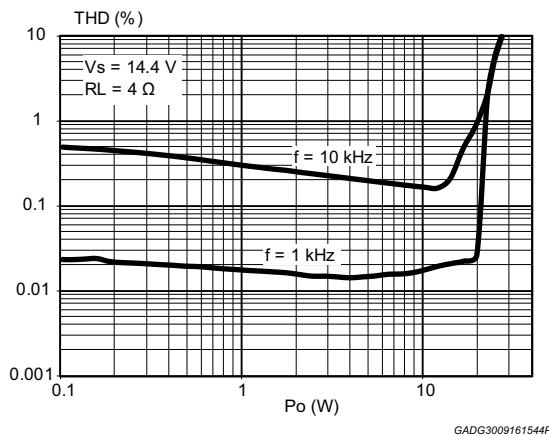
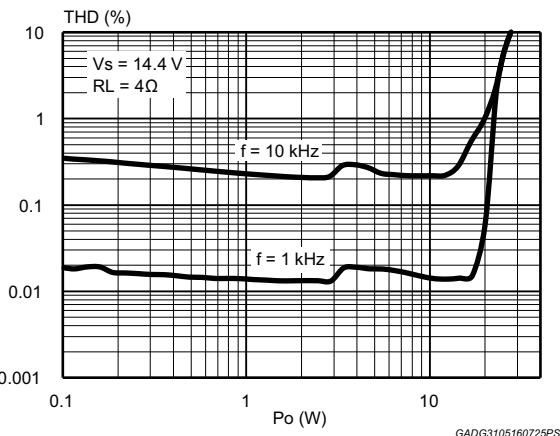
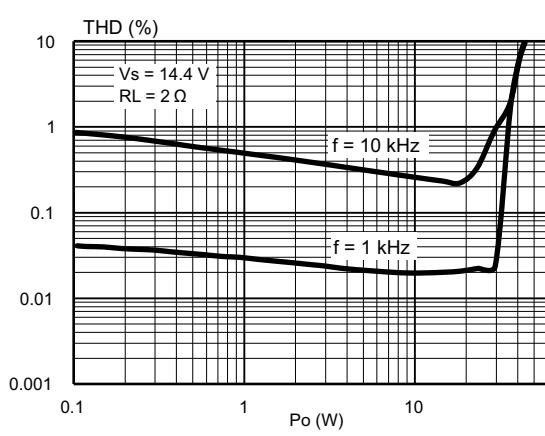
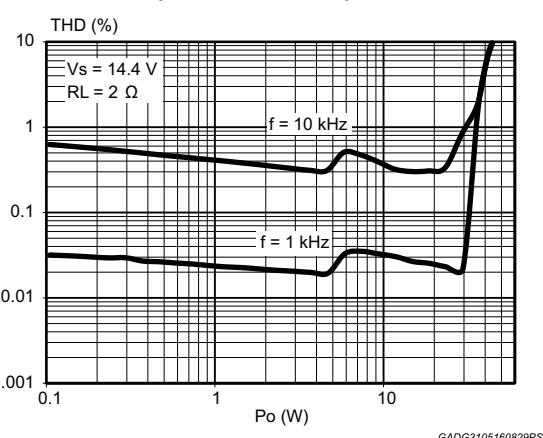
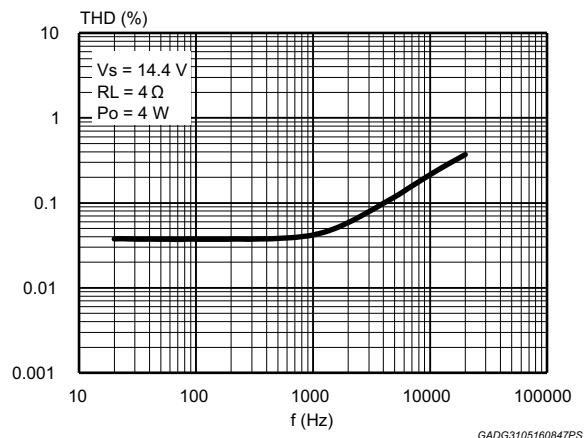
Figure 7. Output power vs. supply voltage (2 Ω, STD mode)**Figure 8. Distortion vs. output power (4 Ω, STD mode)****Figure 9. Distortion vs. output power (4 Ω, SBI mode)****Figure 10. Distortion vs. output power (2 Ω, STD mode)****Figure 11. Distortion vs. output power (2 Ω, SBI mode)****Figure 12. Distortion vs. frequency (4 Ω)**

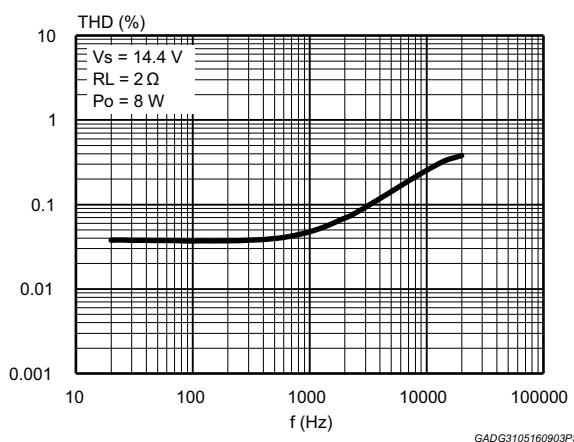
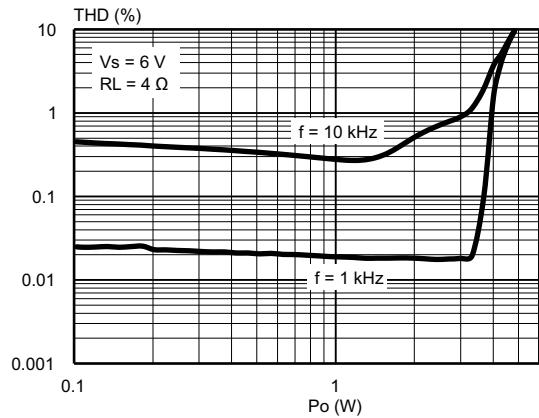
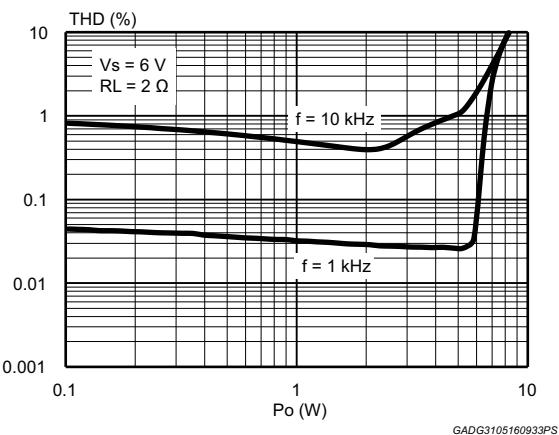
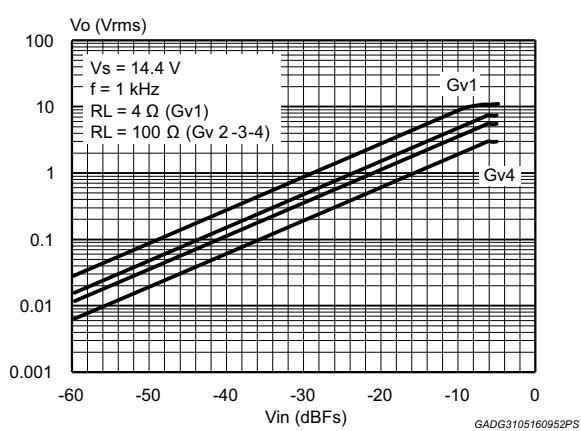
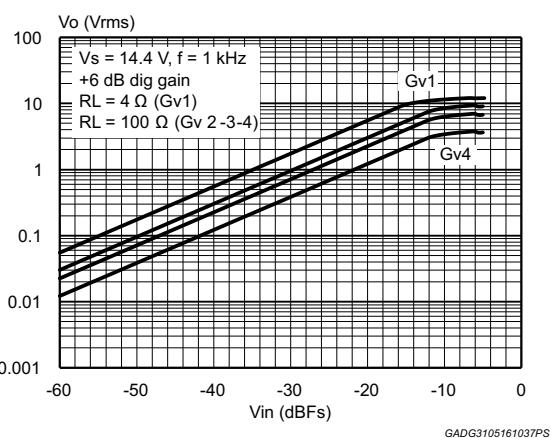
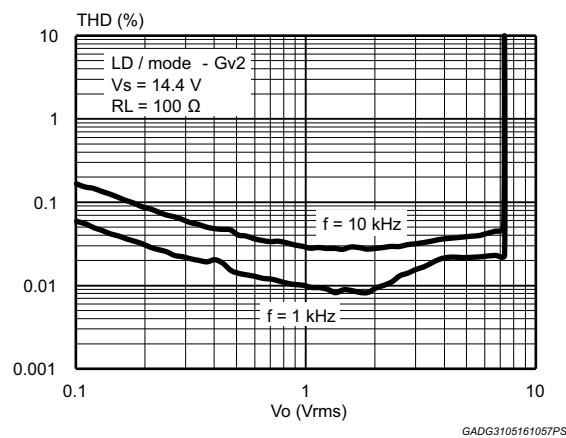
Figure 13. Distortion vs. frequency (2 Ω)**Figure 14. Distortion vs. output power (4 Ω, Vs = 6 V)****Figure 15. Distortion vs. output power (2 Ω, Vs = 6 V)****Figure 16. Vo vs. Vin (Gv1-2-3-4 settings)****Figure 17. Vo vs. Vin (Gv1-2-3-4 settings + 6 dB dig. gain)****Figure 18. Distortion vs. output voltage (LD-Gv2)**

Figure 19. Distortion vs. output voltage (LD-Gv3)

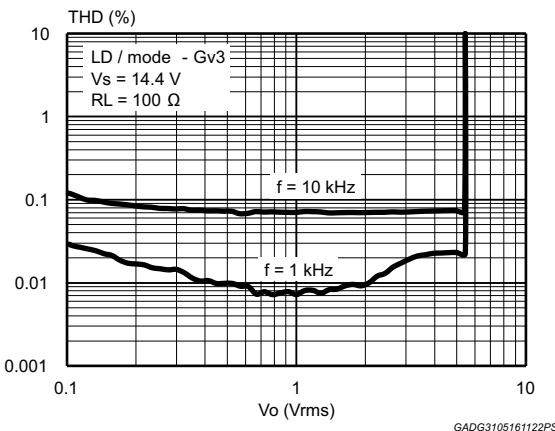


Figure 20. Distortion vs. output voltage (LD-Gv4)

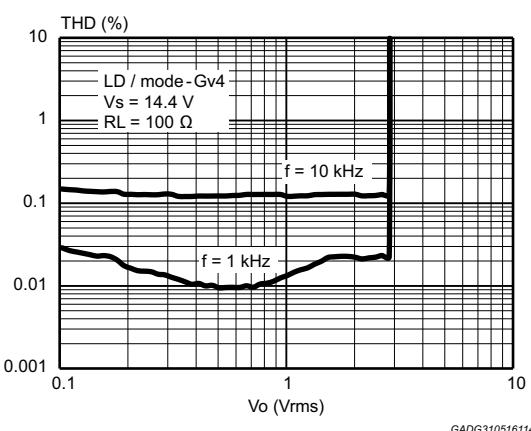


Figure 21. Output attenuation vs. Vs

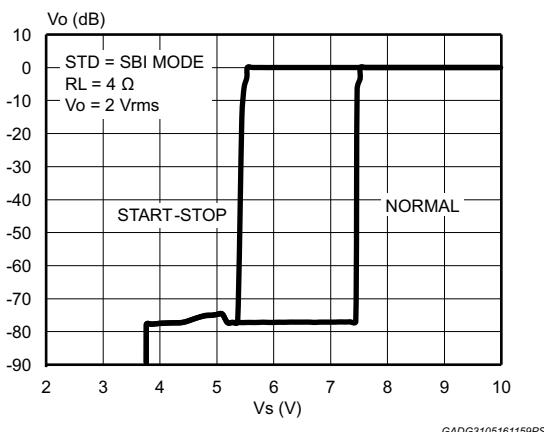


Figure 22. Crosstalk vs. frequency (STD mode)

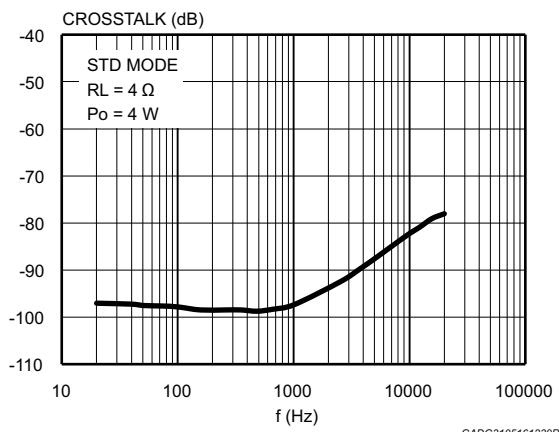


Figure 23. Crosstalk vs. frequency (SBI mode)

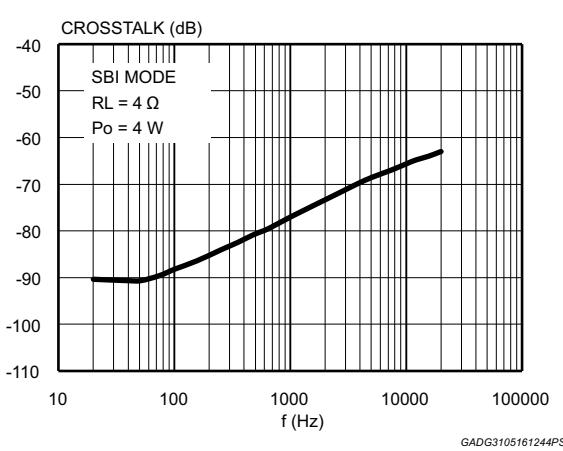


Figure 24. Supply voltage rejection vs. frequency

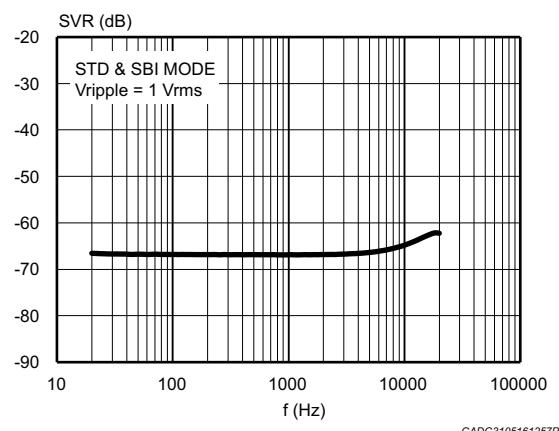
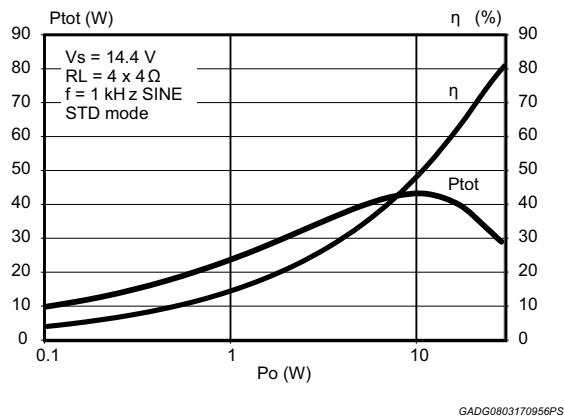
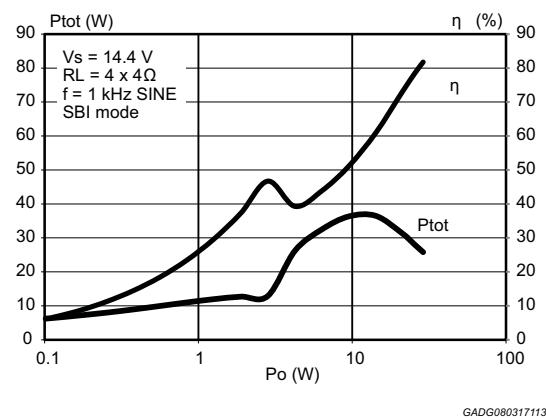
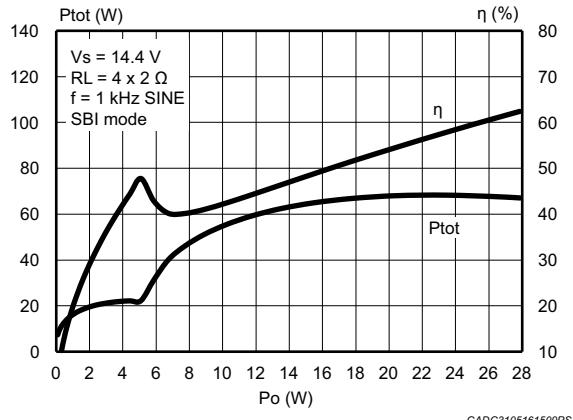
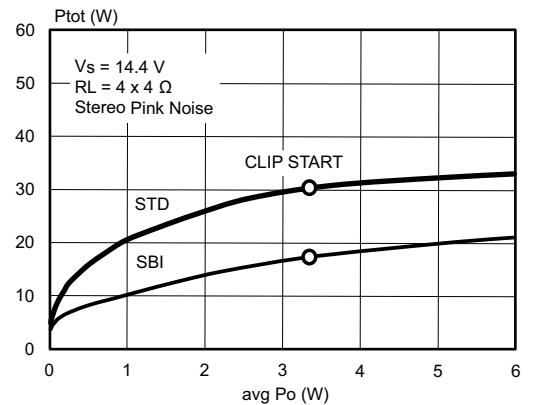
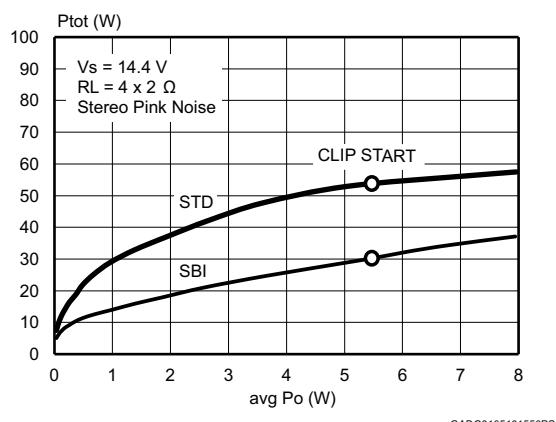
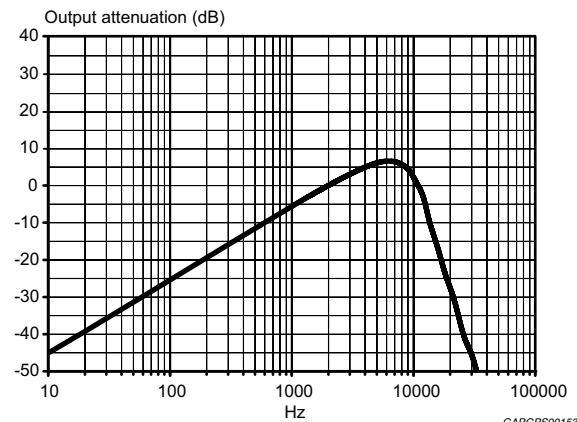


Figure 25. Total power dissipation & efficiency vs. Po (4 Ω, STD, Sine)**Figure 26. Total power dissipation & efficiency vs. Po (4 Ω, SBI, Sine)****Figure 27. Total power dissipation & efficiency vs. Po (2 Ω, SBI, Sine)****Figure 28. Power dissipation vs. average Po (audio program simulation, 4 Ω)****Figure 29. Power dissipation vs. average Po (audio program simulation, 2 Ω)****Figure 30. ITU R-ARM frequency response, weighting filter for transient pop**

4 Operation states

TDA7803A functionality is regulated by means of a finite state machine.

Finite state machine diagram is reported in [Figure 31](#).

Main states are:

- Standby
- ECO-mode
- Amplifier mode
- Turn-on diagnostic
- Permanent diagnostic

4.1 Standby state

When STBY pin is under VILSTBY voltage the amplifier is in stand-by state and the current consumption is very low.

4.2 ECO-mode state

When STBY pin is over VIHSTBY the amplifier is in a state of low current absorption, the ECO-mode. The short circuit protections are active and the amplifier is ready for receiving commands from micro-controller through I²C interface.

Outputs and A3V3 supply are biased at 0 V.

4.3 Amplifier-mode state

When TDA7803A is in ECO-mode state, IB7-d0 is set to "1", (Amplifier-ON), and I²S clock is present the amplifier moves to Amplifier-mode state.

The outputs are biased from 0 V to Vcc/2 and the current consumption reaches "Iq" level until the amplifier is set in MUTE or in PLAY with low level signal. User can move the amplifier from MUTE to PLAY and viceversa acting on IB2-d4, d3 bits.

A hardware unmute pin is available in PSO36 package only.

4.4 Turn-on and permanent diagnostic

TDA7803A provides a powerful and precise diagnostic both with speaker and line driver loads.

There are two main diagnostic states:

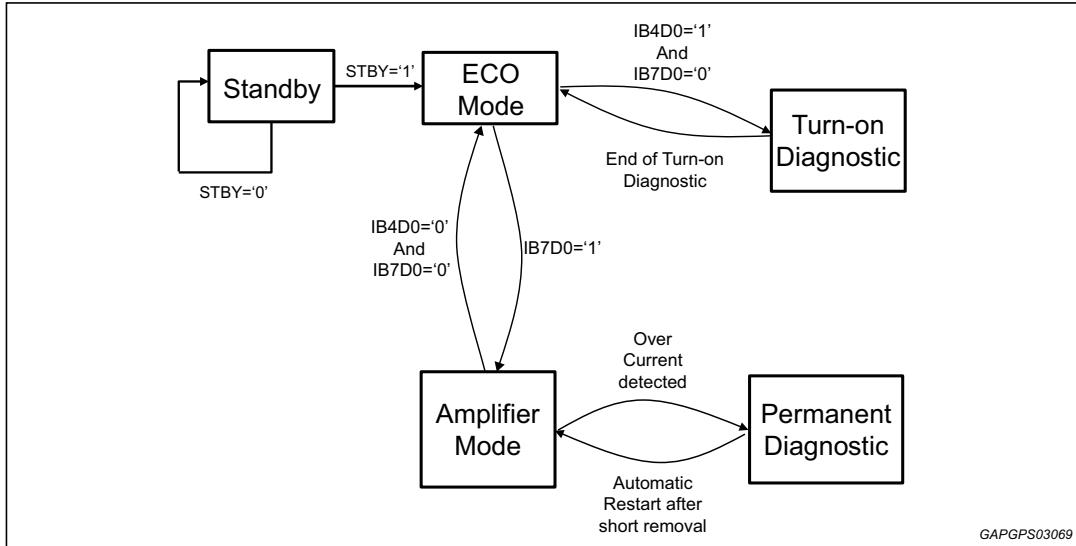
- Turn-on diagnostic
- Permanent diagnostic.

The Turn-on diagnostic could be run in ECO-mode state and is suggested for sensing the presence of faults before amplifier turn-on, in order to avoid unwanted or dangerous conditions due to wrong connections or absence of load.

The Permanent diagnostic is automatically run by TDA7803A when a fault occurs during PLAY and over current protections are triggered.

Turn-on and Permanent diagnostic functionality are described in [Section 6](#).

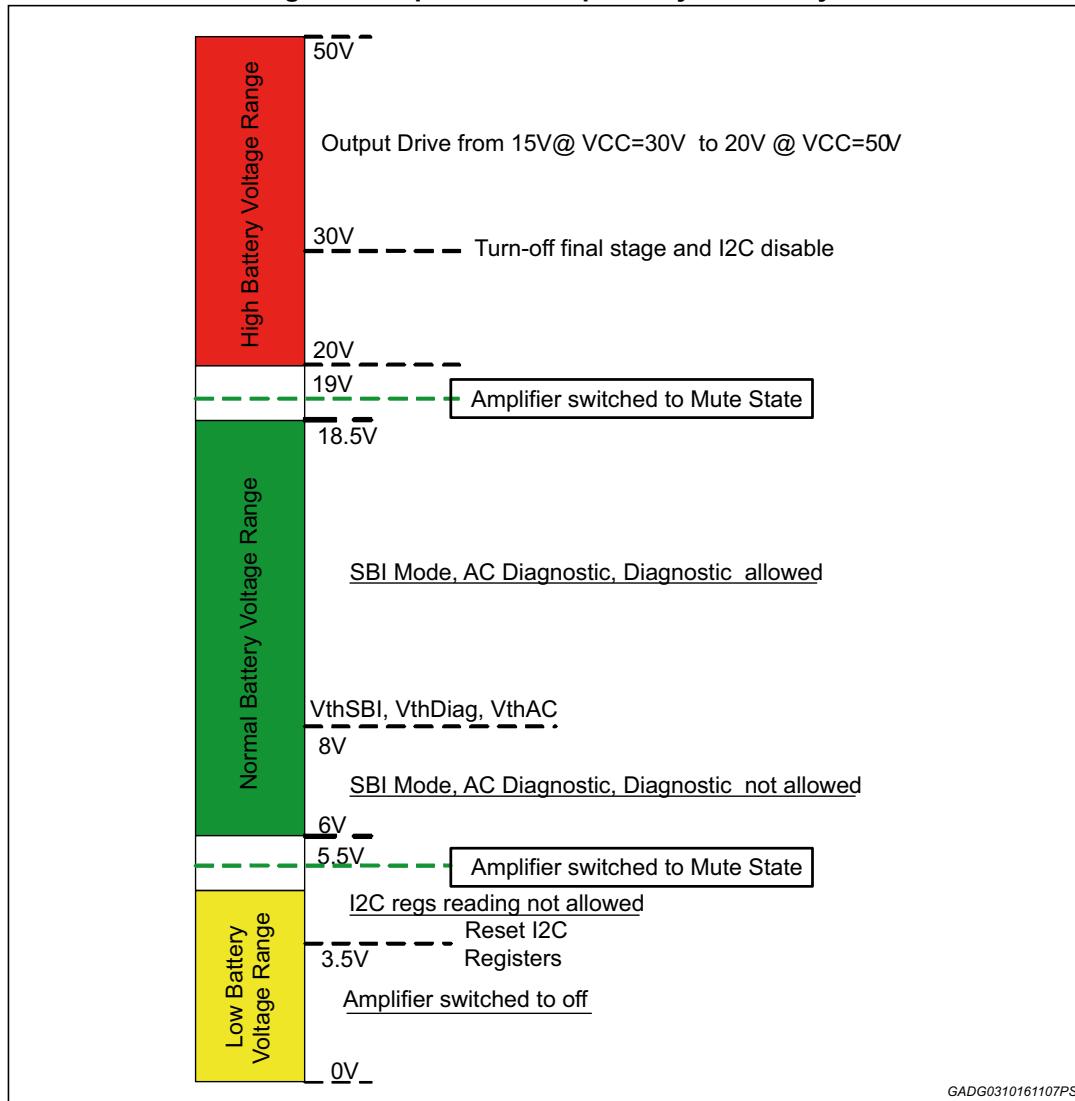
Figure 31. State diagram



5 Operation compatibility vs. battery

Here below the operation compatibility vs. the battery value is shown. For each battery voltage range, only a limited number of functions are available as it is shown below:

Figure 32. Operation compatibility vs. battery



6 Functional description

6.1 Voltage regulators timing

Pins D3V3 and A3V3 are respectively digital and analog internal regulators outputs. The D3V3 rises right after the STBY pin is at the logical value "1" and its rising time depends on the filter capacitor; the minimum value suggested for this filter is 4.7 μ F.

The A3V3 rises after any command that moves the amplifier from ECO - mode; the rising time depends on the combined effect of the external capacitor on the pin and of an internal 2 ms ramp: if the capacitor value is 22 μ F or lower, the internal ramp effect is dominant and the rising time will be about 2 ms. On the other hand, when the capacitor has a higher value, the rise time will be higher as well. The suggested value for this capacitor is 22 μ F at least.

6.2 Turn-on diagnostic description

The turn-on diagnostic is triggered on the rising edge of bit IB4 D0 when IB7 D0 is "0". This happens when the amplifier is in ECO - mode. It is possible to run one or more turn-on diagnostic sequences according to the following procedure:

1. wait the previous cycle is over
2. read the data bytes DB1,DB2,DB3 and DB4

Please note that all these instructions must be sent while the amplifier is still in ECO - mode (IB7 D0 = "0"), otherwise they won't be executed.

Turn-on diagnostic does not start if V_{CC} is below 8 V or one of the muting condition is present, (low battery mute, high voltage mute, PLL-unlock mute, thermal mute, hardware pin mute).

Note: The diagnostic enable bit (IB4 D0) must be set before the amplifier mode bit (IB7 D0).

DB1, DB2, DB3 must be read before DB4 (after DB4 is read the DB1-2-3-4 are reset).

The detected faults are here described:

Soft Short to GND: it detects the presence of a resistor (see [Table 5](#) in "Turn-on diagnostic" section) connected between an output and ground, which could result in a wrong open load or short across load diagnostic result (causing an anomalous current consumption in some cases).

Soft Short to VS: it detects the presence of a resistor (see [Table 5](#) in "Turn-on diagnostic" section) connected between an output and battery, which could result in a wrong open load or short across load diagnostic result (causing an anomalous current consumption in some cases).

Short to GND: it detects the hard connection between an output and ground. The value of the short is able to pull the output between 1.5 V and ground.

Short to VS: it detects the hard connection between an output and battery. The value of the short is able to pull the output between (battery - 1.5 V) and battery.

Short across the speaker: it detects the hard connection across the speaker that is below a certain value. This value guarantees that the IC is able to drive any speaker configuration within the range specified in the datasheet.

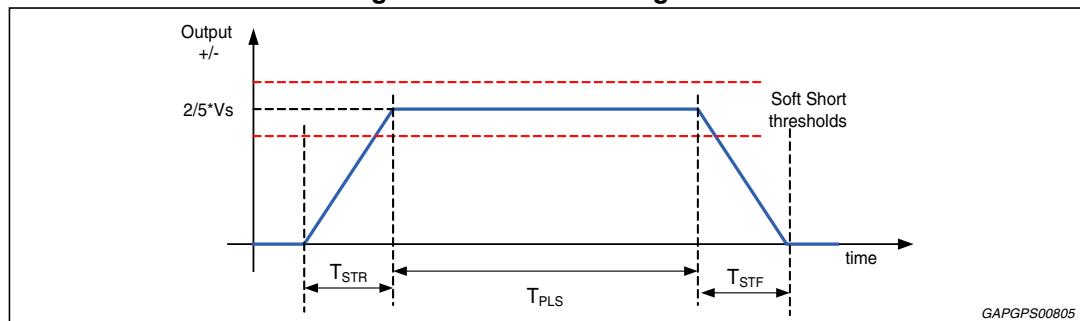
Open Load: it detects a non connected speaker condition.

The diagnostic's results are stored into DB1, DB2, DB3 and DB4 data registers (one for each channel) after the diagnostic is over.

The flow of the diagnostic includes some steps as described below.

- During the first part, the soft-short evaluation is performed. The outputs and an internal reference line are pulled up to a voltage of $2/5 \cdot V_{battery}$ in a time T_{STR} and then compared for a time T_{PLS} . During the plateau time, the comparator outputs are read from the digital part. The outputs are then pulled down to zero (see [Figure 33](#)). The A3V3 supply is 0V and the output stage is in tri-state during this phase.

Figure 33. Soft short diagnostic



- If a soft short is detected, the short to GND/VCC evaluation follows. Pin A3V3 goes up as the amplifier stage is turned on; the power and the outputs are risen up to $1/2 \cdot V_{battery}$ and then compared to $(V_{battery} - 1.5 \text{ V})$ and 1.5 V for a time T_{PLS} . At the end of the plateau (T_{PLS}) output and A3V3 go back to 0V and the results obtained are written into the I²C Bus registers once the diagnostic is over. For soft short resistance above the defined thresholds, the normal, short or open load recognition is guaranteed.

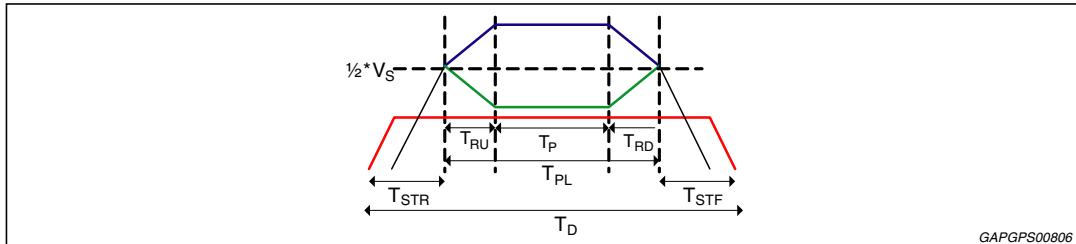
In case the short to VCC or GND is detected during this phase a '1' is written in DBx-D1/D0 (VCC/GND) but not in DBx-D6. In case the hard short is not detected a '1' is written all DBx-D6.

The turn-on diagnostic is then completed and the amplifier goes back to the ECO - mode.

- However, if a soft short is not detected, then we can also exclude the Short to Vs/GND, and don't need to be checked. In this case, short across the speaker and the open load evaluation can be performed. Pin A3V3 goes up as the amplifier stage is turned on and the outputs are risen up to $1/2 \cdot V_{battery}$. A first pulse for "Short load detection" is done: exploiting the presence of a D/A converter, a subsonic (inaudible) voltage pulse is digitally and internally generated and converted. The pulse amplitude increasing is stopped when the current flowing through the speaker $I_{speaker}$ is the same as a prefixed one I_{high} (high current) or because it reaches the maximum value permitted. Since the differential output voltage V_o is well known, it is possible to keep monitored the value of the connected speaker during the transition and plateau. In the case the $I_{speaker}$ will get to an higher value than I_{high} , $V_o < V_{short}$ (short circuit threshold) the result is short load (DBx - D3 = '1'), otherwise it is normal load (DBx - D3 = '0'); when $I_{speaker}$ does not reach I_{high} the turn-on diagnostic is not completed yet because the result could be still normal or open load.
- This is called "Open load detection". If IB4 D1/D2 = 1 the power DMOS need to be changed again: the outputs are pulled down to zero, the DMOS are switched and then the outputs raised up to $1/2 \cdot V_{battery}$ again. This sequence is done in order to avoid any pop noise during the power set. The procedure is the same as the previous case or in

case of $IB4$ ($D1/D2 = 0$). The pulse amplitude is stopped when the current flowing through the speaker I_{speaker} is the same as prefixed one I_{low} (low current) or because it reaches the maximum value permitted. When I_{speaker} reaches the value I_{low} and $V_o < V_{\text{open}}$ (open load threshold) then the speaker can be considered as a normal load ($DBx-D2='0'$). In all other cases the result will be open load ($DBx-D2='1'$) (see [Figure 34](#)).

Figure 34. Short circuit and open load diagnostic

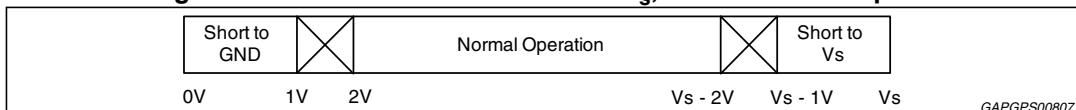


The whole diagnostic time depends on the number of pulses that are done. At least two pulses are done, but they could be three in case of open load. The values inserted into the [Table 6](#), are calculated basing on $F_s = 48000$ Hz.

In all cases the fault is sent out to the registers only if it is stable throughout the whole plateau period. If this condition is not respected, any possible misconnections (Soft-short, Short to VCC/GND, Short Across or Open Load) won't be reported. The faults for the turn-on diagnostic are written in DB (1, 2, 3, 4) ($D1, D2, D3, D4$) (a byte for each channel and a bit for each fault). They are consistent if $DB0 D6 = "1"$. After a reading the data byte are reset.

The fault-detection thresholds for short to GND/ V_s remain unchanged independently from the gain setting. They are as in [Figure 35](#).

Figure 35. Short to GND and short to V_s , threshold description



Concerning the short across the speaker / open speaker, the threshold changes from line driver mode and speaker mode diagnostic setting, as load expected are pretty different (either normal speaker's impedance or high impedance). Speaker or line driver mode is selectable from $IB4$ $D2$ for channels 1 and 3 and $IB4$ $D1$ for channel 2 and 4. The values in case of speaker mode are as in [Figure 36](#). The same thresholds will change as in [Figure 37](#), if line driver mode diagnostic is selected.

Figure 36. Short across the speaker and open load threshold description, in speaker mode

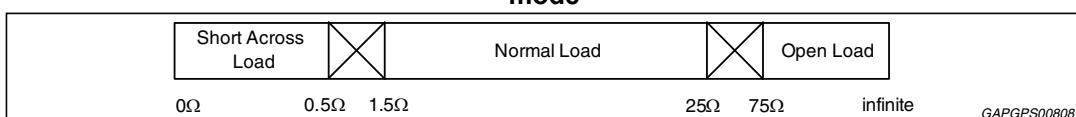


Figure 37. Short across the speaker and open load threshold description, line driver mode

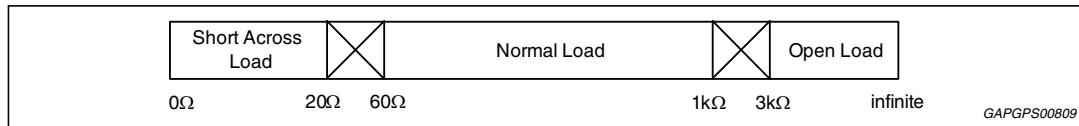


Table 6. Start-up pulse typical timings ($F_s = 48$ kHz)

Symbol	Parameter	Min	Typ	Max	Unit	Note
T_{STR}	Time to rise the outputs from 0V to a certain battery's percentage	-	10 (+ 10)	-	ms	When A3V3 goes up, the reported number has to be added
T_{STF}	Time to rise the outputs from a certain battery's percentage to 0V	-	10 (+ 10)	-	ms	When A3V3 goes down, the reported number has to be added
T_{PLS}	Plateau time for soft-short and short to VCC/GND diagnostic	-	80	-	ms	This time parameter is load independent and is not stretchable setting bit IB6[7:5]
T_P	Plateau time for short circuit or open load diagnostic detection phase	-	80 ⁽¹⁾	-	ms	$T_P = 86 \text{ ms} \cdot X$ when $140 \text{ ms} - 2 \cdot T_{RU} > 80 \text{ ms}$
						$T_P = (140 \text{ ms} - 2 \cdot T_{RU}) \cdot X$ when $140 \text{ ms} - 2 \cdot T_{RU} < 80 \text{ ms}$
T_{PL}	Pulse time for short circuit or open load diagnostic detection phase	-	120	122.4 ⁽²⁾	ms	$T_P = (2 \cdot T_{RU} + T_P) \cdot X$
X	Multiplier factor in case of diagnostic active	-	1,2,4,8	-	-	IB6[7:5] setting
$T_{RU}=T_{RD}$	Ramp-up and ramp-down diagnostic pulse's time	-	5.8 ⁽³⁾	-	-	2 ohm case
						4 ohm case
T_{SS}	Soft-short diagnostic time	-	100	-	ms	Output rising time + Output falling time + plateau time (no A3V3)
T_{HS}	Short to VCC and GND diagnostic time	-	120	-	ms	A3V3 rising and falling time (10 ms x2) + Output rising and falling time + plateau time
T_D	Short load and open load diagnostic time	-	148	-	ms	2 ohm case (X=1)
						4 ohm case (X=1)
T_{tot}	Total diagnostic time	-	260	-	ms	4 ohm load and no faults ($T_{tot} = T_{SS} + T_D$)
						Hard or soft short to supplies ($T_{tot} = T_{SS} + T_{HS}$)
						Open load (X = 1, IB4 (D1/D2) = 0) $T_{tot} = T_{SS} + T_{D1} + T_{D2}$

Table 6. Start-up pulse typical timings ($F_s = 48$ kHz) (continued)

Symbol	Parameter	Min	Typ	Max	Unit	Note
I_{high}	Test current for the short load pulse	-	200 40	-	mA	For speaker mode For line driver mode
I_{low}	Test current for the open load pulse	-	40 2	-	mA	For speaker mode For line driver mode

1. For typical loudspeaker of 2 and 4 ohm.
2. These numbers are evaluated in simulation.
3. Typical values for 4 Ω and 2 Ω and zero offset. These numbers depend on the loudspeaker and also on the intrinsic offset of the amplifier. For 2 Ω loudspeaker, -30 mV offset and $F_s = 48$ kHz $T_{RU} = 21.2$ ms; for 4 Ω and same surrounding conditions $T_{RU} = 22.1$ ms. Under these conditions $T_{PL} = 122.4$ ms for 2 Ω and 124.4 for 4 Ω . For higher values the number are not reported here.

When the amplifier is biased and the IB4 D0 = "1", the permanent diagnostic is enabled. The turn-on diagnostic state is held until an over current event is triggered. When this happens, a new diagnostic cycle can start.

6.3 Permanent diagnostic

The detectable faults are (see [Table 5](#) for definitions):

- Short to GND
- Short to Vs
- Short across the speaker

Then following additional features are also provided:

- Input offset detection
- AC diagnostic

When an over current event occurs, TDA7803A has two different cycles that could react with:

- Restart cycle: it is a 2 ms pulse. During this period a check of the output is performed.
- Plateau cycle: it is an 80 ms cycle. During this period a check of the outputs is performed and the results of diagnostic analysis are written into the I²C bus.

TDA7803A has two different operating behaviors when an over current event is detected:

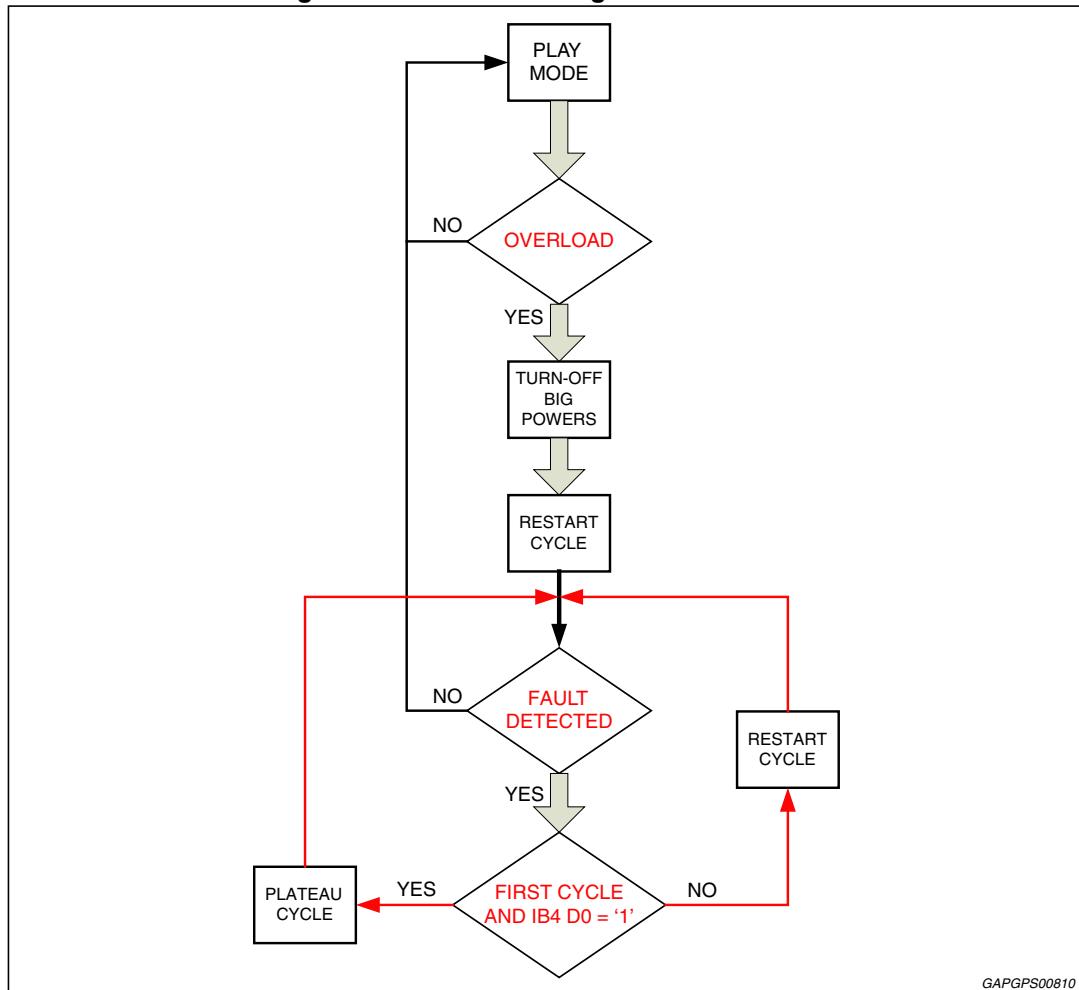
- Restart mode, (IB4 D0 = "0"). The diagnostic is not enabled. Each audio channel operates independently from each other. If any of the above mentioned faults occurs, only the channel(s) where the fault happened is shut down. The diagnostic performs restart cycles every 2 ms until the fault condition is present. The amplifier restarts in play only once the overload is removed. In Restart mode reporting diagnostic results are turned off and the corresponding bits in the channels' data byte registers will be reset accordingly.
- Diagnostic mode, (IB4 D0 = "1"). It is enabled via I²C and self activated if an output overload occurs to the speaker outputs. If any of the above mentioned faults occurs,

only the channel(s) where the fault happened is shut down. Once activated, the diagnostic procedure develops as below:

- The diagnostic performs one restart cycle in order to avoid momentary recirculation spikes which could give erroneous results. If a normal state (no overloads) is detected, the channel returns back active.
- Instead, if after the restart cycle, the overload is still detected, then the diagnostic performs a plateau cycle.
- After the plateau cycle, a restart cycle is going to be performed every 2 ms until the fault condition is removed. The data acquired from the plateau cycle are stored and can be read from the microprocessor. If the fault condition persists, a new plateau cycle can be programmed from I²C simply by reading. This ensures continuous diagnostic throughout the car-radio operating time.

For a more immediate understanding, the permanent diagnostic's flowchart is as in *Figure 38*.

Figure 38. Permanent diagnostic flow-chart



When a plateau cycle is done during the permanent diagnostic the bit D5 of byte connected to the channel where the overload occurred is set to "1". If all the bits related to the diagnostic are "0", then the fault has possibly been removed or not detected. Eventually, an

over current event could have been occurred on a loudspeaker with a very high inductance and it took more than 2 ms to get the current reduced.

A plateau cycle can be recalled by means of a reading procedure of bytes DB1/2/3/4 when the amplifier is performing the restart cycle. As for the turn-on diagnostic, when DB4 is read DB1/2/3/4 are reset, therefore the incremental reading is suggested in order not to miss any data.

Please note that if the over-current cause was removed before the reading the plateau cycle cannot restart.

6.4 AC diagnostic

The goal of this feature is to detect accidental disconnection of tweeters in 2-way speaker and, more in general, the presence of capacitive (AC) coupled load. This diagnostic is based on the notion that the overall speaker's impedance (woofer + parallel tweeter) tends to increase towards high frequencies if the tweeter gets disconnected. This happens because the remaining speaker (woofer) would be out of its operating frequency's range (high impedance).

To determine the load impedance, a sine wave tone of a suitable frequency should be provided to the output pins and the AC diagnostic is able to determine if the tweeter is connected or not. The tweeter is not connected if for four consecutive sine waves the current threshold on the load is not crossed.

AC diagnostic is managed by I²C commands. When IB4 D3 = "1", the AC diagnostic is enabled; IB4 D4 is used to choose the current level threshold to be used as a reference for the test.

The results of the AC diagnostic test are stored in DB5 D3..6. It is written "1" if the tweeter for that channel is present.

The AC diagnostic is able to give the correct results only if the input signal $V_{out} < V_s - 4V$. User knows that this condition is verified by reading "0" in DB5 D7. When DB5 D7 = "0", it mean that the test's signal was too high.

6.5 Input offset detector

Input offset detector aim is to avoid any possible offset that could come from the audio signal source through I2S/TDM input stream.

For this purpose the TDA7803A input offset detector performs an evaluation of the input signal and calculates if an offset with values higher than -19.5 dBFS is present.

Moreover, if high pass filter function is selected by means of IB3-d0, the TDA7803A will eliminate the input offset giving a complete robustness to any disturbance or malfunction coming from external audio chain blocks.

The input offset detector and high-pass filtering can be used during PLAY mode.

6.6 Double faults

Faults can occur simultaneously. When this happens, faults are read out in accordance with the priority table ([Table 7](#)).

Please note that a "short to GND" and a "short to V_S " can be simultaneously read only when an open load is present; however it would mean three faults at the same time, which is not covered by TDA7803A.

Table 7. Double faults priority

-	Soft short to GND ⁽¹⁾	Soft short to V_S ⁽¹⁾	Short to GND	Short to V_S	Short across load	Open load ⁽¹⁾
Soft short to GND	Soft Short to GND	/	Short to GND	/	Soft Short to GND	Soft Short to GND
Soft short to V_S	/	Soft Short to V_S	/	Short to V_S	Soft Short to V_S	Soft Short to V_S
Short to GND	Short to GND	/	Short to GND	/	Short to GND	Short to GND
Short to V_S	/	Short to V_S	/	Short to V_S	Short to V_S	Short to V_S
Short across load	/	/	/	/	Short across load	N.A.
Open load	/	/	/	/	/	Open Load

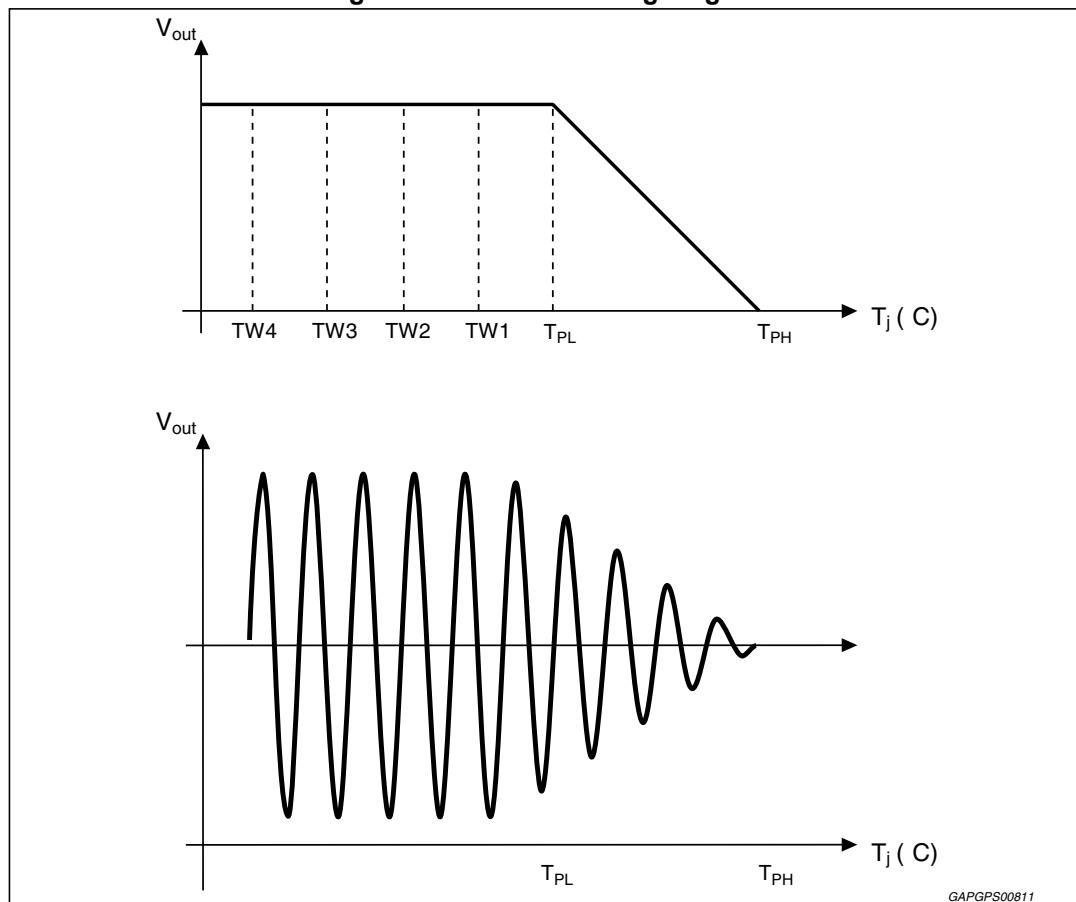
1. Open load, soft short to GND and soft short to V_S are only available for the turn-on diagnostic; in fact the permanent diagnostic can be triggered from an over current event, and none of these events can be the cause of an over current.

6.7 Thermal protection

The TDA7803A has four thermal warning thresholds (Tw_1 , Tw_2 , Tw_3 , Tw_4) which are stored in I^2C data bytes. Only one of the thermal warnings can be sent to the pin CDdiag and it is selectable via I^2C bus.

A temperature dependent mute function is implemented in order to protect the junction against over temperature events and prevent the IC from sound quality degradation. For temperatures higher than T_{pl} , the device is gradually forced to the mute state. When the temperature is T_{pl} the output signal is attenuated by 0.5 dB, while at the T_{ph} the attenuation is >60 dB. The distortion is kept low throughout the whole muting transition. The thermal protection's behaviour is shown in [Figure 39](#).

Figure 39. Thermal muting diagram



6.8 Voltage monitoring feature and ADC characteristics

Through this feature it is possible to monitor the V_{CC} value on I²C data line; below a short description of the limits, granularity, frequency of operation of this function.

The result of V_{CC} sensing voltage range is 5 V - 19 V; the V_{CC} - ADC value conversion is expressed in the table below. The V_{CC} sensing voltage range is 5 V - 19 V (with a typical reset intervention at 4.8 V), with a precision of 200 mV effective (considering 1 bit of noise). The output update frequency is 2 MHz.

So, in order to exploit this function, the user should address only the DB7 with the following subaddress: '10011010' (*) and then read the data contained in DB7.

(*) 'I' is the auto increment bit.

The V_{CC} value is expressed by 8 bits binary code:

Table 8. V_{CC} value express by 8 bit with thermometric code

V_{CC}	ADC value
5 V	01000001
6 V	01010000
7 V	01011101

Table 8. V_{CC} value express by 8 bit with thermometric code (continued)

V_{CC}	ADC value
8 V	01101011
9 V	01111001
10 V	10000110
11 V	10010100
12 V	10100010
13 V	10101111
14 V	10111101
14.4 V	11000010
15 V	11001011
16 V	11011001
17 V	11100110
18 V	11110100
19 V	11111111

6.9 Mute management

The transition Mute → Play can happen once the device is in amplifier mode and IB2-D3/D4 = "1" or after it has been put in mute for one of the causes listed in [Table 9](#). It is done by means of a digital ramp whose time constant is programmable by IB2 D7, D6 and D5 bits.

The transition Play → Mute occurs when certain conditions are verified and it can be Digital or Analog. An overview of all the events that might happen is reported in the [Table 9](#).

Table 9. Transition play to mute strategy

Cause of transition Play → Mute	When it happens	Analog	Digital
I ² C instruction	When bit IB2 D4,D3 = "0" (Mute command)	No	Yes Timing for transition is fixed by IB2 D7, D6, D5
Low battery mute	When there is a battery dip and the Vs goes below the auto mute threshold (selectable by IB2 D1)	Yes	IB2-D2 = 0: Yes IB2-D2 = 1: Disable If digital mute is enabled, timing for transition is fixed by IB2 D7-D6-D5
High battery mute	When Vs ramp up above 19V	Yes	No
PLL un-lock	The PLL lock detector goes down for some reason	Yes	Not possible because in case of un-lock, digital core is reset so not working
Thermal mute	When Tw1 is "1"	Yes	Disabled
Tristate command	No	Yes	Timing for transition is fixed by IB2-D7, D6, D5

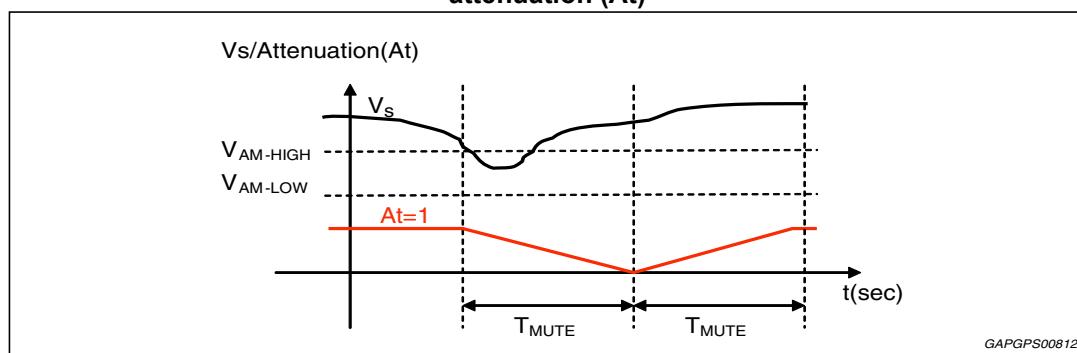
6.9.1 Auto-mute threshold

The device in play mode is put in mute when the supply voltage gets below the V_{lowM} threshold.

The muting strategy for this kind of event is reported in [Figure 40](#). Both analog and digital mute start when the supply voltage is below V_{lowM_HIGH} . The digital mute transition lasts a period T_{MUTE} . The analog mute attenuation is proportional to V_s ; when V_s is at V_{lowM_LOW} the mute attenuation is A_M .

Note that, once it is engaged, the digital mute procedure will apply the A_M attenuation. It is not possible to stop it and move the device to play mode in advance. The concept of this procedure is to avoid that fast oscillation on V_s can generate fast oscillation on the output.

Figure 40. Low voltage mute attenuation, supply voltage variation (V_s); result digital attenuation (A_t)



When the battery goes below the auto-mute low threshold, it is possible to disable the digital muting if IB2 D2 = "1". In this case the mute will be only analog.

The digital mute is also disabled during the turn-on diagnostic.

6.9.2 Mute and unmute commutation time

Table 10. Mute and unmute commutation time

Parameter	Test condition	Typ.	Unit
Mute and unmute commutation time	Programmable by I ² C bus register IB2(7:5) $F_s = 44.1$ kHz	1.45	ms
		6	
		12	
		25	
		45	
		90	
		180	
		370	

6.10 Class SBI - Improved high efficiency principle

TDA7803A embeds an improved high efficiency feature that minimizes the power dissipated through the heat sink basing on the musical signal characteristic. All channels are connected to a common bar by means of four power switches. When an input signal goes

under a threshold that depends on the Vs level, the switch will short the corresponding output to the common bar in such a way that it can exchange current with the other channel. The dissipation reduction can be up to 50% compared to standard AB class.

The TDA7803A sets the high efficiency mode by default, but it can be changed through the bits IB0 D3, D2, D1 and D0.

6.11 High power and parallel mode configuration

The TDA7803A is able to support high power applications thanks to its characteristics. Whenever a higher output power with low impedance loads is needed (i.e. 2ohm load), it is recommended to enable the current capability enhancer through the IB5[4:1] register.

When needed, the TDA7803A can also support the parallel mode configuration. The functionality is allowed since the two output powers gates (master and slave) are shorted together and only one of the two drivers is effectively working (the master). At the same time the outputs are shorted on the application in such a way to minimize the resistive path.

The I2C bits IB6-d2,d3 are reserved for this function, as it follows:

Bits (D3, D2):

- "00" single channel mode configuration for all channels;
- "01" (ch1 and ch2): parallel mode configuration, (ch3 and ch4): single channel mode configuration;
- "10" (ch1 and ch2): single channel mode configuration, (ch3 and ch4): parallel mode configuration;
- "11" all channels set in parallel mode configuration.

The master channels are channel 1 when ch1 and ch2 are configured in parallel mode, and channel 3 when ch3 and ch4 are configured in parallel mode.

6.12 Power on reset threshold

When V_{CC} is lower than 4 V the integrity of I2C registers content is not guaranteed. In this case the I2C registers are reset and the TDA7803A is put in Eco-mode state. This event is communicated with a "0" on DB0-d7 I2C bit.

7 Additional features

7.1 Noise gating

Noise gating is an automatic noise reduction feature that activates when output signal reaches inaudible levels.

When input signal level falls below -102dBFS the system activity is automatically optimized in order to limit the output noise level as much as possible and permits the full audio chain to bring very low noise level on the output speakers.

The noise gating process has a 100ms observation time before turning on, in order to avoid spurious activations.

The feature is enabled by default and can be disabled selecting IB3-d2.

7.2 Tri-state mode

It can be activated by IB0-4..7= 1. It allows to turn-off one or more channels by individually disabling it or them by turning to a safety mode status (high impedance) whenever an overload is detected by the diagnostics, in order to prevent any other inconveniences. All the other sections not interested by a fault will remain completely operational. The tri-state mode has to be used with the IC preventively set to Standard Class-AB mode (IB0-D0..3 = 1). Not to be used as an alternative to "IB7-D0" command (amp on/off during normal operation)

8 I²S and TDM bus interface

The audio input port is a three/four-wire synchronous serial interface that can operate only as Slave. Pins SD13 and SD24 are the serial data inputs. The audio data format accepted from TDA7803A is the I²S standard.

Input data can also be sent in time division multiplexed (TDM). Pins SCK (bit clock) and WS (frame select) complete the I²S interface.

When I2S-clk is lost during amplifier operations a protection circuit acts and puts the amplifier in a safe condition: amplifier short circuit protections are guaranteed, dump protection is guaranteed, signal is muted and outputs bias is under control.

In order to avoid other side effects user should put the amplifier in standby moving STBY pin to 0 V.

8.1 I²S and TDM input data frame format

The audio data word length for each channel may be up to 24 bit. Either for I2S or TDM mode, the frame for each channel has 32 bit length.

The following table summarizes the frequencies configurations.

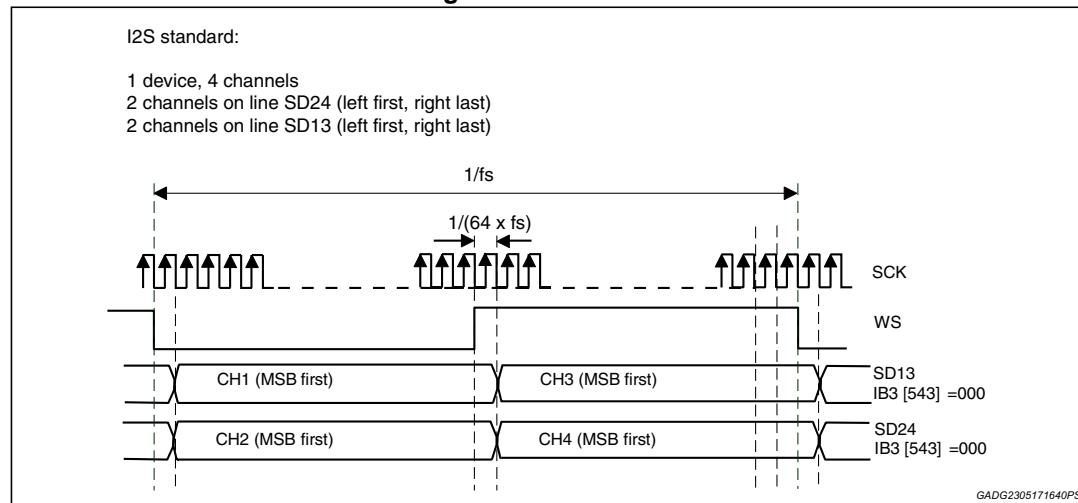
Table 11. System input frequencies

Frequency sampling (Fs)	System clock frequency (f _{SCK}), (MHz)		
	I ² S standard	TDM 4ch	TDM 8ch/8+8ch
44.1 (kHz)	2.8224	5.6448	11.2896
48 (kHz)	3.072	6.144	12.288
96 (kHz)	6.144	12.288	24.576
192 (kHz)	12.288	24.576	N.A.

8.2 I²S input data format

The TDA7803A accepts I²S standard interface format as in [Figure 41](#) and the I²C bit configuration is IB3 [D5,D4,D3] = "000".

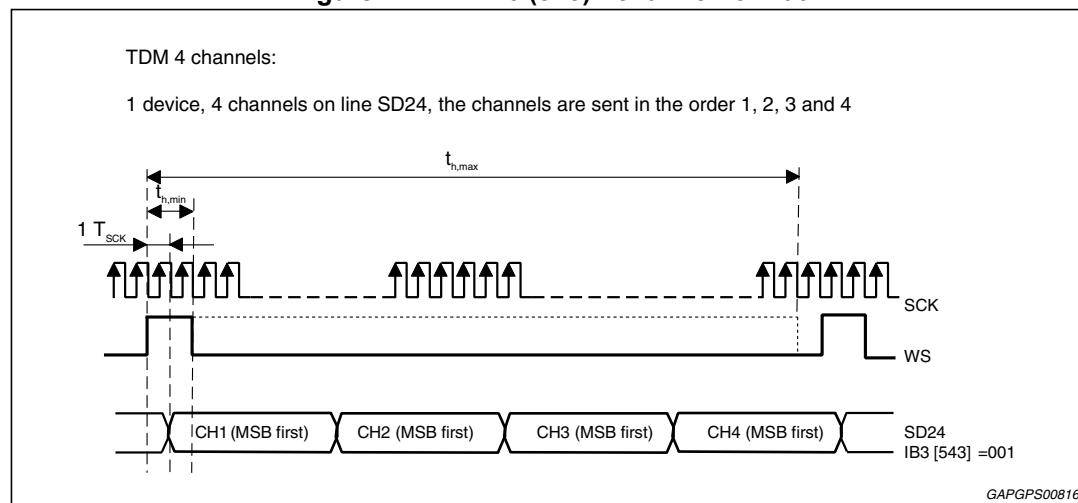
Figure 41. I²S format



8.3 TDM input data format

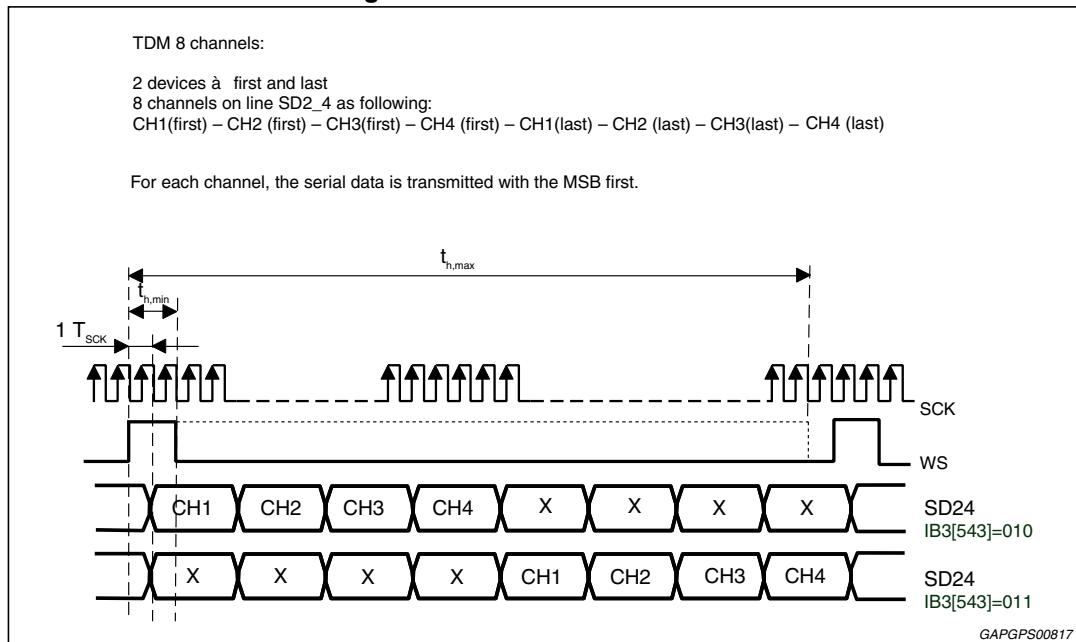
TDM 4-channel is allowed for TDA7803A and it is as in [Figure 42](#). All the channels are sent on the audio data line SD24. The channel's order is 1, 2, 3 and 4. The I²C bit configuration is IB3 [D5, D4, D3] = "001".

Figure 42. TDM 16 (8+8) - channel format



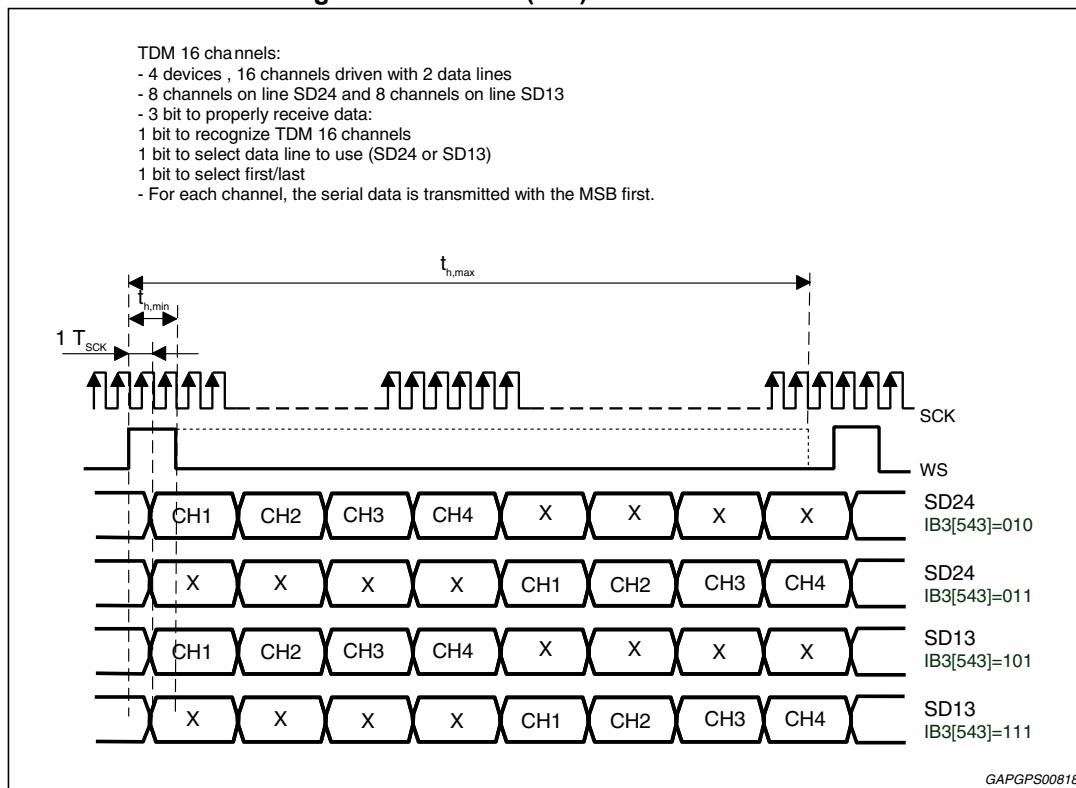
TDM 8-channel is also allowed and two devices (device 1 and device 2) can be driven by using just one serial data line SD24. There are two selectable options
 When IB3 [D5,D4,D3] = "010" device 1 is first sent; when IB3 [D5,D4,D3] = "011" device 2 is first sent. In [Figure 43](#) TDM 8-channel format is showed.

Figure 43. TDM 8-channel format



The TDM 8 channel is expandable to TDM 16 channel (Figure 44) where both SD24 and SD13 data lines are used. All the configurations are selectable via I²C.

Figure 44. TDM 16 (8+8) - channel format



8.4 Timings requirements

Figure 45. Audio interface timing

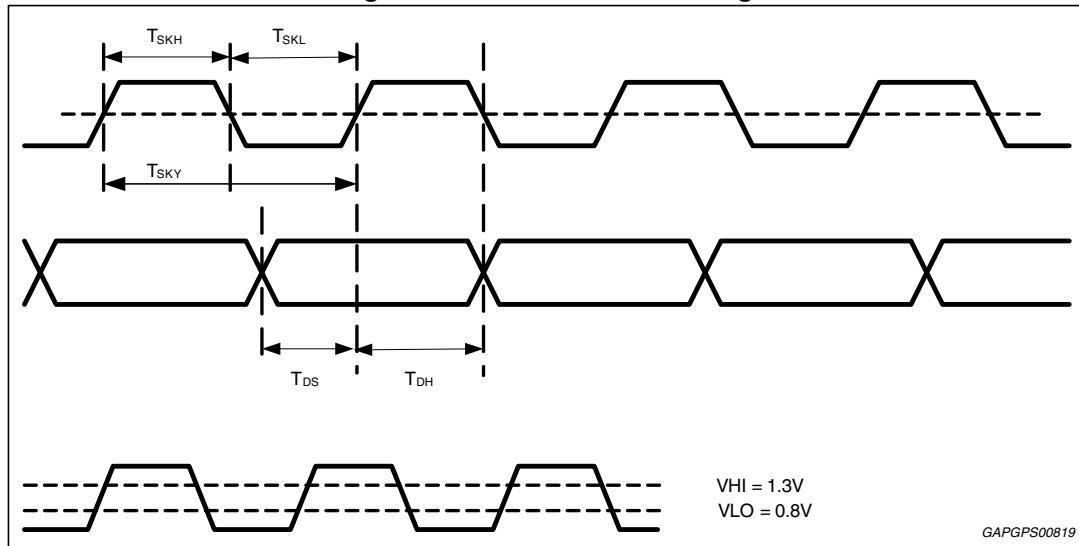


Table 12. I²S interface timing

Symbol	Parameter	note	min	max	unit
Fsck0	SCK (bit clock) frequency	-	-	49.152	MHz
-	SCK (bit clock) frequency tolerance	-	0.9Fsck0	1.1Fsck0	MHz
Tsck	SCK period	-	20	-	ns
-	SCK duty cycle	-	40	60	%
Tsckh	SCK high time	-	6	-	ns
Tskl	SCK low time	-	6	-	ns
-	SCK transition time	-	-	4	ns
-	WS (word select) frequency	-	-	192	kHz
Twsh	WS high time	I ² S standard	25 or 32 Tsck (duty cycle=50%)	-	ns
Twsh	WS high time	TDM 4-channel	1 Tsck	127 Tsck	ns
Twsh	WS high time	TDM 8 - TDM 16 (8+8) channel	1 Tsck	255 Tsck	ns
Tws	WS setup time	-	5	-	ns
Twh	WS hold time	-	6	-	ns
Tds	SD13 SD24 (data inputs) setup time before SCK rising edge	-	5	-	ns
Tdh	SD13 SD24 (data inputs) hold time after SCK rising edge	-	6	-	ns

For TDM mode:

- WS changes at SCK falling edge, on clock period before the MSB is transmitted
- WS does not need to be symmetrical. It need to stay high for at least 2 SCK period clock. The maximum duration is:
 - $T_{h_max} = 127 T_{SCK}$ in TDM 4-channel
 - $T_{h_max} = 255 T_{SCK}$ in TDM 8-channel and TDM 16 (8+8) - channels
- The other timings are like in [Table 12](#).

8.5 Group delay

The group delay is due to the FIR filter first interpolator and it is $T_{delay} = 32/F_s$.

9 I²C bus interface

Data transmission from microprocessor to the TDA7803A and viceversa takes place through the 2 wires I²C bus interface, consisting of the two lines SDA and SCL (pull-up resistors to positive supply voltage must be connected).

When I²C bus is active, the user can select the IC's operating mode. The diagnostic cycle results are stored into the data byte, and read the instruction and data bytes back.

The protocol used for the bus is depicted in *Figure 46* and comprises:

- a start condition (S)
- a chip Address byte (the LSB bit determines read/write transmission)
- a Subaddress byte
- a sequence of Data (N-bytes + acknowledge)
- a stop condition (P)

Figure 46. I²C bus protocol description

S	Address	A	Subaddress	A	Data	P			
Address	=	1	1	0	1	1	ADD2	ADD1	R/W
Subaddress	=	I	SUBA6	SUBA5	SUBA4	SUBA3	SUBA2	SUBA1	SUBA0
Data	=	DATA	DATA	DATA	DATA	DATA	DATA	DATA	DATA

GAPG1504160751PS

Description:

- S = Start
- R/W = '0' => Receive-Mode (Chip could be programmed by uP)
- I = Auto increment; when 1, the address is automatically incremented for each byte transferred
- A = Acknowledge
- P = Stop
- MAX CLOCK SPEED 400kbit/sec

There are four I²C addresses (for PowerSO36 package): 1101100, 1101101, 1101110, 1101111.

For Flexiwatt package only the 1101100 is available.

9.1 Writing procedure

There are two possible procedures:

1. without increment: the I bit is set to 0 and the register to be written is addressed by the subaddress SUB A. Only this register is written by the DATA byte following the subaddress byte.
2. with increment: the I bit is set to 1 and the first register to be written is the one addressed by subaddress SUB A. Then all the registers from SUB A up to stop bit or the reaching of last register are written.

9.2 Reading procedure

There are two possible procedures:

1. without increment: the I bit is set to 0 and the only register to be read is addressed by the subaddress sent in the previous write procedure.
2. with increment: the I bit is set to 1 and the first register to be read is the one addressed by subaddress sent in the previous write procedure. Then all the registers from this subaddress up to stop bit or the reaching of last register are read.

9.3 Data validity

The data on the SDA line must be stable during the high period of the clock. The HIGH and LOW state of the data line can only change when the clock signal on the SCL line is LOW.

9.4 Start and stop conditions

A start condition is a HIGH to LOW transition of the SDA line while SCL is HIGH.

The stop condition is a LOW to HIGH transition of the SDA line while SCL is HIGH.

9.5 Byte format

Every byte transferred to the SDA line must contain 8 bits. Each byte must be followed by an acknowledge bit. The MSB is transferred first.

9.6 Acknowledge

The transmitter* puts a resistive HIGH level on the SDA line during the acknowledge clock pulse. The receiver** has to pull-down (LOW) the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during this clock pulse.

* Transmitter

- = master (μ P) when it writes an address or instruction byte to the TDA7803A
- = slave (TDA7803A) when the μ P reads a data byte from TDA7803A

** Receiver

- = slave (TDA7803A) when the μ P writes an address or instruction byte to the TDA7803A
- = master (μ P) when it reads a data byte from TDA7803A

9.7 Address selection

To select the proper I²C address a resistor must be connected to ADD pin as follows:

Table 13. Address threshold

ADD2	ADD1	Rload
0	0	120K < R
0	1	56K < R < 64K
1	0	30K < R < 38K
1	1	R < 15K

9.8 I²C bus timings

This paragraph describes more in detail the I²C bus protocol used and its timings. [Figure 47](#) and [Table 14](#) include the timings that have to be respected in order to correctly write into/read from the I²C registers.

Figure 47. I²C bus interface timing

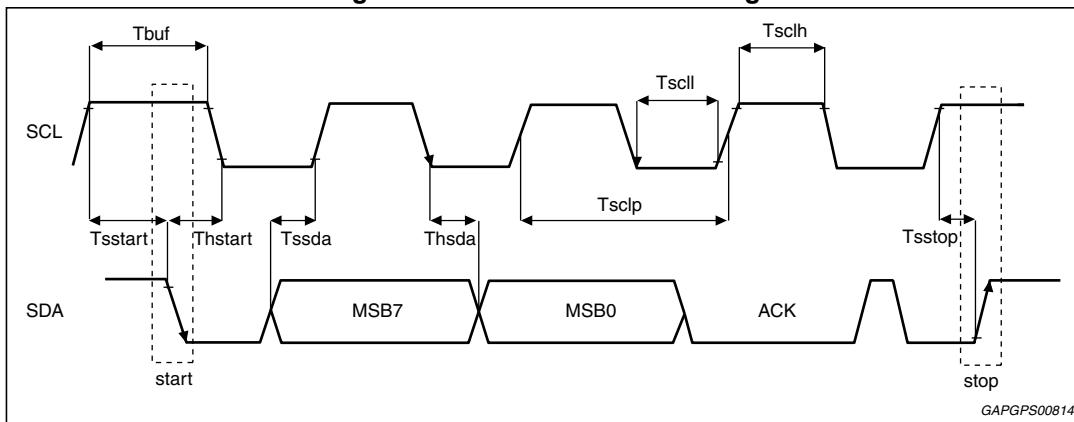


Table 14. I²C bus interface timing

Symbol	Parameter	Min	Max	Unit
Fscl	SCL (clock line) frequency	-	400	kHz
Tscl	SCL period	2500	-	ns
Tsclh	SCL high time	0.6	-	μs
Tscll	SCL low time	1.3	-	μs
Tsstart	Setup time for start condition	0.6	-	μs
Thstart	Hold time for start condition	0.6	-	μs
Tsstop	Setup time for stop condition	0.6	-	μs
Tbuf	Bus free time between a stop and a start condition	1.3	-	μs
Tssda	Setup time for data line	100	-	ns
Thsda	Hold time for data line	0 ⁽¹⁾	-	ns
Tf	Fall time for SCL and SDA	-	300	ns

1. Device must internally provide a hold time of at least 300 ns for the SDA signal to bridge the undefined region of the falling edge of SCL.

10 I²C registers

10.1 Instruction byte

10.1.1 IB0 - Subaddress "I0000000h" - default = "00000000"

Table 15. IB0 - Subaddress "I0000000h" - default = "00000000"

Bit	Instruction decoding bit
D7	Channel 4 Tristate Mode 0: off 1: on
D6	Channel 3 Tristate Mode 0: off 1: on
D5	Channel 2 Tristate Mode 0: off 1: on
D4	Channel 1 Tristate Mode 0: off 1: on
D3	Channel 4 Amplifier Mode 0: High Efficiency SBI mode 1: Standard Class AB Mode
D2	Channel 3 Amplifier Mode 0: High Efficiency SBI mode 1: Standard Class AB Mode
D1	Channel 2 Amplifier Mode 0: High Efficiency SBI mode 1: Standard Class AB Mode
D0	Channel 1 Amplifier Mode 0: High Efficiency SBI mode 1: Standard Class AB Mode

10.1.2 IB1 - Subaddress "I0000001h" - default = "00000000"

Table 16. IB1 - Subaddress "I0000001h" - default = "00000000"

Bit	Instruction decoding bit
D7	Impedance efficiency optimizer (front channels) 0: Efficiency optimized for 2 ohm 1: Efficiency optimized for 4 ohm
D6	Impedance efficiency optimizer (rear channels) 0: Efficiency optimized for 2 ohm 1: Efficiency optimized for 4 ohm
D5 D4	Digital gain selection D4 D5 Digital gain 0 0 No digital gain 0 1 +6 dB 1 0 +12 dB 1 1 Not used
D3 D2	Gain Channel 1 & 3 D3 D2 Gain 0 0 GV1 0 1 GV2 1 0 GV3 1 1 GV4
D1 D0	Gain Channel 2 & 4 D1 D0 Gain 0 0 GV1 0 1 GV2 1 0 GV3 1 1 GV4

10.1.3 IB2 - Subaddress "I0000010h" - default = "00000000"

Table 17. IB2 - Subaddress "I0000010h" - default = "00000000"

Bit	Instruction decoding bit
D7	Mute Time Setting D7 D6 D5 mute timing (Fs = 44.1 kHz) 0 0 0 1.45 ms 0 0 1 5.8 ms 0 1 0 11.6 ms 0 1 1 23.2 ms 1 0 0 46.4 ms 1 0 1 92.8 ms 1 1 0 185.5 ms 1 1 1 371.1 ms
D4	Mute 1&3 0: Channels 1 & 3 Muted 1: Channels 1 & 3 un-Muted
D3	Mute 2&4 0: Channels 2 & 4 Muted 1: Channels 2 & 4 un-Muted
D2	Disable digital mute 0: Digital mute ON 1: Digital mute OFF
D1	Internal use – set “0”
D0	Low Battery Mute threshold 0: 5.3 V (guaranteed play down to 6 V) 1: 7.3 V (guaranteed play down to 8 V)

10.1.4 IB3 - Subaddress "I0000011h" - default = "00000000"

Table 18. IB3 - Subaddress "I0000011h" - default = "00000000"

Bit	Instruction decoding bit																																
D7-D6	<p>Sample frequency range (Word select frequency)</p> <p>D7 D6 Sample frequency</p> <table> <tr><td>0</td><td>0</td><td>44.1 kHz</td></tr> <tr><td>0</td><td>1</td><td>48 kHz⁽¹⁾</td></tr> <tr><td>1</td><td>0</td><td>96 kHz</td></tr> <tr><td>1</td><td>1</td><td>192 kHz</td></tr> </table>	0	0	44.1 kHz	0	1	48 kHz ⁽¹⁾	1	0	96 kHz	1	1	192 kHz																				
0	0	44.1 kHz																															
0	1	48 kHz ⁽¹⁾																															
1	0	96 kHz																															
1	1	192 kHz																															
D5	Digital Input Format																																
D4	<p>D5 D4 D3</p> <table> <tr><td>0</td><td>0</td><td>0</td><td>I2S standard</td></tr> <tr><td>0</td><td>0</td><td>1</td><td>TDM – 4ch</td></tr> <tr><td>0</td><td>1</td><td>0</td><td>TDM – 8ch (SD2_4 input, device 1)</td></tr> <tr><td>0</td><td>1</td><td>1</td><td>TDM – 8ch (SD2_4 input device 2)</td></tr> <tr><td>1</td><td>0</td><td>0</td><td>TDM – 16ch (8 + 8) (SD2_4 input - device 1)</td></tr> <tr><td>1</td><td>0</td><td>1</td><td>TDM – 16ch (8 + 8) (SD2_4 input - device 2)</td></tr> <tr><td>1</td><td>1</td><td>0</td><td>TDM – 16ch (8 + 8) (SD1_3 input - device 3)</td></tr> <tr><td>1</td><td>1</td><td>1</td><td>TDM – 16ch (8 + 8) (SD1_3 input - device 4)</td></tr> </table>	0	0	0	I2S standard	0	0	1	TDM – 4ch	0	1	0	TDM – 8ch (SD2_4 input, device 1)	0	1	1	TDM – 8ch (SD2_4 input device 2)	1	0	0	TDM – 16ch (8 + 8) (SD2_4 input - device 1)	1	0	1	TDM – 16ch (8 + 8) (SD2_4 input - device 2)	1	1	0	TDM – 16ch (8 + 8) (SD1_3 input - device 3)	1	1	1	TDM – 16ch (8 + 8) (SD1_3 input - device 4)
0	0	0	I2S standard																														
0	0	1	TDM – 4ch																														
0	1	0	TDM – 8ch (SD2_4 input, device 1)																														
0	1	1	TDM – 8ch (SD2_4 input device 2)																														
1	0	0	TDM – 16ch (8 + 8) (SD2_4 input - device 1)																														
1	0	1	TDM – 16ch (8 + 8) (SD2_4 input - device 2)																														
1	1	0	TDM – 16ch (8 + 8) (SD1_3 input - device 3)																														
1	1	1	TDM – 16ch (8 + 8) (SD1_3 input - device 4)																														
D3	Noise Gating Function enable/disable																																
D2	<p>0: enable 1: disable</p>																																
D1	<p>Input offset detection</p> <p>0: enable 1: disable</p>																																
D0	<p>Digital High pass filter enable/disable</p> <p>0: disable 1: enable</p>																																

1. Configurations IB3 [D7, D6] =00 and 01 are the same from a signal processing point of view. The distinction is needed in order to handle functions timings and duration.

Note: Byte IB3 settings can be changed only if the amplifier is in ECO mode state, otherwise the command is ignored.

10.1.5 IB4 - Subaddress "I0000100h" - default = "00000000"

Table 19. IB4 - Subaddress "I0000100h" - default = "00000000"

Bit	Instruction decoding bit
D7	Internal use – set "0"
D6	Short Fault information on CD/diag pin 0: yes 1: no
D5	Offset information on CD/diag pin. Selection possible only if IB3(0) = "0" 0: yes 1: no
D4	AC diagnostic current threshold 0: high 1: low
D3	AC Diagnostic Enable/Disable 0: disable 1: enable
D2	Channel 1&3 Diagnostic Mode 0: Speaker mode 1: Line Driver mode
D1	Channel 2&4 Diagnostic Mode 0: Speaker mode 1: Line Driver mode
D0	Diagnostic Mode Enable/Disable 0: disable 1: enable

10.1.6 IB5 - Subaddress "I0000101h" - default = "00000000"

Table 20. IB5 - Subaddress "I0000101h" - default = "00000000"

Bit	Instruction decoding bit		
	Thermal threshold programmability:		
D7, D6	D7	D6	Thermal threshold (TWs)
	0	0	Default (datasheet value)
	0	1	TWs shifted -10°C
	1	0	TWs shifted -20°C
	1	1	Not used
D5	Internal use – set "0"		
D4, D3, D2, D1	Current capability enhancer D4 - D1 0000 disabled 1111 enabled		
D0	Internal use – set "0"		

10.1.7 IB6 - Subaddress "I0000110h" - default = "00000000"

Table 21. IB6 - Subaddress "I0000110h" - default = "00000000"

Bit	Instruction decoding bit				
D7 D6 D5	Diagnostic pulse stretch				
	D7	D6	D5	Diagnostic timing set	
	0	0	0	Default	
	0	0	1	Stretched*2	
	0	1	0	Stretched*4	
	0	1	1	Stretched*8	
D4	1	0	0	Stretched*16	
	Others			Default	
D4	Internal use – set "0"				
D3 D2	Parallel mode Configuration D3 D2 (like LOADA,LOADB):				
	D3	D2	Load configuration		
	0	0	Single channel mode on 1,2,3 & 4 channel		
	0	1	Parallel mode only on 1 & 2 channels		
	1	0	Parallel mode only on 3 & 4 channels		
D1	1	1	Parallel mode on both sides		
	Internal use – set "0"				
D0	Internal use – set "0"				

10.1.8 IB7 - Subaddress "I0000111h" - default = "00000000"

Table 22. IB7 - Subaddress "I0000111h" - default = "00000000"

Bit	Instruction decoding bit
	Temperature warning information on CDdiag pin D7 D6 D5 Temperature 0 0 0 TW1 0 0 1 TW2 0 1 0 TW3 0 1 1 TW4 1 x x no thermal warning information on diag pin
D4	Clipping detection level for front channels D4 D3 0 0 threshold 1 for all channel 1 and 3 0 1 threshold 2 for all channel 1 and 3 1 0 threshold 3 for all channel 1 and 3 1 1 no clipping for channel 1 and 3
D2	Clipping detection level for rear channels D2 D1 0 0 threshold 1 for all channel 2 and 4 0 1 threshold 2 for all channel 2 and 4 1 0 threshold 3 for all channel 2 and 4 1 1 no clipping for channel 2 and 4
D0	Amplifier on/off 0: off 1: on

10.2 Data byte

10.2.1 DB0 - Subaddress: "I0010000h"

Table 23. DB0 - Subaddress: "I0010000h"

Bit	Instruction decoding bit
D7	Power on reset (POR) 0: the start-up phase to move from 'stand by' state to 'ECO - mode' state is running 1: the device is 'out of stand by'.
D6	Start-up Diagnostic status 0: Turn-on Diag. cycle not activated or not terminated 1: Turn-on Diag. cycle terminated
D5	Diagnostic Data Valid 1: diagnostic data not valid 0: diagnostic data valid
D4	Internal use
D3	Internal use
D2	Internal use
D1	Channel 2 & 4 in mute/play 0: Channel 2 & 4 in play 1: Channel 2 & 4 in mute
D0	Channel 1 & 3 in mute/play 0: Channel 1 & 3 in play 1: Channel 1 & 3 in mute

10.2.2 DB1 - Subaddress: "I0010001h" - Channel 1

Table 24. DB1 - Subaddress: "I0010001h" - Channel 1

Bit	Instruction decoding bit
D7	Overcurrent protection Channel 1: 0: Overcurrent protection NOT triggered on CH1 1: Overcurrent protection triggered on CH1
D6	Channel 1 Soft Short present 0: No Soft short 1: Soft Short (only during turn-on diagnostic)
D5	Channel 1 offset detection 0: No output offset 1: Output offset detected
D4	Channel 1 Permanent Diagnostic status 0: Permanent diagnostic cycle not activated or not terminated 1: Permanent diagnostic cycle terminated
D3	Channel 1 Normal/Short Load 0: Normal load 1: Short load
D2	Channel 1 Open load 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 1 Short to Vcc 0: No Hard short to Vcc 1: Hard short to Vcc
D0	Channel 1 Short to GND 0: No Hard short to GND 1: Hard Short to GND

10.2.3 DB2 - Subaddress: "I0010010h" - Channel 2

Table 25. DB2 - Subaddress: "I0010010h" - Channel 2

Bit	Instruction decoding bit
D7	Overcurrent protection Channel 2: 0: Overcurrent protection NOT triggered on CH2 1: Overcurrent protection triggered on CH2
D6	Channel 2 Soft Short present 0: No Soft short 1: Soft Short (only during turn-on diagnostic)
D5	Channel 2 offset detection 0: No output offset 1: Output offset detected
D4	Channel 2 Permanent Diagnostic status 0: Permanent diagnostic cycle not activated or not terminated 1: Permanent diagnostic cycle terminated
D3	Channel 2 Normal/Short Load 0: Normal load 1: Short load
D2	Channel 2 Open load 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 2 Short to Vcc 0: No Hard short to Vcc 1: Hard short to Vcc
D0	Channel 2 Short to GND 0: No short to GND 1: Short to GND

10.2.4 DB3 - Subaddress: "I0010011h" - Channel 3

Table 26. DB3 - Subaddress: "I0010011h" - Channel 3

Bit	Instruction decoding bit
D7	Overcurrent protection Channel 3: 0: Overcurrent protection NOT triggered on CH3 1: Overcurrent protection triggered on CH3
D6	Channel 3 Soft Short present 0: No Soft short 1: Soft Short (only during turn-on diagnostic)
D5	Channel 3 offset detection 0: No output offset 1: Output offset detected
D4	Channel 3 Permanent Diagnostic status 0: Permanent diagnostic cycle not activated or not terminated 1: Permanent diagnostic cycle terminated
D3	Channel 3 Normal/Short Load 0: Normal load 1: Short load
D2	Channel 3 Open load 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 3 Short to Vcc 0: No Hard short to Vcc 1: Hard short to Vcc
D0	Channel 3 Short to GND 0: No short to GND 1: Short to GND

10.2.5 DB4 - Subaddress: "I0010100h" - Channel 4

Table 27. DB4 - Subaddress: "I0010100h" - Channel 4

Bit	Instruction decoding bit
D7	Overcurrent protection Channel 4: 0: Overcurrent protection NOT triggered on CH4 1: Overcurrent protection triggered on CH4
D6	Channel 4 Soft Short present 0: No Soft short 1: Soft Short (only during turn-on diagnostic)
D5	Channel 4 offset detection 0: No output offset 1: Output offset detected
D4	Channel 4 Permanent Diagnostic status 0: Permanent diagnostic cycle not activated or not terminated 1: Permanent diagnostic cycle terminated
D3	Channel 4 Normal/Short Load 0: Normal load 1: Short load
D2	Channel 4 Open load 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 4 Short to Vcc 0: No Hard short to Vcc 1: Hard short to Vcc
D0	Channel 4 Short to GND 0: No short to GND 1: Short to GND

10.2.6 DB5 - Subaddress: "I0010101h"

Table 28. DB5 - Subaddress: "I0010101h"

Bit	Instruction decoding bit
D7	AC DIAG – Signal level compatible with AC diag detection 0: Signal ok 1: Signal too high
D6	AC DIAG – Channel 4 tweeter detection 0: Ch4 tweeter not present 1: Ch4 tweeter present
D5	AC DIAG – Channel 3 tweeter detection 0: Ch3 tweeter not present 1: Ch3 tweeter present
D4	AC DIAG – Channel 2 tweeter detection 0: Ch2 tweeter not present 1: Ch2 tweeter present
D3	AC DIAG – Channel 1 tweeter detection 0: Ch1 tweeter not present 1: Ch1 tweeter present
D2	Front channel clip detection 0: No clipping on front channel 1: Clipping on front channel
D1	Rear channel clip detection 0: No clipping on rear channel 1: Clipping on rear channel
D0	PLL lock detector 0: PLL no locked 1: PLL locked

10.2.7 DB6 - Subaddress: "I0010110h"

Table 29. DB6 - Subaddress: "I0010110h"

Bit	Instruction decoding bit
D7	TW1 0: TW1 threshold not trespassed 1: TW1 threshold trespassed
D6	TW2 0: TW2 threshold not trespassed 1: TW2 threshold trespassed
D5	TW3 0: TW3 threshold not trespassed 1: TW3 threshold trespassed
D4	TW4 0: TW4 threshold not trespassed 1: TW4 threshold trespassed
D3	Internal use
D2	Internal use
D1	Internal use
D0	Internal use

10.2.8 DB7 - Subaddress: "I0010111h" - Vcc level ADC conversion

Table 30. DB7 - Subaddress: "I0010111h" - Vcc level ADC conversion

Bit	Instruction decoding bit
D7	Battery Level (7)
D6	Battery Level (6)
D5	Battery Level (5)
D4	Battery Level (4)
D3	Battery Level (3)
D2	Battery Level (2)
D1	Battery Level (1)
D0	Battery Level (0)

11 Package information

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11.1 PowerSO-36 (slug up) package information

Figure 48. PowerSO-36 (slug up) package outline

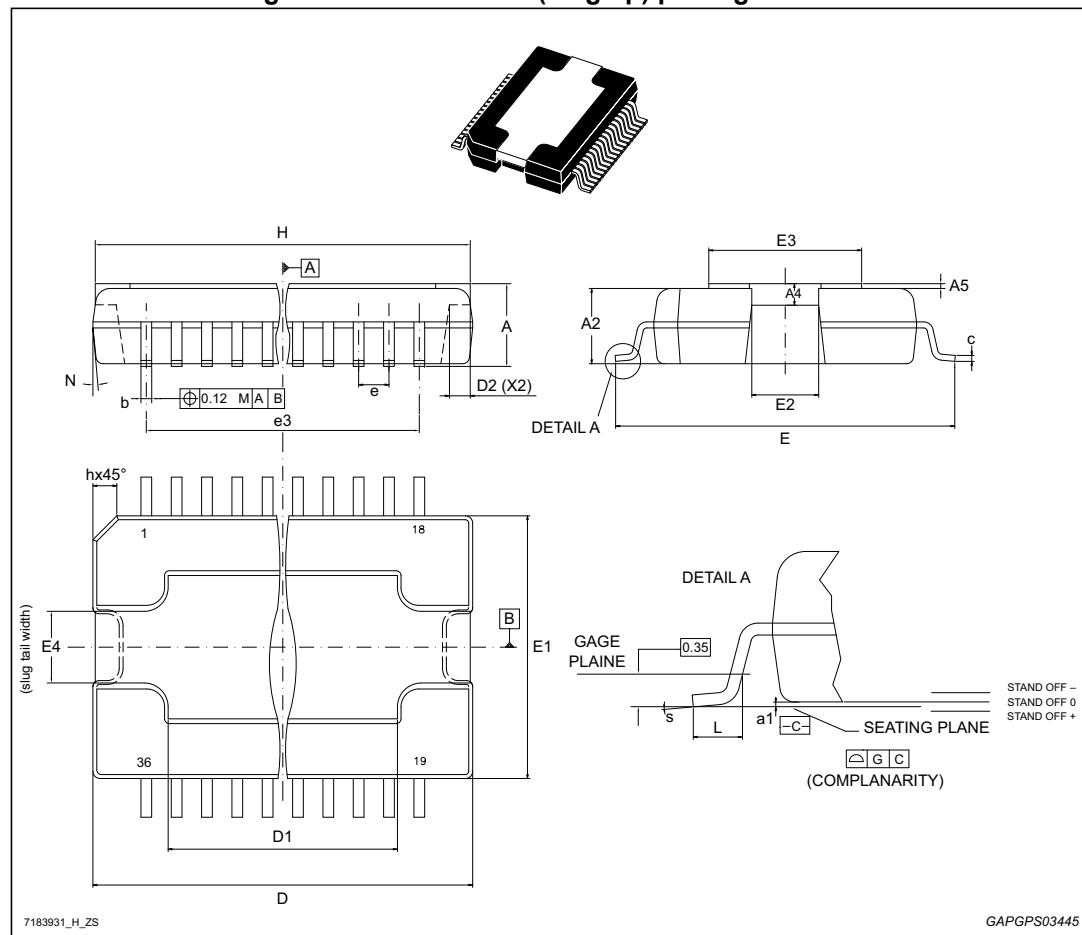


Table 31. PowerSO-36 (slug up) package mechanical data

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	3.27	-	3.41	0.1287	-	0.1343
A2	3.1	-	3.18	0.1220	-	0.1252

Table 31. PowerSO-36 (slug up) package mechanical data (continued)

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A4	0.8	-	1.0	0.0315	-	0.0394
A5	-	0.2	-	-	0.0079	-
a1	0.03	-	-0.04	0.0012	-	-0.0016
b	0.22	-	0.38	0.0087	-	0.0150
c	0.23	-	0.32	0.0091	-	0.0126
D ⁽²⁾	15.8	-	16.0	0.6220	-	0.6299
D1	9.4	-	9.8	0.3701	-	0.3858
D2	-	1.0	-	-	0.0394	-
E	13.9	-	14.5	0.5472	-	0.5709
E1 ⁽²⁾	10.9	-	11.1	0.4291	-	0.4370
E2	-	-	2.9	-	-	0.1142
E3	5.8	-	6.2	0.2283	-	0.2441
E4	2.9	-	3.2	0.1142	-	0.1260
e	-	0.65	-	-	0.0256	-
e3	-	11.05	-	-	0.4350	-
G	0	-	0.075	0	-	0.0031
H	15.5	-	15.900	0.6102	-	0.6260
h	-	-	1.1	-	-	0.0433
L	0.8	-	1.1	0.0315	-	0.0433
N	-	-	10°	-	-	10°
S	-	-	8°	-	-	8°

1. Values in inches are converted from mm and rounded to 4 decimal digits.

2. 'D' and 'E1' do not include mold flash or protusions.
Mold flash or protusions shall not exceed 0.15mm (0.006").

11.2 Flexiwatt 27 (vertical) package information

Figure 49. Flexiwatt 27 (vertical) package outline

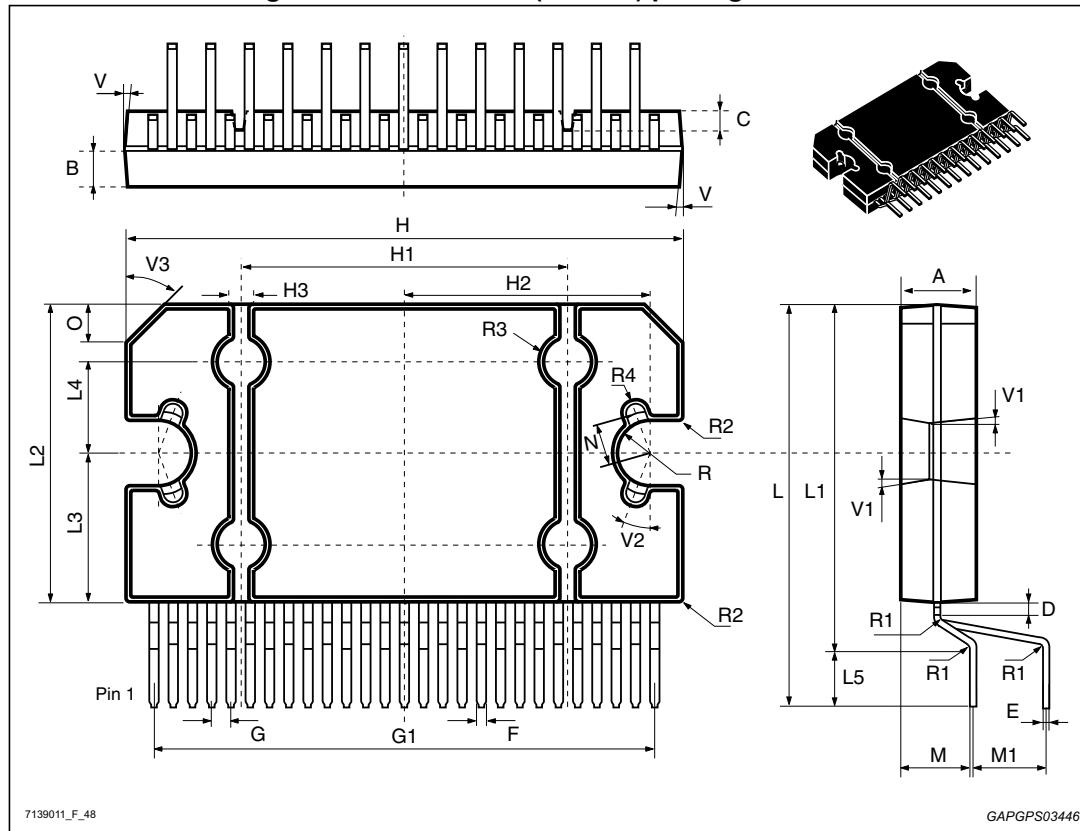


Table 32. Flexiwatt 27 (vertical) package mechanical data

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	4.45	4.50	4.65	0.1752	0.1772	0.1831
B	1.80	1.90	2.00	0.0709	0.0748	0.0787
C	-	1.40	-	-	0.0551	-
D	0.75	0.90	1.05	0.0295	0.0354	0.0413
E	0.37	0.39	0.42	0.0146	0.0154	0.0165
F ⁽²⁾	-	-	0.57	-	-	0.0224
G	0.80	1.00	1.20	0.0315	0.0394	0.0472
G1	25.75	26.00	26.25	1.0138	1.0236	1.0335
H ⁽³⁾	28.90	29.23	29.30	1.1378	1.1508	1.1535
H1	-	17.00	-	-	0.6693	-
H2	-	12.80	-	-	0.5039	-

Table 32. Flexiwatt 27 (vertical) package mechanical data (continued)

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
H3	-	0.80	-	-	0.0315	-
L ⁽³⁾	22.07	22.47	22.87	0.8689	0.8846	0.9004
L1	18.57	18.97	19.37	0.7311	0.7469	0.7626
L2 ⁽³⁾	15.50	15.70	15.90	0.6102	0.6181	0.6260
L3	7.70	7.85	7.95	0.3031	0.3091	0.3130
L4	-	5	-	-	0.1969	-
L5	3.35	3.5	3.65	0.1319	0.1378	0.1437
M	3.70	4.00	4.30	0.1457	0.1575	0.1693
M1	3.60	4.00	4.40	0.1417	0.1575	0.1732
N	-	2.20	-	-	0.0866	-
O	-	2	-	-	0.0787	-
R	-	1.70	-	-	0.0669	-
R1	-	0.5	-	-	0.0197	-
R2	-	0.3	-	-	0.0118	-
R3	-	1.25	-	-	0.0492	-
R4	-	0.50	-	-	0.0197	-
V	5°			5°		
V1	3°			3°		
V2	20°			20°		
V3	45°			45°		

1. Values in inches are converted from mm and rounded to 4 decimal digits.

2. dam-bar protusion not included.

3. molding protusion included.

11.3 Flexiwatt 27 (SMD) package information

Figure 50. Flexiwatt 27 (SMD) package outline

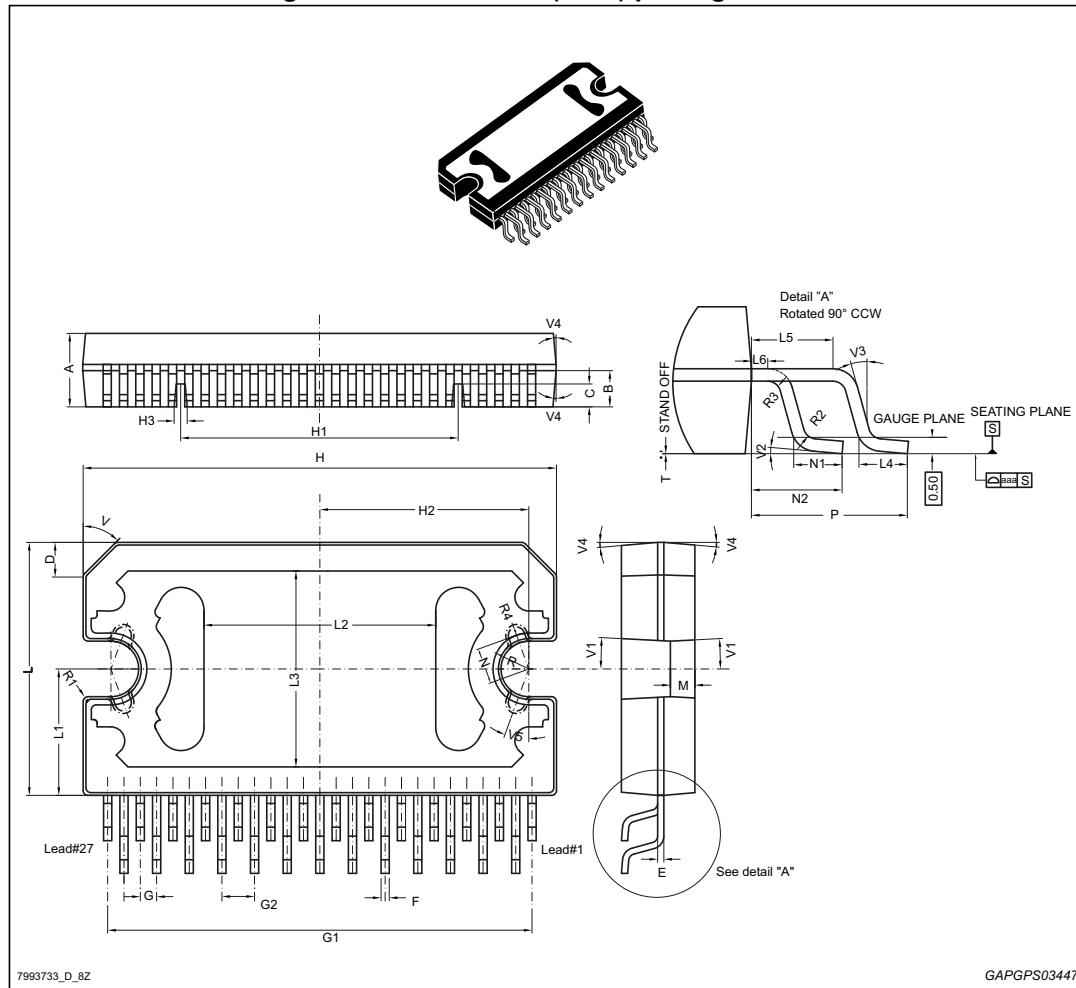


Table 33. Flexiwatt 27 (SMD) package mechanical data

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	4.45	4.50	4.65	0.1752	0.1772	0.1831
B	2.12	2.22	2.32	0.0835	0.0874	0.0913
C	-	1.40	-	-	0.0551	-
D	-	2.00	-	-	0.0787	-
E	0.36	0.40	0.44	0.0142	0.0157	0.0173
F ⁽²⁾	0.47	0.51	0.57	0.0185	0.0201	0.0224
G ⁽³⁾	0.75	1.00	1.25	0.0295	0.0394	0.0492

Table 33. Flexiwatt 27 (SMD) package mechanical data (continued)

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
G1	25.70	26.00	26.30	1.0118	1.0236	1.0354
G2 ⁽³⁾	1.75	2.00	2.25	0.0689	0.0787	0.0886
H ⁽²⁾	28.85	29.23	29.40	1.1358	1.1508	1.1575
H1	-	17.00	-	-	0.6693	-
H2	-	12.80	-	-	0.5039	-
H3	-	0.80	-	-	0.0315	-
L ⁽²⁾	15.50	15.70	15.90	0.6102	0.6181	0.6260
L1	7.70	7.85	7.95	0.3031	0.3091	0.3130
L2	14.00	14.20	14.40	0.5512	0.5591	0.5669
L3	11.80	12.00	12.20	0.4646	0.4724	0.4803
L4	1.30	1.48	1.66	0.0512	0.0583	0.0654
L5	2.42	2.50	2.58	0.0953	0.0984	0.1016
L6	0.42	0.50	0.58	0.0165	0.0197	0.0228
M	-	1.50	-	-	0.0591	-
N	-	2.20	-	-	0.0866	-
N1	1.30	1.48	1.66	0.0512	0.0583	0.0654
N2 ⁽³⁾	2.73 ⁽³⁾	2.83	2.93	0.1075	0.1114	0.1154
P ⁽³⁾	4.73	4.83	4.93	0.1862	0.1902	0.1941
R	-	1.70	-	-	0.0669	-
R1	-	0.30	-	-	0.0118	-
R2	0.35	0.40	0.45	0.0138	0.0157	0.0177
R3	0.35	0.40	0.45	0.0138	0.0157	0.0177
R4	-	0.50	-	-	0.0197	-
T ⁽³⁾	-0.08	-	0.10	-0.0031	-	0.0039
aaa ⁽³⁾	-	0.1	-	-	0.0039	-
V	-	45°	-	-	45°	-

1. Values in inches are converted from mm and rounded to 4 decimal digits.

2. Dimension "F" doesn't include dam-bar protrusion.
Dimensions "H" and "L" include mold flash or protrusions.

3. Golden parameters.

11.4 Flexiwatt 27 (horizontal) package information

Figure 51. Flexiwatt 27 (horizontal) package outline

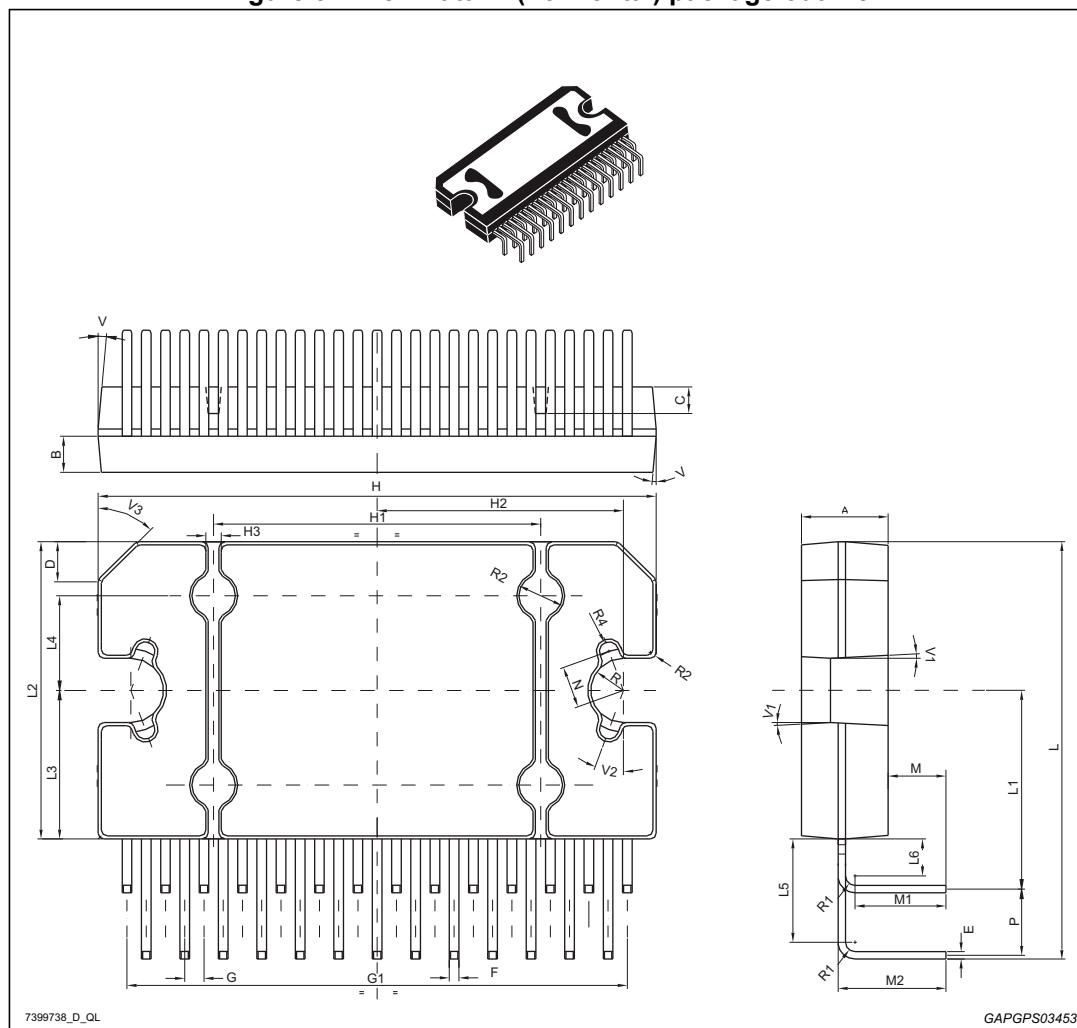


Table 34. Flexiwatt 27 (horizontal) package mechanical data

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	4.45	4.50	4.65	0.1752	0.1772	0.1831
B	1.80	1.90	2.00	0.0709	0.0748	0.0787
C	-	1.40	-	-	0.0551	-
D	-	2.00	-	-	0.0787	-
E	0.37	0.39	0.42	0.0146	0.0154	0.0165
F ⁽²⁾	-	-	0.57	-	-	0.0224
G	0.75	1.00	1.25	0.0295	0.0394	0.0492

Table 34. Flexiwatt 27 (horizontal) package mechanical data (continued)

Ref	Dimensions					
	Millimeters			Inches ⁽¹⁾		
	Min.	Typ.	Max.	Min.	Typ.	Max.
G1	25.70	26.00	26.30	1.0118	1.0236	1.0354
H ⁽³⁾	28.90	29.23	29.30	1.1378	1.1508	1.1535
H1	-	17.00	-	-	0.6693	-
H2	-	12.80	-	-	0.5039	-
H3	-	0.80	-	-	0.0315	-
L ⁽³⁾	21.64	22.04	22.44	0.8520	0.8677	0.8835
L1	10.15	10.50	10.85	0.3996	0.4134	0.4272
L2 ⁽³⁾	15.50	15.70	15.90	0.6102	0.6181	0.6260
L3	7.70	7.85	7.95	0.3031	0.3091	0.3130
L4	-	5	-	-	0.1969	-
L5	5.15	5.45	5.85	0.2028	0.2146	0.2303
M	2.75	3.00	3.50	0.1083	0.1181	0.1378
M1	-	4.73	-	-	0.1862	-
M2	-	5.61	-	-	0.2209	-
N	-	2.20	-	-	0.0866	-
P	3.20	3.50	3.80	0.1260	0.1378	0.1496
R	-	1.70	-	-	0.0669	-
R1	-	0.5	-	-	0.0197	-
R2	-	0.3	-	-	0.0118	-
R3	-	1.25	-	-	0.0492	-
R4	-	0.50	-	-	0.0197	-
V	5°			5°		
V1	3°			3°		
V2	20°			20°		
V3	45°			45°		

1. Values in inches are converted from mm and rounded to 4 decimal digits.

2. dam-bar protusion not included.

3. molding protusion included.

11.5 Package marking information

Figure 52. PowerSO-36 marking information

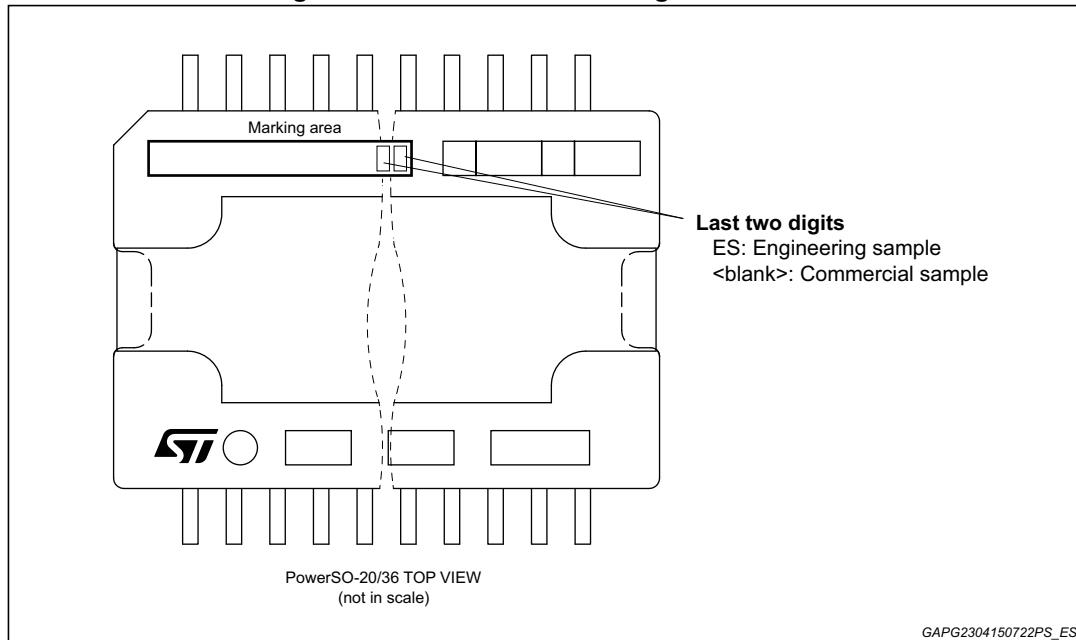
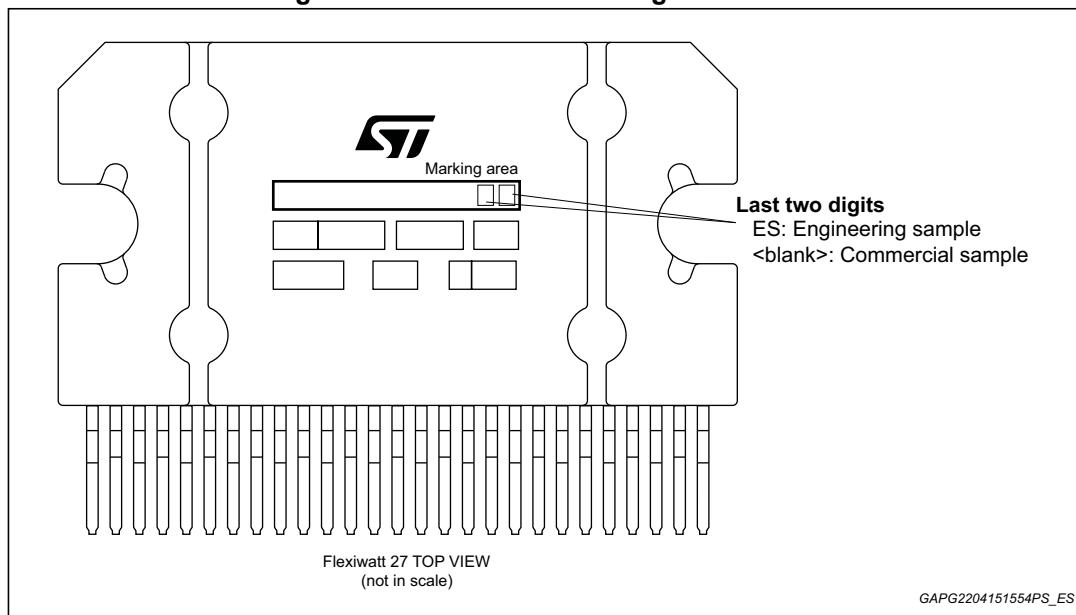


Figure 53. Flexiwatt 27 marking information



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12 Order codes

Table 35. Ordering information

Order code	Package	Packing
TDA7803A-48X	Flexiwatt27 (Vertical)	Tube
TDA7803A-QLX	Flexiwatt27 (Horizontal)	Tube
TDA7803A-8ZX	Flexiwatt27 (SMD)	Tube
TDA7803A-8ZT		Tape & reel
TDA7803A-ZSX	PowerSO36	Tube
TDA7803A-ZST		Tape & reel

13 Revision history

Table 36. Document revision history

Date	Revision	Changes
16-Jun-2017	1	Initial release.
19-Oct-2017	2	Removed note 1 (Part number not yet released for production.) on Table 35: Ordering information on page 70 .
15-Dec-2017	3	Update column note for "T _{PLS} and X" parameters in Table 6 .
18-Jan-2018	4	Document changed from "Confidential" to "Public", no content change.
15-Jan-2019	5	Corrected in Table 3 the value for "C _{max} - Maximum capacitor vs. ground connected to the output" from 10 nF to 4.7 nF. Updated Table 13: Address threshold on page 45 .

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