TLE4241SYS_SHIELD

User guide

LITIX™ Linear
Z8F80503016

About this document

Scope and purpose

The TLE4241GM is an AEC qualified adjustable current LITIX™ Linear device, especially designed to drive LEDs. It embeds:

- Built-in diagnosis and protection features
- Adjustable constant output current up to 70 mA
- Wide input voltage range
- Voltage loop availability to implement constant output voltage power supply

The device also incorporates a PWM input that offers the possibility to adjust the LED brightness by pulse width modulation.

The TLE4241SYS_SHIELD can be used for:

- Standalone evaluation board for TLE4241GM device
- Shield for Arduino

The board is especially suited to quickly setup demos in the context of blind spot indication as it features input for ultrasound sensor, has an integrated buzzer and features 3 LEDs. Such designs are typically found in rear radar applications or are directly integrated into mirrors.

Intended audience

The scope of this user guide is to provide instructions on the use of TLE4241SYS_SHIELD.

This user guide describes the TLE4241SYS_SHIELD with PCB version P02. Additionally, schematic version S02 is described.

Evaluation board

This board is to be used during the design-in process for evaluation and proof of concepts for new projects adopting the TLE4241GM.

Note: PCB and auxiliary circuits are NOT optimized for final customer design.

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Safety precautions

Safety precautions

Note: Please note the following warnings regarding the hazards associated with development systems.

Table 1 Safety precautions

	**Warning:** *The evaluation or reference board contains DC bus capacitors which take time to discharge after removal of the main supply. Before working on the drive system, wait five minutes for capacitors to discharge to safe voltage levels. Failure to do so may result in personal injury or death. Darkened display LEDs are not an indication that capacitors have discharged to safe voltage levels.*
	**Caution:** *Only personnel familiar with the drive, power electronics and associated machinery should plan, install, commission and subsequently service the system. Failure to comply may result in personal injury and/or equipment damage.*
	**Caution:** *The evaluation or reference board contains parts and assemblies sensitive to electrostatic discharge (ESD). Electrostatic control precautions are required when installing, testing, servicing or repairing the assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with electrostatic control procedures, refer to the applicable ESD protection handbooks and guidelines.*
	**Caution:** *A drive that is incorrectly applied or installed can lead to component damage or reduction in product lifetime. Wiring or application errors such as undersizing the motor, supplying an incorrect or inadequate AC supply, or excessive ambient temperatures may result in system malfunction.*

Table of contents

1 The board at a glance

TLE4241GMSHIELD is an extension board for Arduino UNO intended to evaluate 2 main applications for automotive environment (please refer to Chapter 2.3):

- Blind spot indicator
- Parking radar sensor

When connected to a properly programmed Arduino UNO board, the ultrasonic sensor (not included in the evaluation kit) will allow the user to activate the onboard LEDs when certain conditions are satisfied.

TLE4241GMSHIELD can also operate in standalone condition. In this particular case, the PWM signal of the TLE4241GM will be fixed and the LEDs will be turned on at its maximum regulated output current, as shown on the table below.

Parameter	Value	Conditions
Input voltage supply	8 V to 45 V	Standalone operation
	12 V	Arduino connected
Output current	32.5 mA	R_{REF} = 18 kΩ

The output current is regulated by the resistance R_{REF} placed between the REF pin and ground.

Note: Change this resistor if different output current is needed.

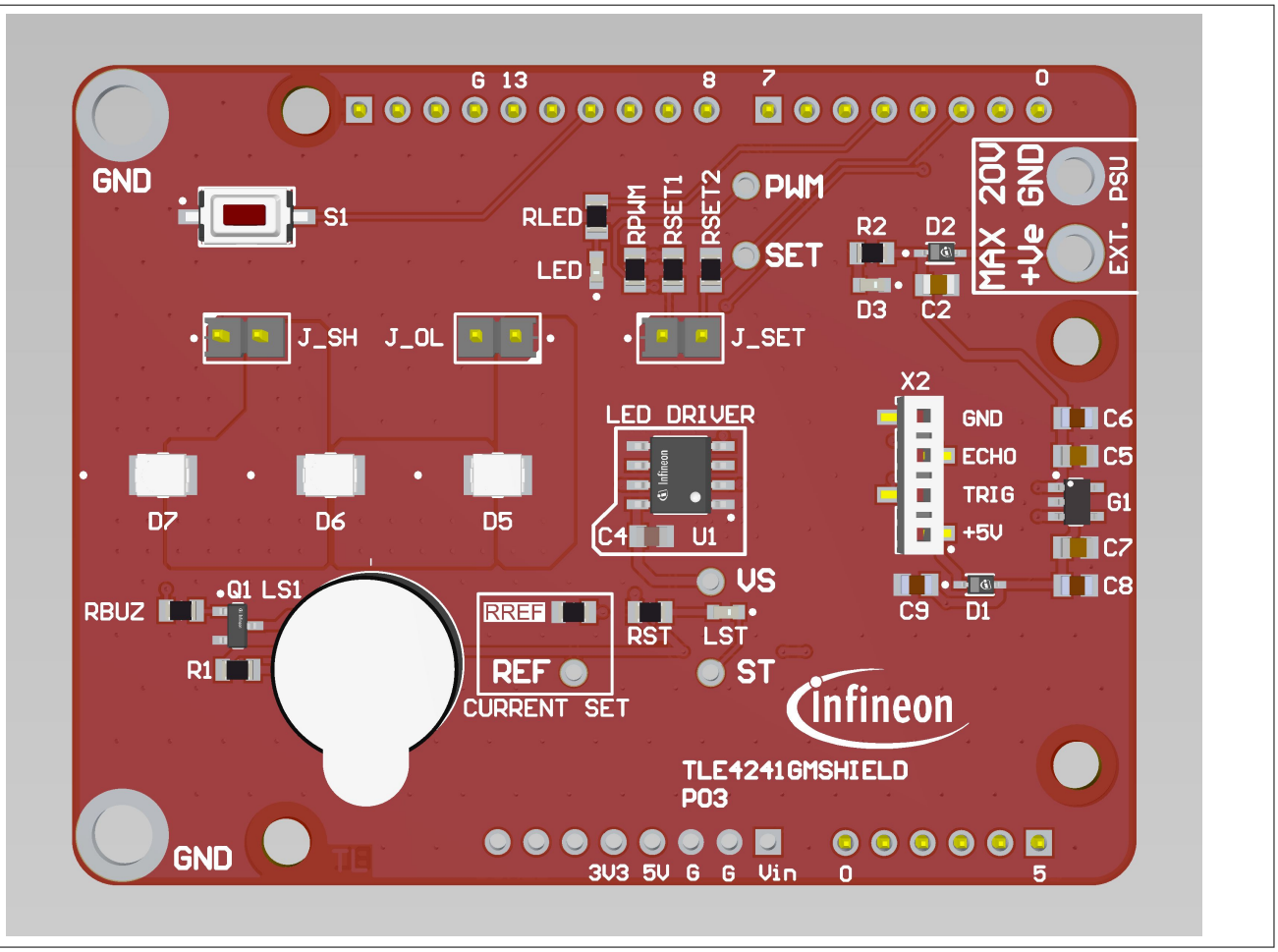

Figure 1 TLE4241SYS_SHIELD board

2 System and functional description

2.1 Getting started

The jumpers are positioned as follows when TLE4241GMSHIELD is operating both in standalone condition or is connected to Arduino UNO.

Table 2 Jumper position

Jumper number	Condition	Description
J_OL	Closed	LED load is connected to TLE4241GM output
J_SH	Open	LED load is composed of 3 LEDs
J_SET	Open	Output current analog adjustment is managed by Arduino board

The default configuration is depicted in the figure below.

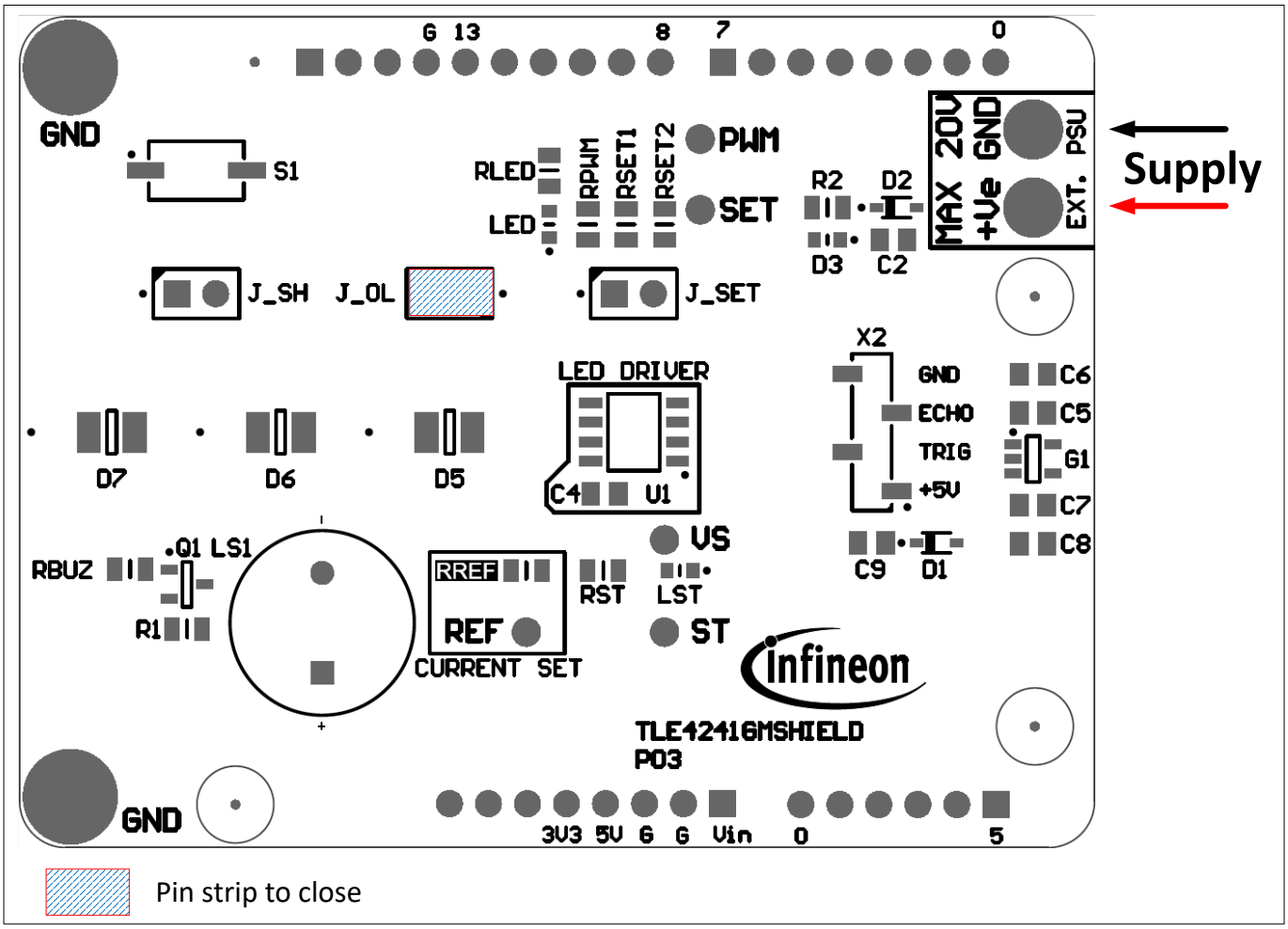

Figure 2 Default configuration of the board

2.2 Description of the functional blocks

Current adjustment

TLE4241GM output current adjustment is performed by changing the value of R_{REF}, that will set the output current level according to the following formula:

$$I_{OUT} = \frac{1.2}{R_{REF}} \times 487 + 0.1$$

On this board the resistor placed on the REF pin R_{REF} is equal to 18 kΩ. The regulated current is 32.5 mA.

2.3 Operation with Arduino

TLE4241GMSHIELD is designed to operate in conjunction with Arduino UNO board (not provided).

In this condition, TLE4241GM output current can be controlled from Arduino UNO board, that will variate PWM and SET signals. Maximum output current is anyway defined by R_{REF} resistor value.

Example code enables the user to evaluate two possible scenarios:

- Blind spot indicator
- Parking sensor

It is possible to change the scenario by clicking **on-board Scenario Selection S1 button** for 2 seconds.

On X2 on-board connector, it is possible to connect an external ultra-sound sensor (not included), to measure the distance from the board to an object. The sensor will be supplied with an on-board 5 V supply. The TRIG pin is used to initiate the distance measurement, while the ECHO pin is used to read back the distance measure from the ultra-sound module. Please refer to the silkscreen for the signal pinout.

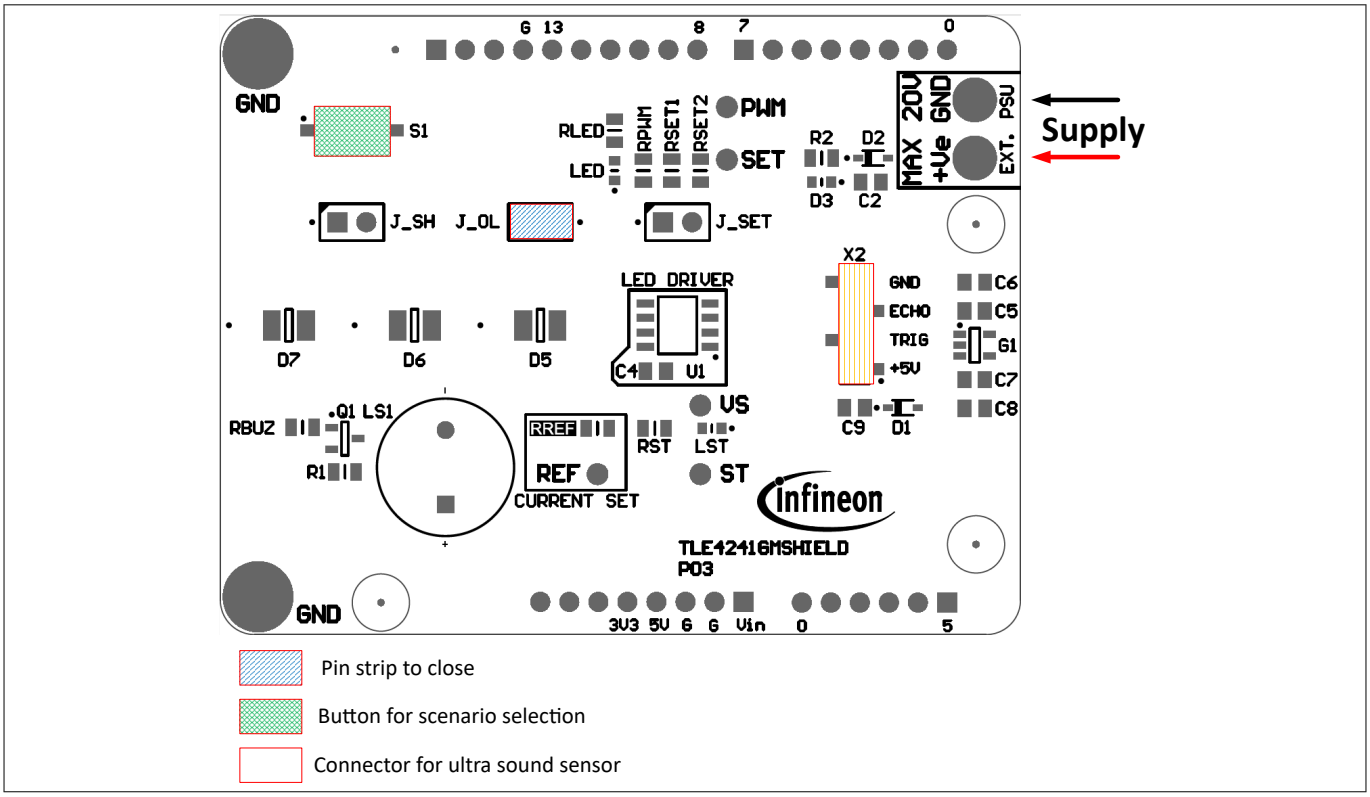

Figure 3 Button and connector for ultrasound sensor position

Note: Example code is not provided in this user guide, and can be downloaded from Infineon website.

2.3.1 Blind spot indicator function

In general, blind spot detection system is designed to assist the driver by monitoring the blind spots on both sides of the vehicle.

When blind spot indicator scenario is selected, by selecting **on-board Scenario Selection S1 button** on the board, the ultra sonic sensor detects any obstacle within 30 cm. Arduino UNO, will then raise the TLE4241GM PWM pin voltage, resulting in turning on the output channel. When the obstacle is removed, Arduino UNO will lower PWM voltage, resulting in turning off the output channel.

It is possible to modify the distance threshold when the output level is triggered changing the threshold value in the example code provided from 20 cm to 240 cm.

2.3.2 Parking sensor function

In general, the parking sensor system is designed to assist the driver by indicating with a sound and light how close to an obstacle the vehicle is when the driver parks the vehicle.

When **Parking Sensor** is selected, the ultrasonic sensor detects obstacles within the range of the detection capabilities of the used sensor.

Arduino UNO is programmed to act differently based on the detected distance from the obstacle. The frequency of the LED blinking is adjusted depending on the distance from the obstacle.

In both scenarios, the on-board buzzer is activated when an obstacle is detected.

3 Fault detection

The system has been designed to detect the following error conditions:

- Open load
- Short to GND
- Overtemperature

In each case, ST pin will be pulled LOW, and the error status will be detected to Arduino UNO board (if connected).

By using the evaluation board, it is possible to evaluate:

- An open load condition by leaving the jumper J_OL open
- A short to GND condition by closing the jumper J_SH

4 System design

4.1 Schematics

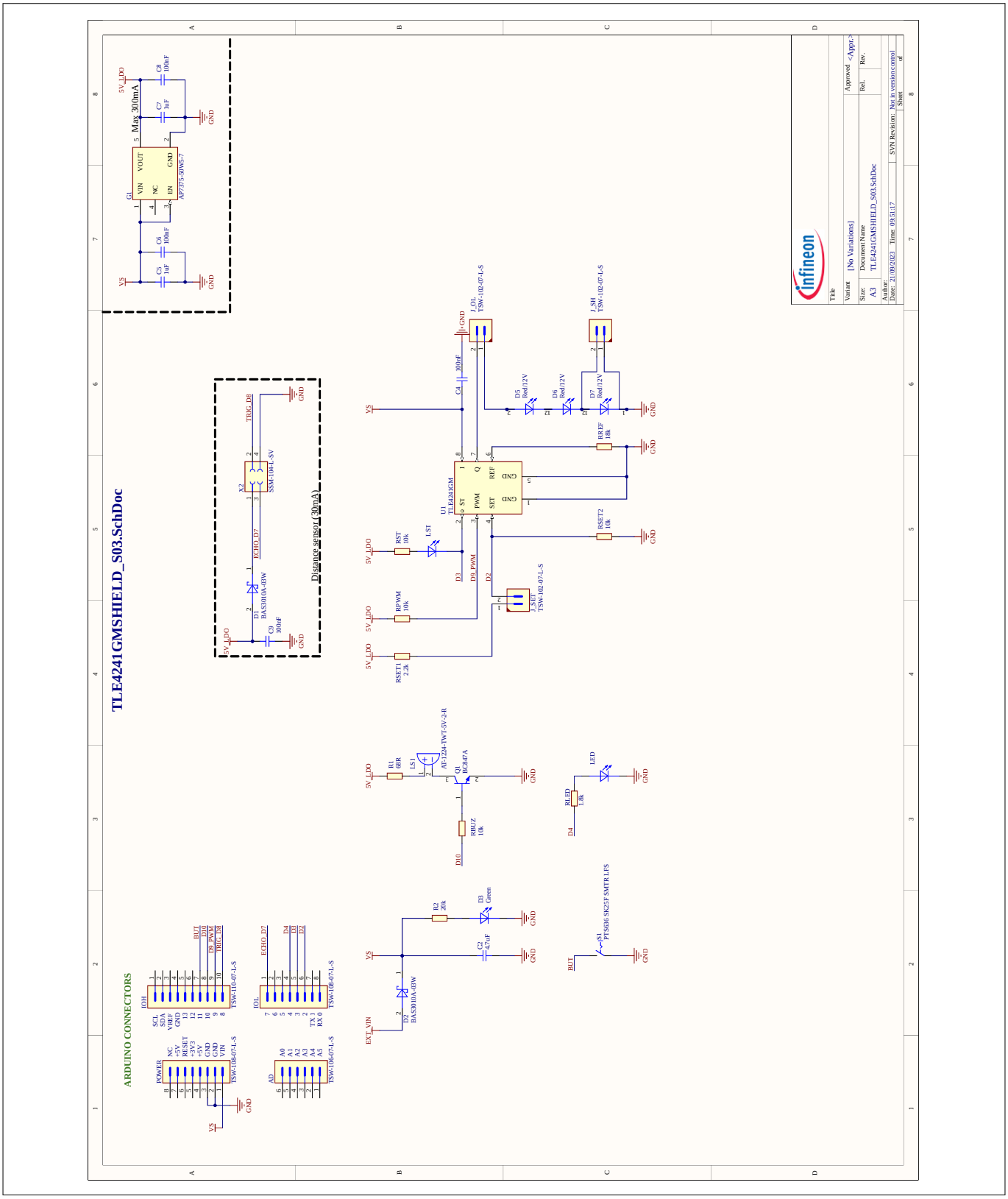

Figure 4 TLE4241GMSHIELD_S03_P03_schematic

4.2 PCB layout

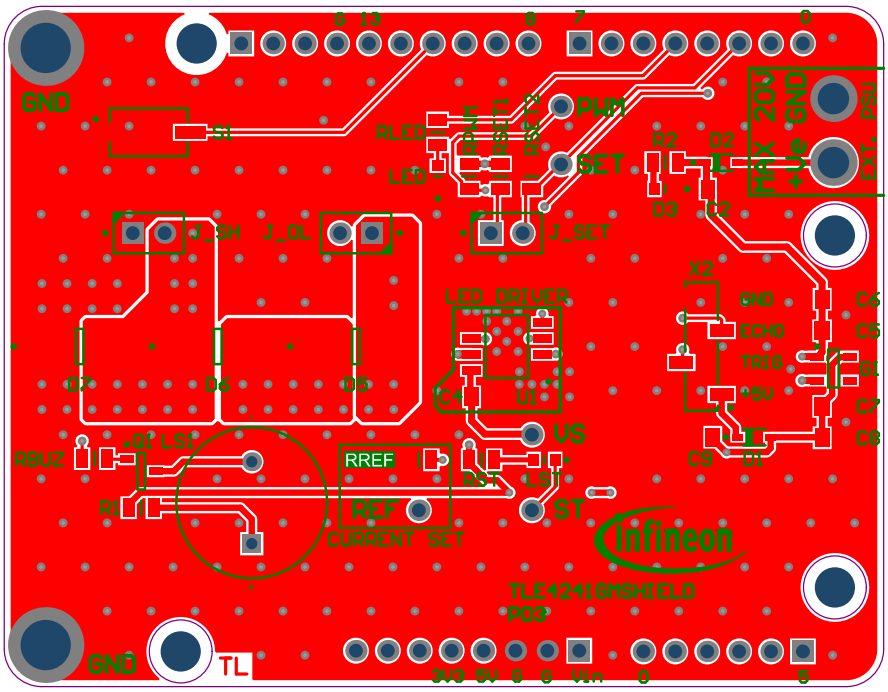

Figure 5 PCB layout top view

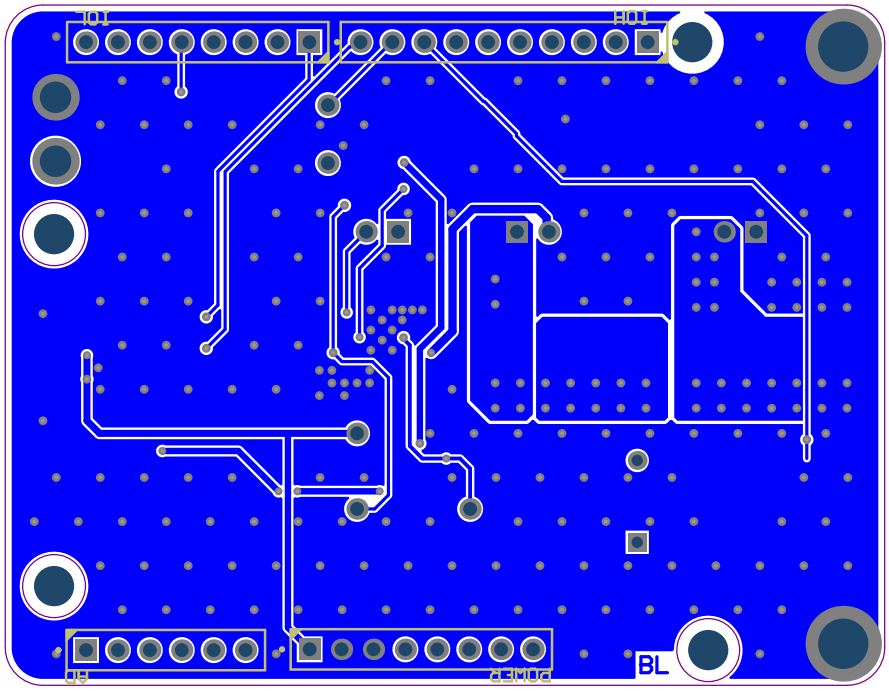

Figure 6 PCB layout bottom view - flipped horizontally

4.3 Bill of material

Quantity	Designator	Value	Description	Manufacturer
1	AD	TSW-106-07-L-S	Through hole .025 SQ Post Header, 2.54mm pitch, 6 pin, vertical, single row	Samtec
1	C2	4.7uF	CAP/CERA / 4.7uF/25V / 10% / X7S (EIA) / -55°C to 125°C/0805(2012) / SMD / -	MuRata
1	C4	100nF	CAP / CERA / 100nF / 50V / 10% / X8R (EIA) / -55°C to 125°C / 0805 / SMD / -	AVX
2	C5, C7	1uF	CAP / CERA / 1uF / 50V / 10% / X7R (EIA) / -55°C to 125°C / 0805 / SMD / -	MuRata
3	C6, C8, C9	100nF	CAP / CERA / 100nF / 50V / 10% / X7R (EIA) / -55°C to 125°C / 805(2012) / SMD / -	AVX
2	D1, D2	BAS3010A-03W	Medium Power AF Schottky Diode	Infineon Technologies
1	D3	Green	Standard 0603 SMD LED	Vishay
3	D5, D6, D7		PowerTOPLED, 633nm Red	OSRAM Opto Semiconductors
1	G1	AP7375-50W5-7	ULDO Regulator With Wide Input Voltage Range, 300mA	Diodes Incorporated
1	IOH	TSW-110-07-L-S	Through hole .025 SQ Post Header, 2.54mm pitch, 10 pin, vertical, single row	Samtec
2	IOL, POWER	TSW-108-07-L-S	Through hole .025 SQ Post Header, 2.54mm pitch, 8 pin, vertical, single row	Samtec
3	J_OL, J_SET, J_SH	TSW-102-07-L-S	Through hole .025'' SQ Post Header, 2.54mm pitch, 2 pin, vertical, single row	Samtec
2	LED, LST		Low Current 0603 SMD LED	Vishay
1	LS1	WST-0906T	Internally Driven Electro Magnetic Buzzer, 5V, 30mA, 2.7kHz	Soberton
1	Q1	BC847A	NPN Silicon AF Transistor	Infineon Technologies
1	R1	68R	RES / STD / 68R / 125mW / 1% / 100ppm/K / -55°C to 155°C / 0805(2012) / SMD / -	Vishay
1	R2	20k	RES / STD / 20k / 125mW / 1% / 100ppm/K / -55°C to 155°C / 0805(2012) / SMD / -	Vishay
4	RBUZ, RPWM, RSET2, RST	10k	RES / STD / 10k / 125mW / 1% / 100ppm/K / -55°C to 155°C / 0805(2012) / SMD / -	Vishay
1	RLED	1.8k	RES / STD / 1.8k / 125mW / 1% / 100ppm/K / -55°C to 155°C / 0805(2012) / SMD / -	Vishay
1	RREF	18k	RES / STD / 18k / 125mW / 1% / 100ppm/K / -55°C to 155°C / 0805(2012) / SMD / -	Vishay
1	RSET1	2.2k	RES / STD / 2.2k / 125mW / 1% / 100ppm/K / -55°C to 155°C / 0805(2012) / SMD / -	Vishay

Quantity	Designator	Value	Description	Manufacturer
1	S1	PTS636 SK25F SMTR LFS	Tactile Switches With Home Automation And Remote Control, 12V	C&K
1	U1	TLE4241GM	Adjustable Current LITIX Linear	Infineon Technologies
1	X2	SSM-104-L-SV	Tiger Claw Surface Mount Socket, 4Pin	Samtec

References

[1] Infineon *TLE4241GM datasheet*; https://www.infineon.com/cms/en/product/power/lighting-ics/litix-automotive-led-driver-ic/litix-linear/tle4241gm/#!documents

Revision history

Document version	Date of release	Description of changes
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