

# TLE4973 Evaluation Board User guide

## Lateral insertion 45° S-bend on Inlay PCB

### About this document

This document describes the evaluation board of TLE4973, Infineon's magnetic current sensor for automotive applications with external current rail.

### Scope and purpose

The evaluation board is meant to be used by the customer solely for the purpose of evaluation and testing. It is not a commercial product and shall not be used for series production. This board is thus not intend to meet any industrial specifications and shall be operated at room temperature.

Due to its purpose, the evaluation board is not subject to the same procedures as regular products regarding Returned Material Analysis (RMA), Process Change Notification (PCN) and Product Withdraw (PWD).

### Intended audience

This document is written for customers who intend to use TLE4973 in current sensing applications.

### Evaluation Board

This board will be used during design in, for evaluation and measurement of characteristics, and proof of datasheet specifications.

*Note: PCB and auxiliary circuits are NOT optimized for final customer design. Boards do not necessarily meet safety, EMI, quality standards (for example UL, CE) requirements.*



**Figure 1**      **TLE4973 EVAL INLAY**

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## **1 Important notice**

### **1 Important notice**

**“Evaluation Boards and Reference Boards” shall mean products embedded on a printed circuit board (PCB) for demonstration and/or evaluation purposes, which include, without limitation, demonstration, reference and evaluation boards, kits and design (collectively referred to as “Reference Board”).**

**Environmental conditions have been considered in the design of the Evaluation Boards and Reference Boards provided by Infineon Technologies. The design of the Evaluation Boards and Reference Boards has been tested by Infineon Technologies only as described in this document. The design is not qualified in terms of safety requirements, manufacturing and operation over the entire operating temperature range or lifetime.**

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## 2 Safety precautions

## 2 Safety precautions

*Note:* Please note the following warnings regarding the hazards associated with development systems.



**Figure 2**      **Safety Precautions**

- **Warning:** Remove or disconnect power from the drive before you disconnect or reconnect wires, or perform maintenance work. Failure to do so may result in personal injury or death.
- **Warning:** Do not keep the programmer connected to the laptop while the board is in use in an inverter. The laptop may be damaged during the operation of the system.
- **Warning:** The evaluation board is intended to be used only in low voltage systems ( $\leq 50$  V).
- **Caution:** The board and device surfaces of the evaluation board may become hot during testing. Hence, necessary precautions are required while handling the board. Failure to comply may cause injury. Please refer to [Chapter 6.2.1.4](#) for an indication of the heating due to the current flow.
- **Caution:** Only personnel familiar with the drive, power electronics and associated machinery should plan, install, commission and subsequently service the system. Failure to comply may result in personal injury and/or equipment damage.
- **Caution:** The evaluation board contains parts and assemblies sensitive to electrostatic discharge (ESD). Electrostatic control precautions are required when installing, testing, servicing or repairing the assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with electrostatic control procedures, refer to the applicable ESD protection handbooks and guidelines.
- **Caution:** A drive that is incorrectly applied or installed can lead to component damage or reduction in product lifetime. Wiring or application errors such as undersizing the motor, supplying an incorrect or inadequate AC supply, or excessive ambient temperatures may result in system malfunction.
- **Caution:** The evaluation board is shipped with packing materials that need to be removed prior to installation. Failure to remove all packing materials that are unnecessary for system installation may result in overheating or abnormal operating conditions.

### 3 The board at a glance

## 3 The board at a glance

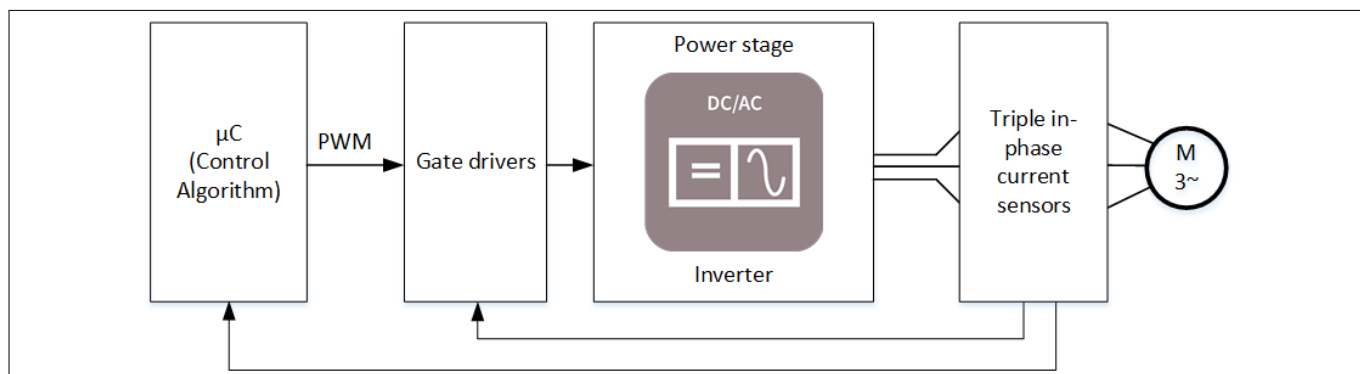
TLE4973 evaluation board is developed to familiarize the users with TLE4973 current sensor for design in support and evaluation purposes. The complete evaluation kit consists of this board and the programmer board, which is explained in [1]. The programmer board supplies the sensors on the evaluation board and allows a fast and easy interfacing to each sensor. If the programmer board is not used, power supply has to be provided externally by the user.

### 3.1 Delivery content

The delivery content consist in TLE4973 evaluation board.

### 3.2 Block diagram

The evaluation board includes three TLE4973 coreless magnetic current sensors for testing in three-phase systems. The evaluation board has been designed to operate safely in low voltage systems ( $\leq 50$  V). It is recommended to disconnect the USB cable between the programmer and the laptop while the system is in operation, in order to avoid damages to the laptop.



**Figure 3** Block diagram of the evaluation board in use in a three-phase system

### 3.3 Main features

- Three TLE4973 sensors, for testing in three-phase systems;
- On board EEPROM to store board settings;
- Compatible with Infineon Current Sensor Programmer [1]

### 3.4 Board parameters and technical data

**Table 1** Evaluation Board Overview

|                                      |                                   |
|--------------------------------------|-----------------------------------|
| <b>Product</b>                       | <b>TLE4973-RE35D5-S0010</b>       |
| Package                              | PG-TDSO-16                        |
| Evaluation board name                | TLE4973 EVAL INLAY                |
| Evaluation board order number        | SP005853842                       |
| Insertion method name                | 45° s-bend on Schweizer Inlay PCB |
| Full scale (FS)                      | $\pm 460.41$ A                    |
| Typical current rail transfer factor | $46.19 \mu\text{T/A}$             |
| Typical sensor sensitivity           | $84.63 \text{ mV/mT (S3)}$        |
| Typical evaluation board sensitivity | $3.91 \text{ mV/A}$               |

**(table continues...)**

### 3 The board at a glance

**Table 1** (continued) Evaluation Board Overview

| Product                      | TLE4973-RE35D5-S0010   |
|------------------------------|------------------------|
| Output mode                  | Single-ended AOUT only |
| OCD threshold                | 647.52 A (139% of FS)  |
| DCDI address [Sensor 1]      | 0xA <sub>hex</sub>     |
| DCDI address [Sensor 2]      | 0xB <sub>hex</sub>     |
| DCDI address [Sensor 3]      | 0xC <sub>hex</sub>     |
| Typical insertion resistance | 17 $\mu\Omega$         |
| Current rail width           | 14 mm                  |
| Current rail thickness       | 1 mm                   |

## 4 System and functional description

# 4 System and functional description

### 4.1 Commissioning

If the evaluation board is used in combination with the Infineon programmer board [1], it is sufficient to connect the two boards and follow the instructions on the GUI [1].

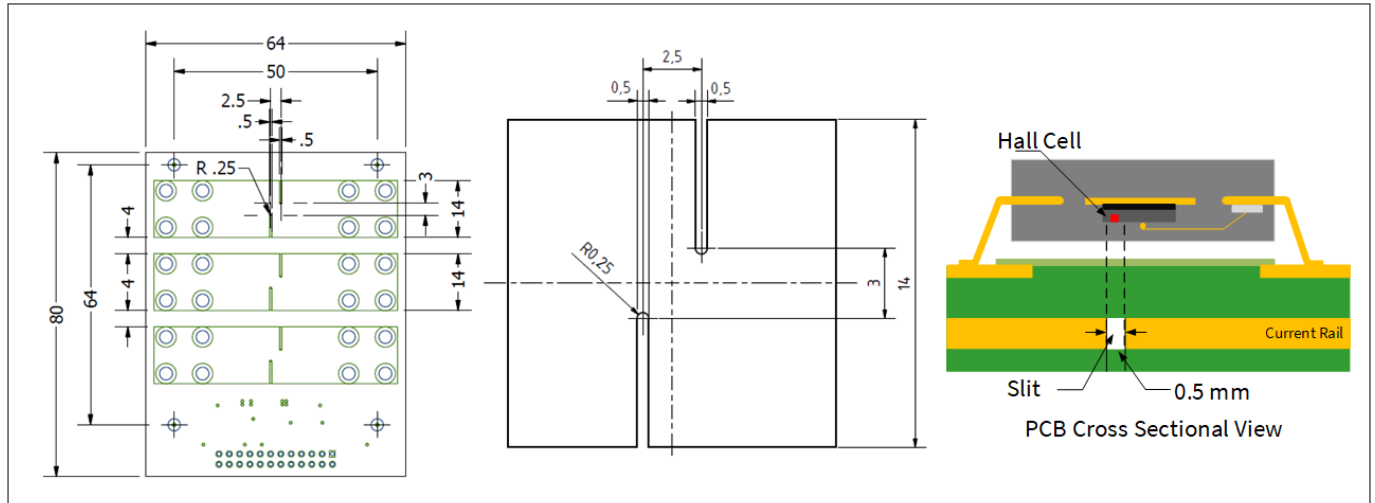
If instead the evaluation board is used as stand-alone, then the user has to supply the board using pin 17 (VS+, LDO input). In order to enable the onboard LDO, pin 19 (EN) has to be connected to the same supply voltage. The supply voltage must be in the range [6,9] V. Please refer to [Chapter 5.4](#) for the complete pinout of the evaluation board connector.

### 4.2 Description of the functional blocks

The board consists of three TLE4973 current sensors to accurately sense AC and DC currents, a EEPROM to store the board settings, a LDO (Low Drop Out) regulator to stabilize the supply voltage of the sensors and a connector to connect to the Infineon programmer board [1]. For additional information about TLE4973 please refer to the user manual [2] and datasheet [3]. Guidelines about sensing structure design are given in the dedicated application note [4].

### 4.3 Sensing Structure Layout & Guidelines

The three sensors are mounted on a PCB and placed on top of the current rail inside the PCB. The sensors are twisted 45° in order to reduce the crosstalk between the three phases, without compromising the frequency response of the sensor and insertion resistance of the conductor. The current rail has a 0.5 mm s-shaped slit. Please refer to the sensing structure design application note [4] for further guidelines.



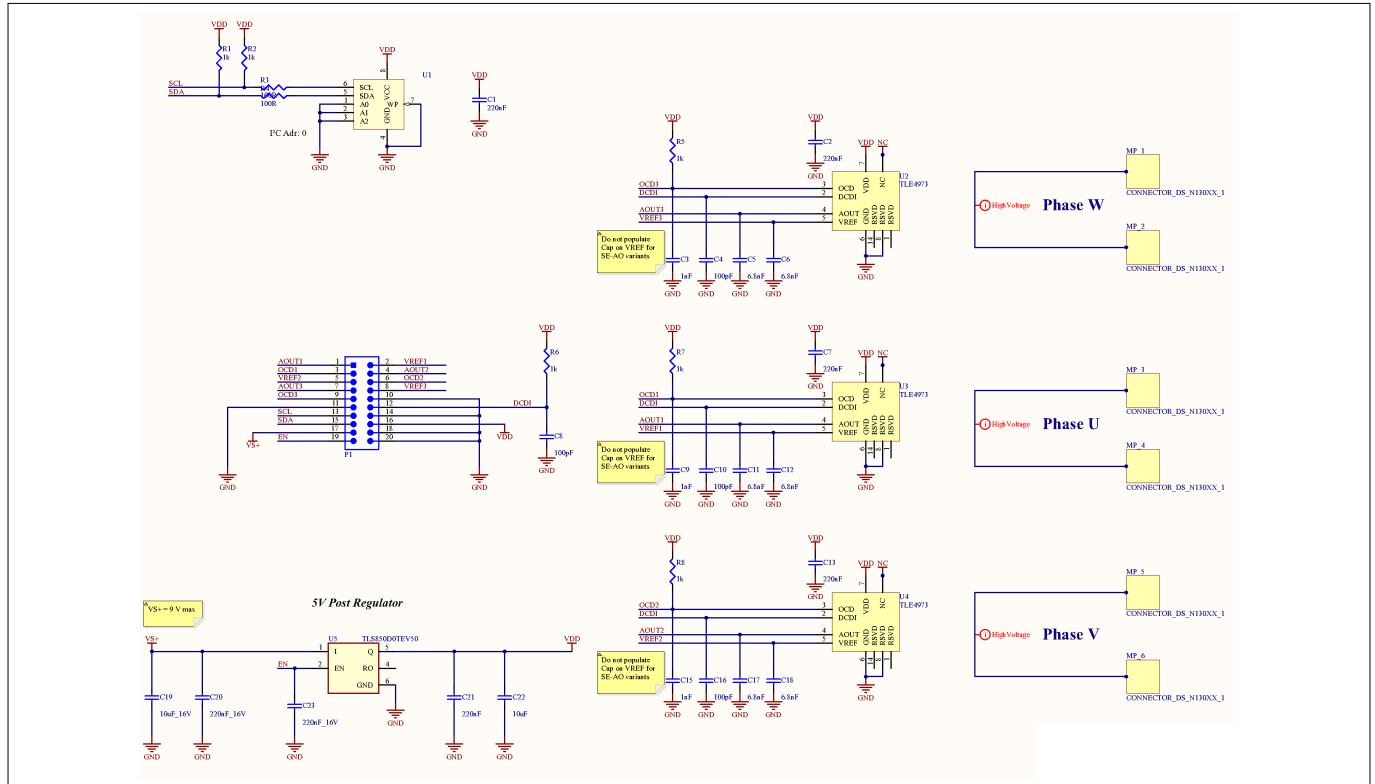
**Figure 4** Sensing structure overview



## 5 System design

# 5 System design

## 5.1 Schematics



**Figure 5 TLE4973 evaluation board schematic**

In order to suppress the high frequency noise and meet the EMC and ESD requirements, the following capacitors have been implemented:

- A 220 nF bypass capacitor at the VDD pins of the sensors;
- A 6.8 nF bypass capacitor at the AOUT and VREF pins of the sensors;
- A 1 nF bypass capacitor at the OCD pin of the sensors;
- A 100pF bypass capacitor at the DCDI pin of the sensors.

Additionally, OCD and DCDI pins of the sensors are connected to 1 kΩ pull-up resistors, as they are open drain pins. A voltage regulator is implemented to supply the sensors with a stable voltage.

## 5 System design

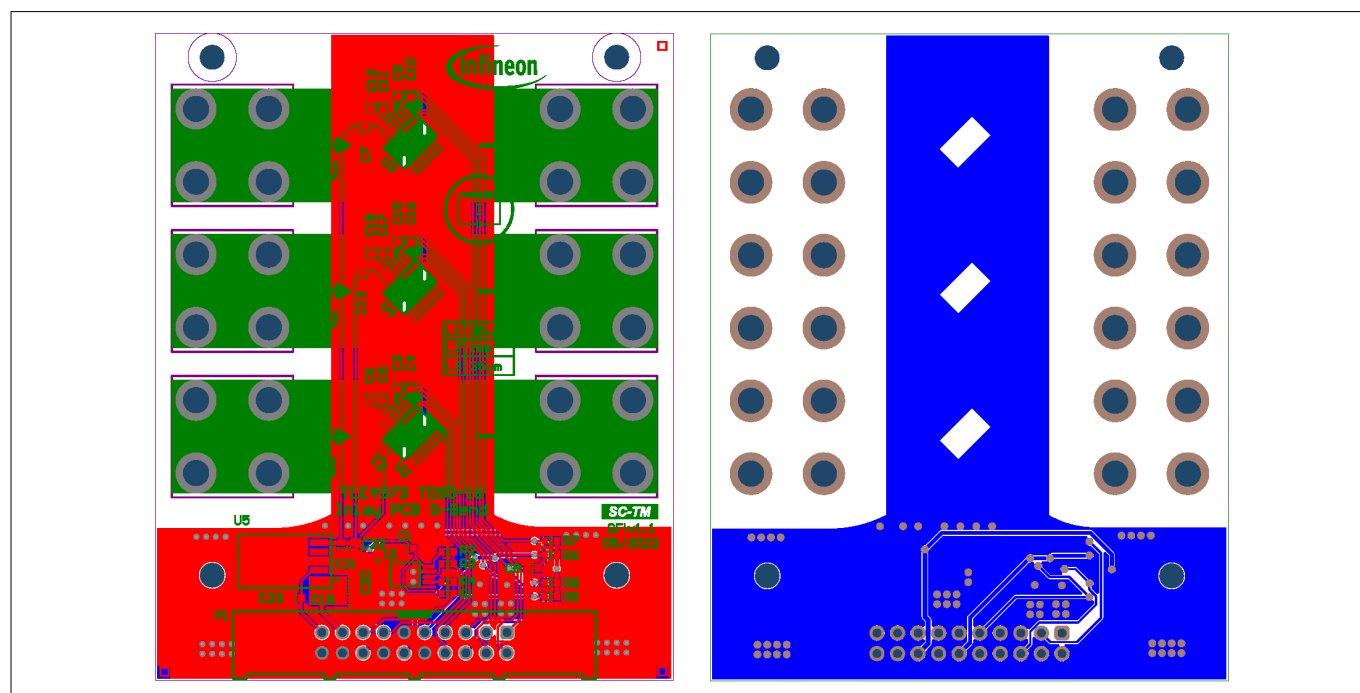
### 5.2 Layout

TLE4973 evaluation board consists of two 32  $\mu\text{m}$  outer metallization layers and one 1 mm inner metallization layer. The inner layer is intended to carry the high current that is sensed by the sensors. Details are shown in the figure below.

| # | Name            | Material      | Type           | Thickness |
|---|-----------------|---------------|----------------|-----------|
|   | Top Overlay     |               | Overlay        |           |
|   | Top Solder      | Solder Resist | Solder Mask    | 0.03mm    |
|   | galv. Cu top    |               | Surface Finish | 0.043mm   |
| 1 | L1_Top          | copper        | Signal         | 0.032mm   |
|   | Prepreg1        | FR4           | Prepreg        | 0.05mm    |
|   | Prepreg2        | FR4           | Prepreg        | 0.05mm    |
| 2 | Inlay           | copper        | Signal         | 1mm       |
|   | Prepreg3        | FR4           | Prepreg        | 0.05mm    |
|   | Prepreg4        | FR4           | Prepreg        | 0.05mm    |
| 3 | L3_Bottom       | copper        | Signal         | 0.032mm   |
|   | galv. Cu bottom |               | Surface Finish | 0.043mm   |
|   | Bottom Solder   | Solder Resist | Solder Mask    | 0.03mm    |
|   | Bottom Overlay  |               | Overlay        |           |

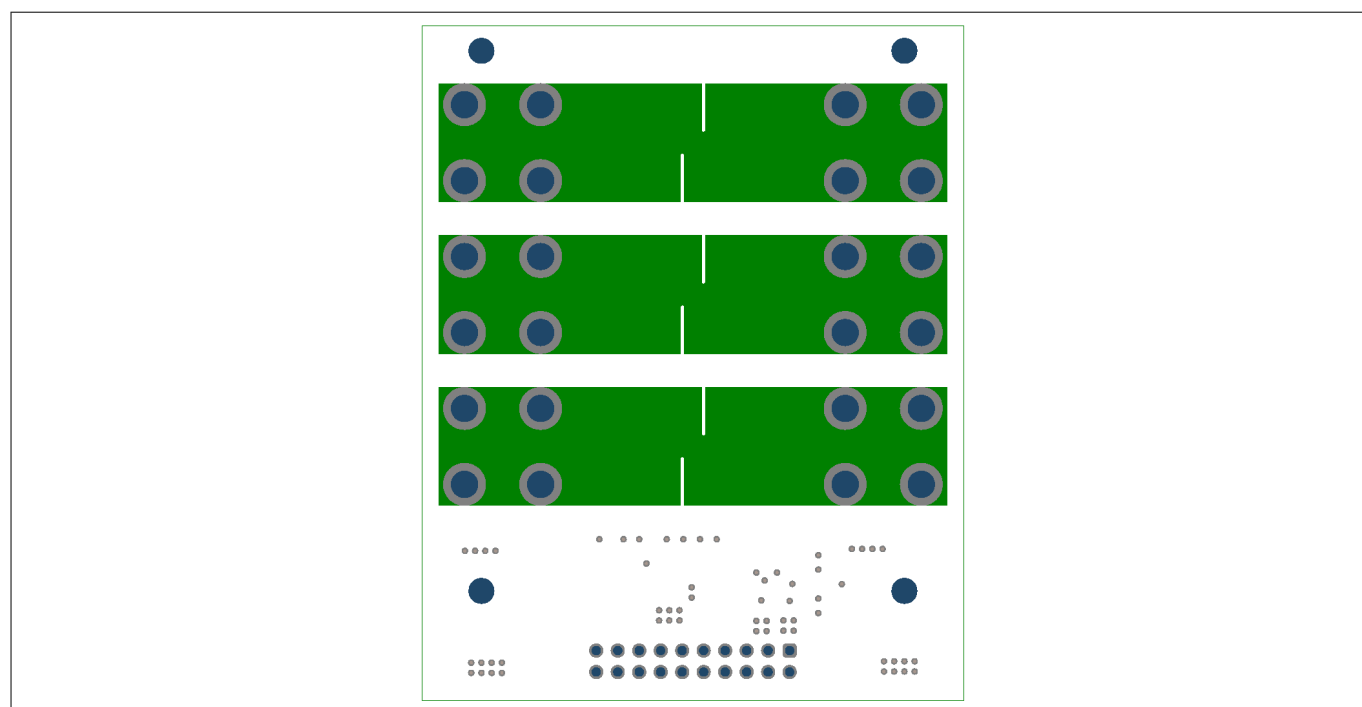
**Figure 6 Evaluation board layer stack up**

The figure below shows the top and bottom layer of the evaluation board. Please contact your local Infineon sales office to receive the Gerber files.



**Figure 7 Evaluation board PCB layout. Top layer (red, left) and bottom layer (blue, right)**

## 5 System design



**Figure 8** Evaluation board PCB layout. Inlay layer

AOUT and VREF tracks of each sensor are traced in parallel on the PCB in order to minimize the common mode noise on the output signal. Additionally, ground planes are used to protect the signal tracks and reduce the parasitic inductive couplings. The ground and power planes are cut below the TLE4973 including input and output pins to avoid the error induced due to the eddy currents. For the same reason, no heat sink or other conductor material shall be placed on the same position of the sensor.

### 5.3 Bill of material

**Table 2** Bill of Material

| Quantity | Designator                         | Value             | Comment                | Footprint  |
|----------|------------------------------------|-------------------|------------------------|------------|
| 1        | U5                                 | TLS850D0TEV50     | LDO                    | PG-TO252-5 |
| 3        | U2, U3, U4                         | TLE4973           | TLE4973 current sensor | PG-TDSO-16 |
| 1        | U1                                 | M24C02-RDW6TP     | Onboard EEPROM         | TSSOP8_W   |
| 2        | R3, R4                             | 100R              | Res                    | R0603      |
| 6        | R1, R2, R5, R6, R7, R8             | 1k                | Res                    | R0603      |
| 1        | P1                                 | Wurth 61202022821 | -                      | -          |
| 6        | MP_1, MP_2, MP_3, MP_4, MP_5, MP_6 | Broxing B1305M    | -                      | -          |
| 1        | C22                                | 10uF              | Cap                    | C0805      |
| 2        | C20, C23                           | 220nF_16V         | Cap                    | C0603      |
| 1        | C19                                | 10uF_16V          | Cap                    | C0805      |
| 3        | C6, C12, C18                       | 6.8nF             | DNP for SE-AO          | C0603      |

(table continues...)

## 5 System design

**Table 2** (continued) **Bill of Material**

| Quantity | Designator           | Value | Comment | Footprint |
|----------|----------------------|-------|---------|-----------|
| 3        | C5, C11, C17         | 6.8nF | Cap     | C0603     |
| 4        | C4, C8, C10, C16     | 100pF | Cap     | C0603     |
| 3        | C3, C9, C15          | 1nF   | Cap     | C0603     |
| 5        | C1, C2, C7, C13, C21 | 220nF | Cap     | C0603     |

### 5.4 Connector details

The evaluation board connector establishes the connection between the evaluation board and the programmer board. Please refer to the programmer user guide [1] for details about the programmer.

**Table 3** **Evaluation board connector pinout**

| Pin Number | Pin name | Pin function  |
|------------|----------|---|
| 1          | AOUT1    | Analog output voltage of sensor 1   |
| 2          | VREF1    | Reference voltage of sensor 1   |
| 3          | OCD1     | Over Current Detection of sensor 1 (open drain)   |
| 4          | AOUT2    | Analog output voltage of sensor 2   |
| 5          | VREF2    | Reference voltage of sensor 2   |
| 6          | OCD2     | Over Current Detection of sensor 2 (open drain)   |
| 7          | AOUT3    | Analog output voltage of sensor 3   |
| 8          | VREF3    | Reference voltage of sensor 3   |
| 9          | OCD3     | Over Current Detection of sensor 3 (open drain)   |
| 10         | GND      | Ground connection   |
| 11         | GND      | Ground connection   |
| 12         | DCDI     | Digital Control Diagnostic Interface. One wire, open drain, connected to all sensors. UART protocol.  |
| 13         | SCL      | Clock for communication with external EEPROM on Infineon's evaluation boards                          |
| 14         | GND      | Ground connection   |
| 15         | SDA      | Data link for communication with external EEPROM on Infineon's evaluation boards                      |
| 16         | VDD      | 5 V supply voltage, connected to each sensor on VDD pin. This voltage is generated onboard by the LDO |

(table continues...)

## 5 System design

**Table 3** (continued) Evaluation board connector pinout

|    |     |   |
|----|-----|---|
| 17 | VS+ | Supply voltage of the evaluation board. Connected to LDO input. To be used to supply the evaluation board as standalone. The voltage must be in the range [6,9] V |
| 18 | GND | Ground connection   |
| 19 | EN  | LDO enable. It must be connected to VS+ when the evaluation board is used as standalone   |
| 20 | GND | Ground connection   |

## 6 System performance

# 6 System performance

## 6.1 Test points

The output voltage of the three sensors, as well as the OCD signals have been measured from the evaluation board connector. Please refer to [Chapter 5.4](#) for the complete pinout of the evaluation board connector.

## 6.2 Test results

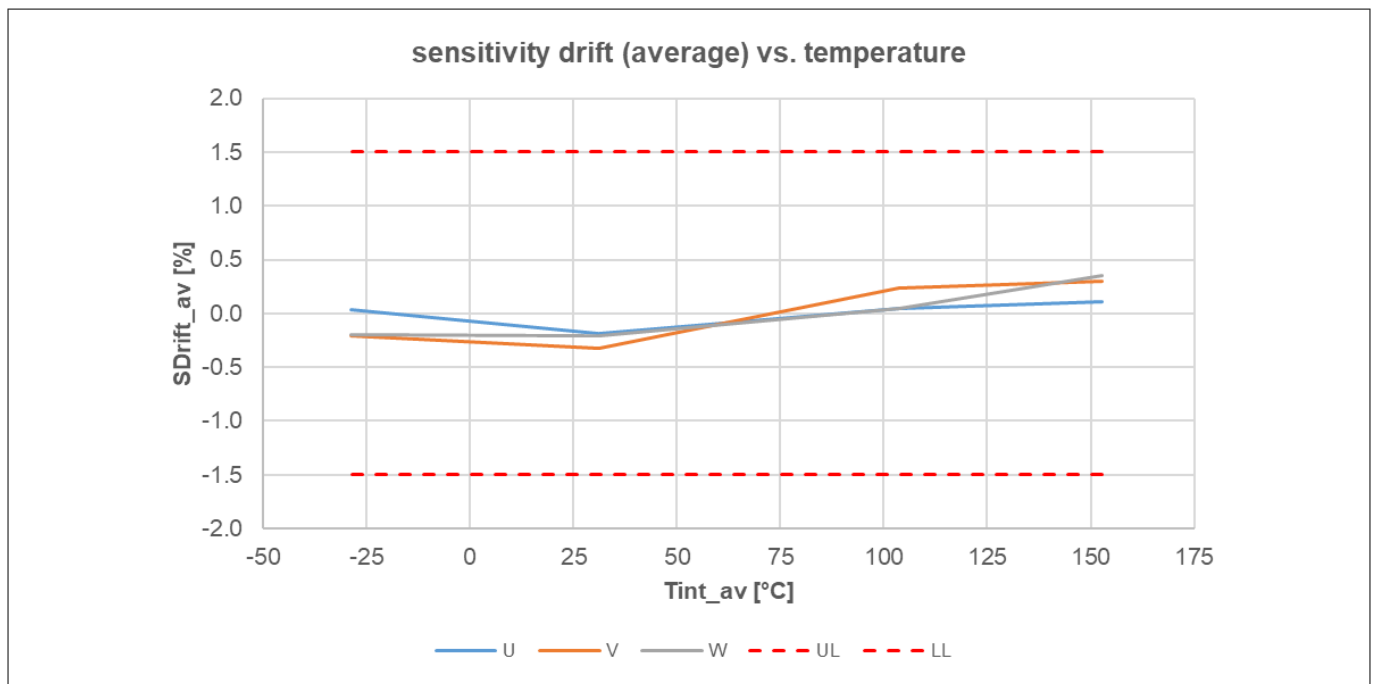
### 6.2.1 Measurement results

This section discusses the results of the measurements performed in the laboratory on the evaluation board. The following measurements have been performed:

1. Sensitivity drift and offset drift over temperature
2. Frequency response
3. Crosstalk
4. Thermal capability

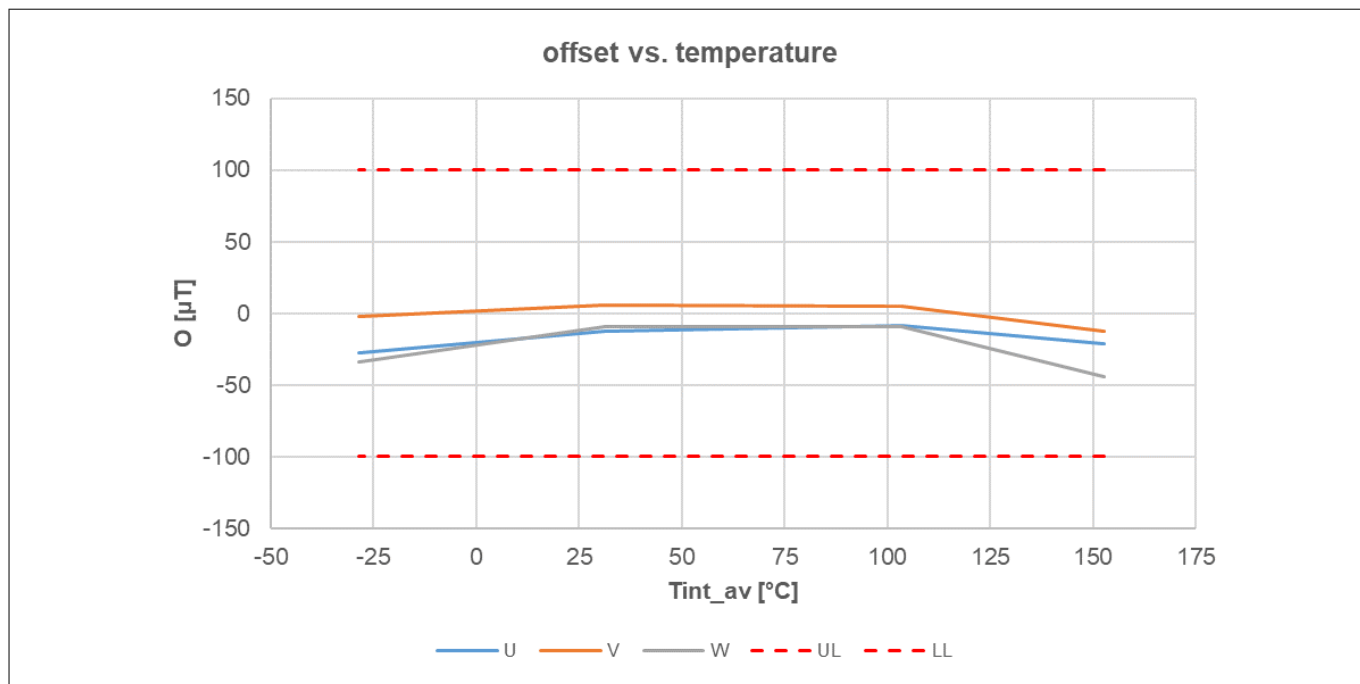
#### 6.2.1.1 Sensitivity drift and offset drift over temperature

The figures below show the TLE4973 evaluation board measurement results of sensitivity drift and offset over temperature when the sensor is placed in the nominal position. The results show extremely stable sensitivity and small offset across the whole temperature range. The absolute value of sensitivity used as target for calibration is shown in [Chapter 3.4](#).



**Figure 9** Sensitivity drift over temperature with respect to average value

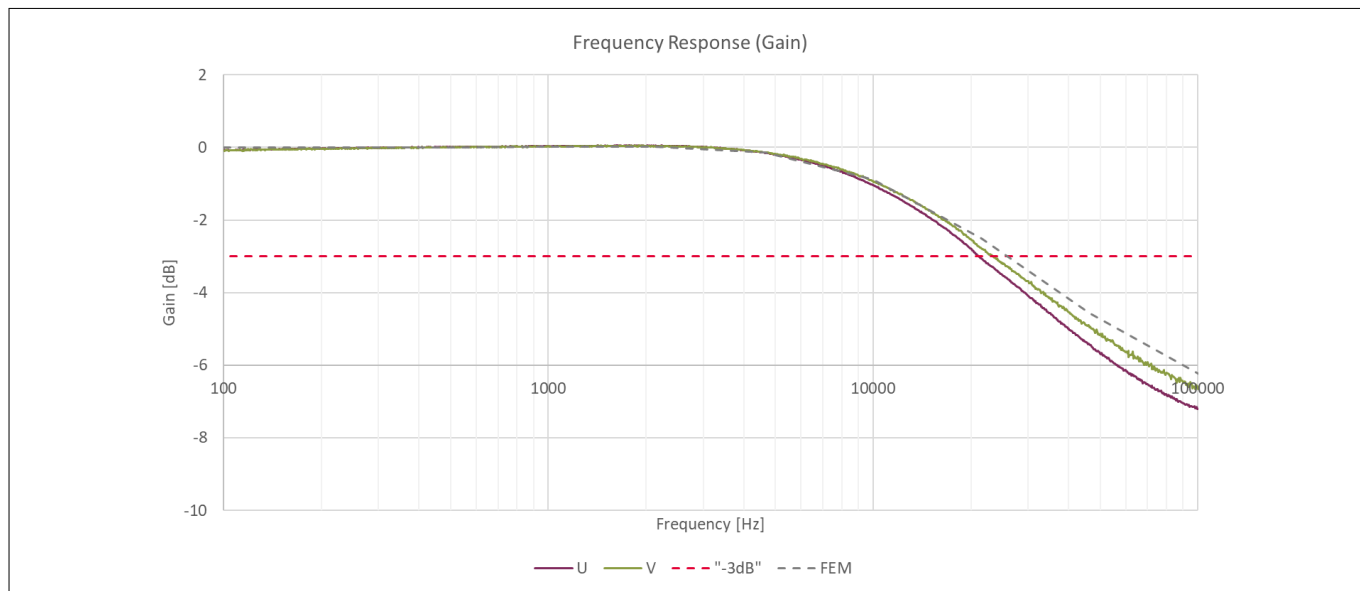
## 6 System performance



**Figure 10** Offset drift over temperature

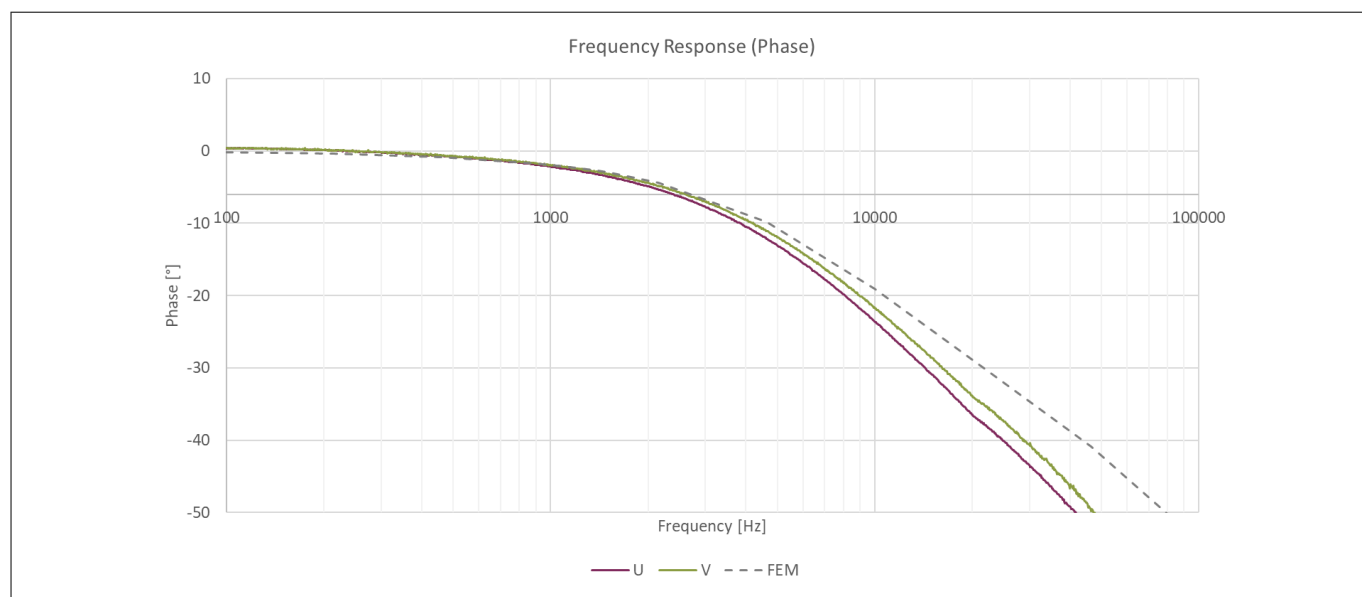
### 6.2.1.2 Frequency response

The figures below show the TLE4973 evaluation board measurement results of frequency response (gain and phase) when the sensor is placed in the nominal position. Two out of three sensors have been measured. A comparison with results from Finite Element Method (FEM) simulations is also provided. The Gain plots are normalized to the DC gain.



**Figure 11** Frequency Response (Gain)

## 6 System performance



**Figure 12**      **Frequency Response (Phase)**

### 6.2.1.3 Crosstalk

The crosstalk is defined as the sensitivity error due to the magnetic stray field generated by the neighboring conductive lines. The crosstalk can be compensated with the “Matrix compensation method” in the microcontroller software. For further information, please refer to the programming board user guide [1] and device user manual [2].

Furthermore, the crosstalk can be reduced orienting the sensors differently with respect to each other, so that the respective sensing elements would see the same field coming from the neighboring conductive lines. Detailed explanation is provided in the application note [4].

The table below shows the sensitivity error due to the crosstalk before the compensation.

**Table 4**      **Crosstalk**

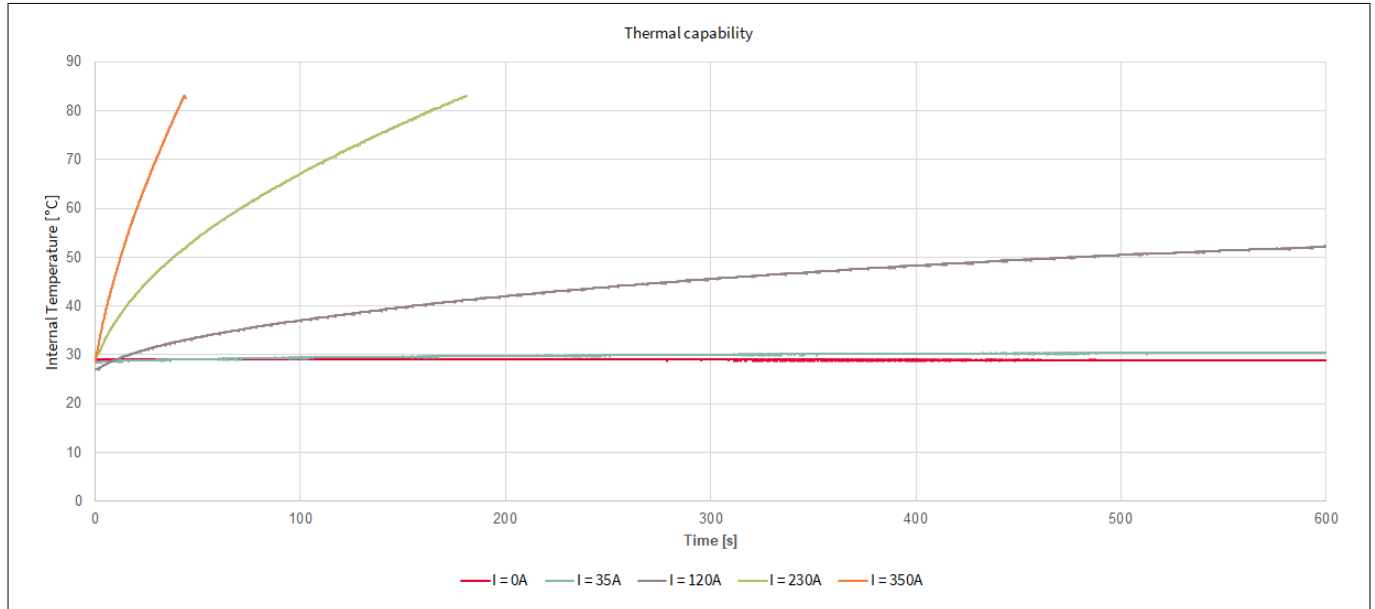
| Active phase | S [%] |        |       |
|--------------|-------|--------|-------|
|              | U     | V      | W     |
| U            | 100   | -1.25  | -0.27 |
| V            | -1.00 | 100.00 | -1.30 |
| W            | -0.10 | -0.89  | 100   |



## 6 System performance

### 6.2.1.4 Thermal capability

The following figure shows the heating of the board and device when a current flows in the evaluation board. The temperature is read out by the sensor over time and the measurement is stopped when a temperature of approximately 80°C is detected. The measurement shows that a cooling of the board is needed, if high currents are applied.



**Figure 13 Thermal capability**

### 6.2.2 Simulation results

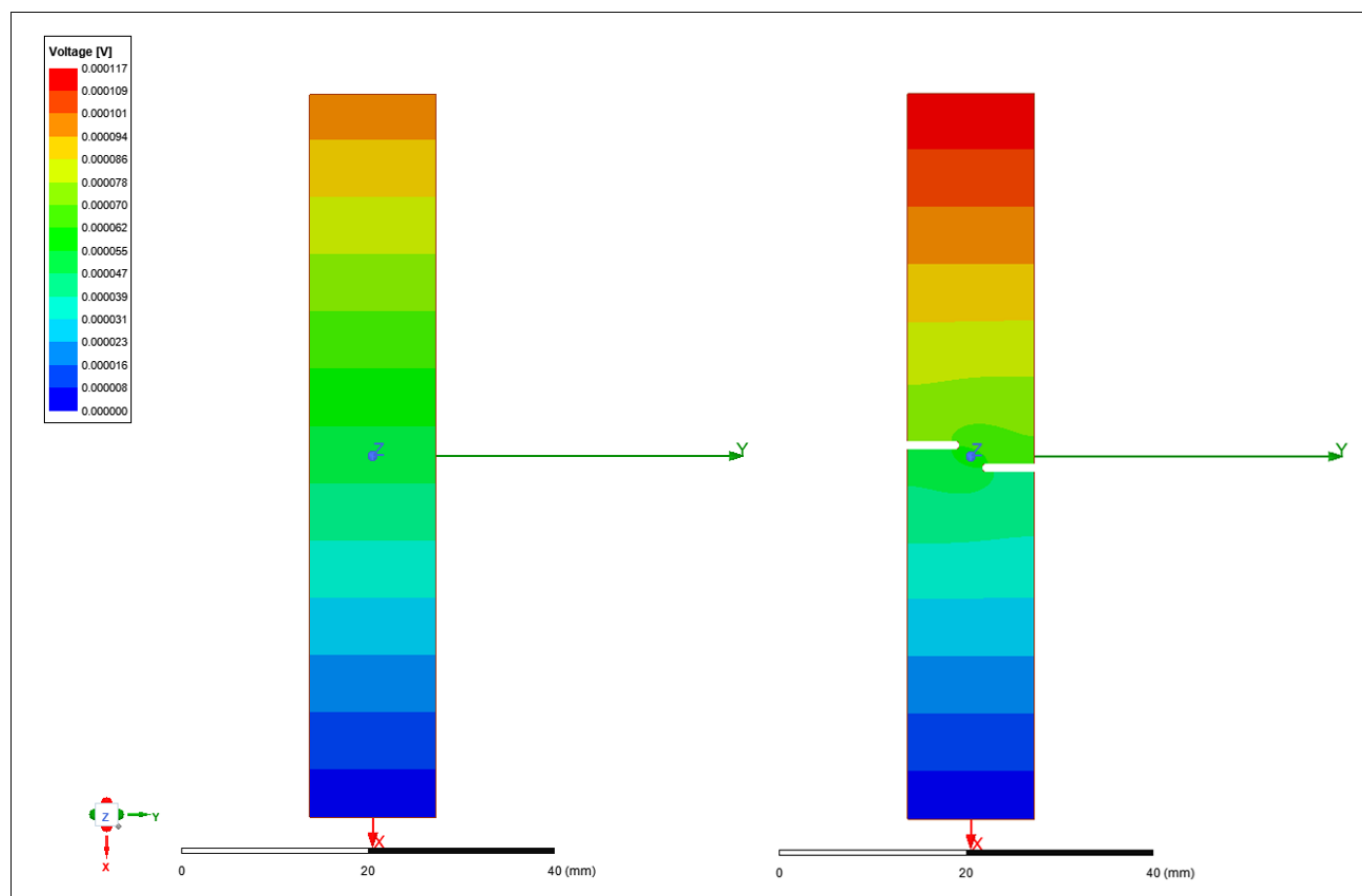
This section discusses the results of the simulations performed in ANSYS Maxwell 3D on the evaluation board to complement the results from measurements. The following simulations have been performed:

1. Conductor and insertion resistance
2. Transfer factor error due to sensor displacement

#### 6.2.2.1 Conductor and insertion resistance

The insertion resistance indicates the additional resistance caused by the sensing structure at 25°C. The simulations are performed with and without slit in the conductor by applying 1 A of current. Simulation results are shown in the figure below. Please note that the legend shows a voltage [V], which is equivalent to resistance [ $\Omega$ ], being the applied current 1 A.

## 6 System performance



**Figure 14** Conductor resistance, without slit (left) and with slit (right)

The table below shows the simulated resistance of the conductor with and without slit and the calculated insertion resistance.

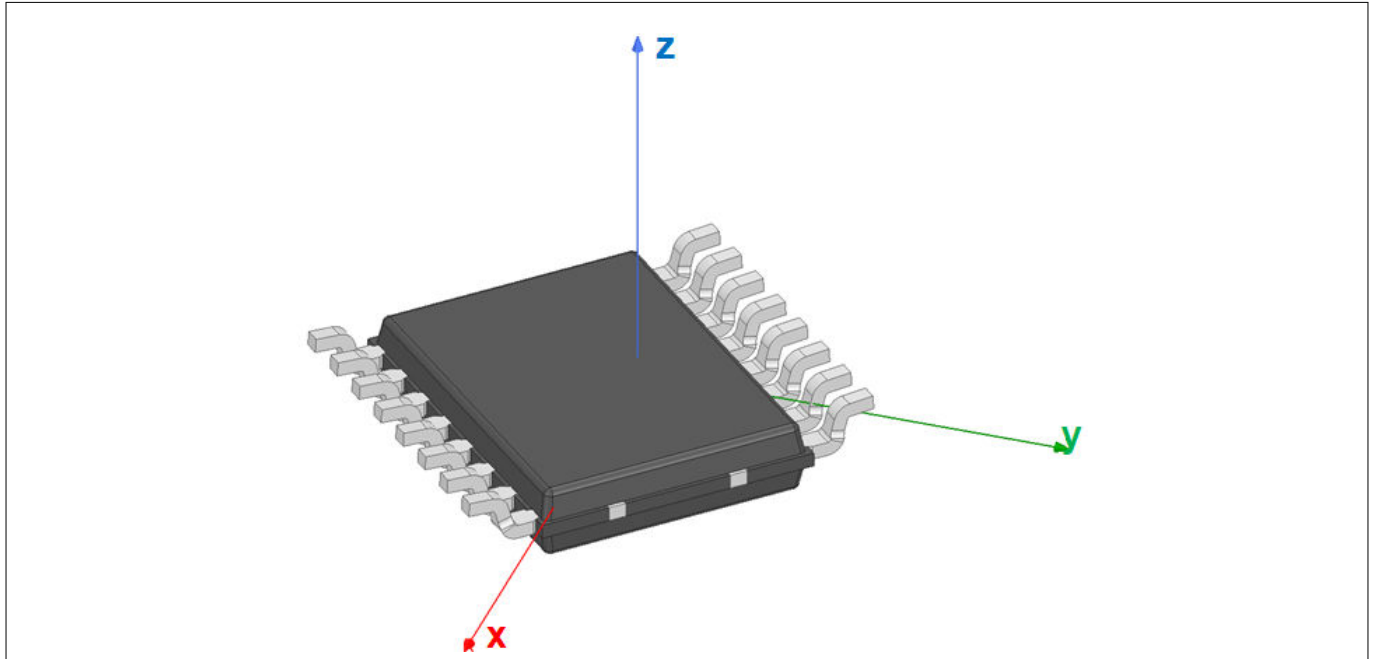
**Table 5** Evaluation Board Conductor Resistance

| Parameter                         | Value           |
|-----------------------------------|-----------------|
| Conductor resistance without slit | 100 $\mu\Omega$ |
| Conductor resistance with slit    | 117 $\mu\Omega$ |
| Insertion resistance              | 17 $\mu\Omega$  |
| Conductor resistance increase     | 17%             |

## 6 System performance

### 6.2.2.2 Transfer factor error due to sensor displacement

The following figures show the transfer factor variation due to sensor displacement in the x, y, and z-axis direction. The transfer factor is defined in  $\mu\text{T}/\text{A}$  and the typical value is shown in [Chapter 3.4](#).



**Figure 15** Reference system for sensor displacement simulations

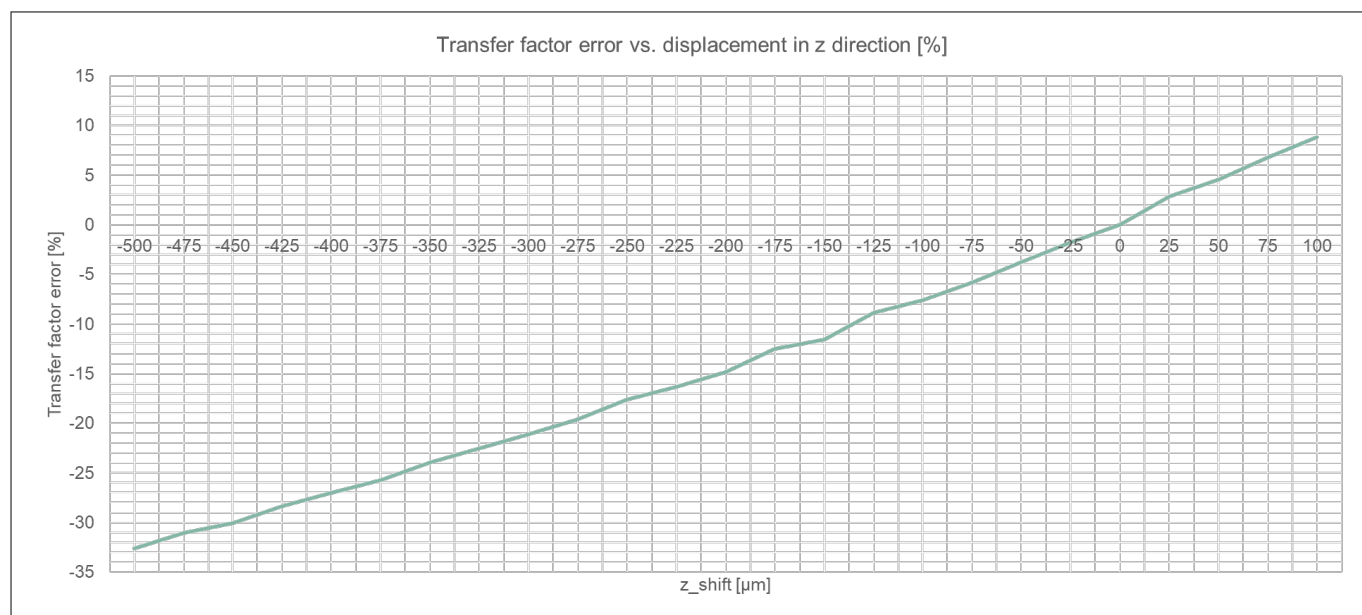


**Figure 16** Transfer factor error due to sensor displacement in x direction

## 6 System performance



**Figure 17** Transfer factor error due to sensor displacement in y direction



**Figure 18** Transfer factor error due to sensor displacement in z direction

## **7 References and appendices**

### **7.1 Abbreviations and definitions**

| <b>Notation</b> | <b>Description</b>                                  |
|-----------------|---|
| AC              | Alternating Current                                 |
| CE              | European Conformity                                 |
| DC              | Direct Current                                      |
| EMC             | Electro-Magnetic Compatibility                      |
| EMI             | Electro-Magnetic Interference                       |
| EEPROM          | Electrically Erasable Programmable Read-Only Memory |
| ESD             | Electro-Static Discharge                            |
| FEM             | Finite Element Method                               |
| GUI             | Graphical User Interface                            |
| LDO             | Low Drop Out  |
| OCD             | Over Current Detection                              |
| PCB             | Printed Circuit Board                               |
| PCN             | Process Change Notification                         |
| PD              | Product Discontinuation                             |
| PWD             | Product Withdraw                                    |
| RMA             | Returned Material Analysis                          |
| SCL             | Serial Clock  |
| SDA             | Serial Data   |
| UL              | Underwriters Laboratories                           |
| USB             | Universal Serial Bus                                |
| DNP             | Do Not Populate                                     |

### **7.2 References**

- [1] Infineon-TLE4973-Current\_Sensor\_Programmer-UG-vxx\_xx-EN
- [2] Infineon-TLE4973-User\_manual-vxx\_xx-EN
- [3] Infineon-TLE4973-RE35x5-S0010-DS-vxx\_xx-EN.pdf; Infineon-TLE4973-RxxxT5-S0010-DS-vxx\_xx-EN.pdf; Infineon-TLE4973-xE35x5-S0001-DS-vxx\_xx-EN.pdf; Infineon-TLE4973-xxxxT5-S0001-DS-vxx\_xx-EN.pdf
- [4] Infineon-TLE4973-Sensing\_Structure\_Design-AN-vxx\_xx-EN

## 8 Revision history

### 8 Revision history

**Table 6**      **Revision History**

| <b>Document version</b> | <b>Date of release</b> | <b>Description of changes</b> |
|-------------------------|------------------------|-------------------------------|
| 1.0                     | 2023-02-27             | Initial release               |

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**Published by**

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**81726 Munich, Germany**

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